

Introduction & motivations
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Orientable case
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Problem
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Bipartite maps
oooooooooooo

General maps
o

Bipartite quadrangulations
ooo

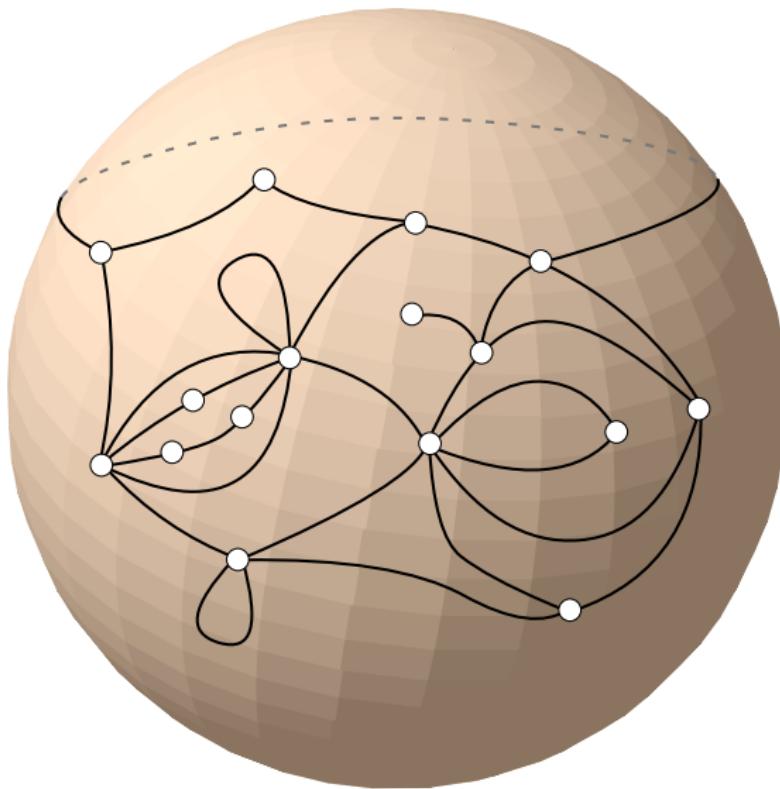
A bijection for nonorientable maps

Jérémie BETTINELLI

January 9, 2020



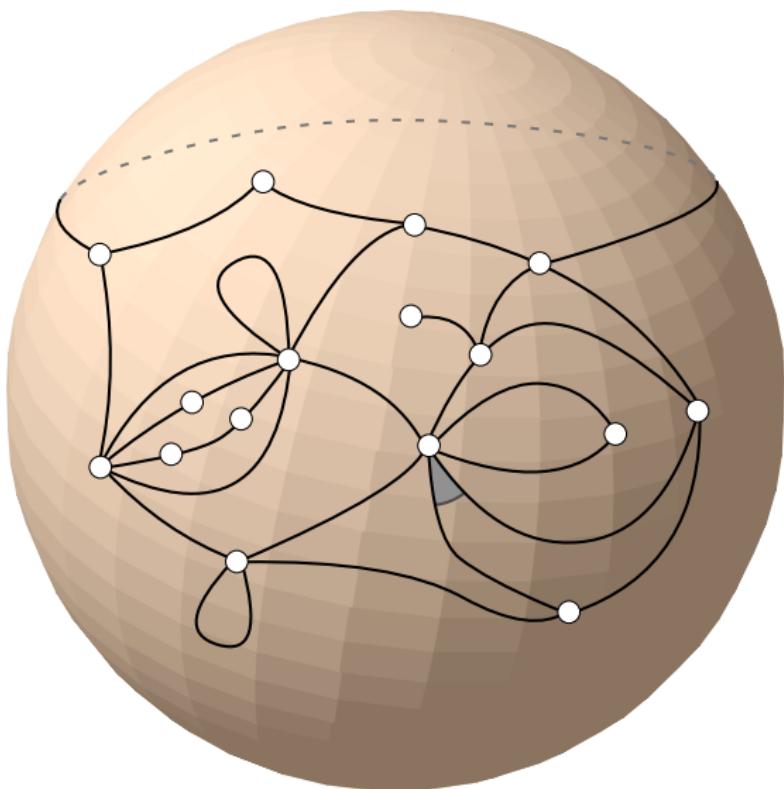
Plane maps



plane map: finite connected graph embedded in the sphere

faces: connected components of the complement

Plane maps



plane map: finite connected graph embedded in the sphere

faces: connected components of the complement

root: distinguished corner

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Orientable case
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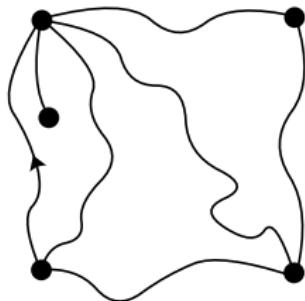
Problem
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Bipartite maps
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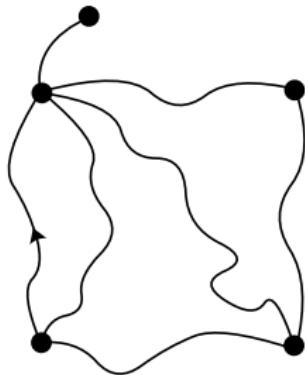
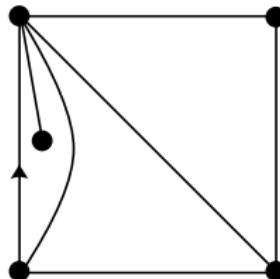
General maps
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Bipartite quadrangulations
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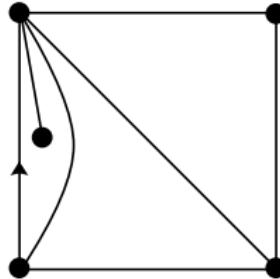
Edge deformation



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Scaling limit: the Brownian sphere

- We denote by $V(\mathfrak{m})$ the vertex-set of \mathfrak{m} and $d_{\mathfrak{m}}$ the graph metric.

Theorem (Le Gall '11, Miermont '11)

Let \mathfrak{q}_n be a uniform plane quadrangulation with n faces. The sequence $(V(\mathfrak{q}_n), (8n/9)^{-1/4} d_{\mathfrak{q}_n})_{n \geq 1}$ converges weakly in the sense of the Gromov–Hausdorff topology toward a random compact metric space a.s. homeomorphic to the sphere, and called the *Brownian sphere*.

Definition (Convergence for the Gromov–Hausdorff topology)

A sequence (\mathcal{X}_n) of compact metric spaces **converges in the sense of the Gromov–Hausdorff topology** toward a metric space \mathcal{X} if there exist isometric embeddings $\varphi_n : \mathcal{X}_n \rightarrow \mathcal{Z}$ and $\varphi : \mathcal{X} \rightarrow \mathcal{Z}$ into a common metric space \mathcal{Z} such that $\varphi_n(\mathcal{X}_n)$ converges toward $\varphi(\mathcal{X})$ in the sense of the Hausdorff topology.

Scaling limit: the Brownian sphere

- We denote by $V(\mathfrak{m})$ the vertex-set of \mathfrak{m} and $d_{\mathfrak{m}}$ the graph metric.

Theorem (B. & Jacob & Miermont '13)

Let \mathfrak{m}_n be a uniform plane map with n edges. The sequence $(V(\mathfrak{m}_n), (8n/9)^{-1/4} d_{\mathfrak{m}_n})_{n \geq 1}$ converges weakly in the sense of the Gromov–Hausdorff topology toward a random compact metric space a.s. homeomorphic to the sphere, and called the [Brownian sphere](#).

Definition (Convergence for the Gromov–Hausdorff topology)

A sequence (\mathcal{X}_n) of compact metric spaces **converges in the sense of the Gromov–Hausdorff topology** toward a metric space \mathcal{X} if there exist isometric embeddings $\varphi_n : \mathcal{X}_n \rightarrow \mathcal{Z}$ and $\varphi : \mathcal{X} \rightarrow \mathcal{Z}$ into a common metric space \mathcal{Z} such that $\varphi_n(\mathcal{X}_n)$ converges toward $\varphi(\mathcal{X})$ in the sense of the Hausdorff topology.

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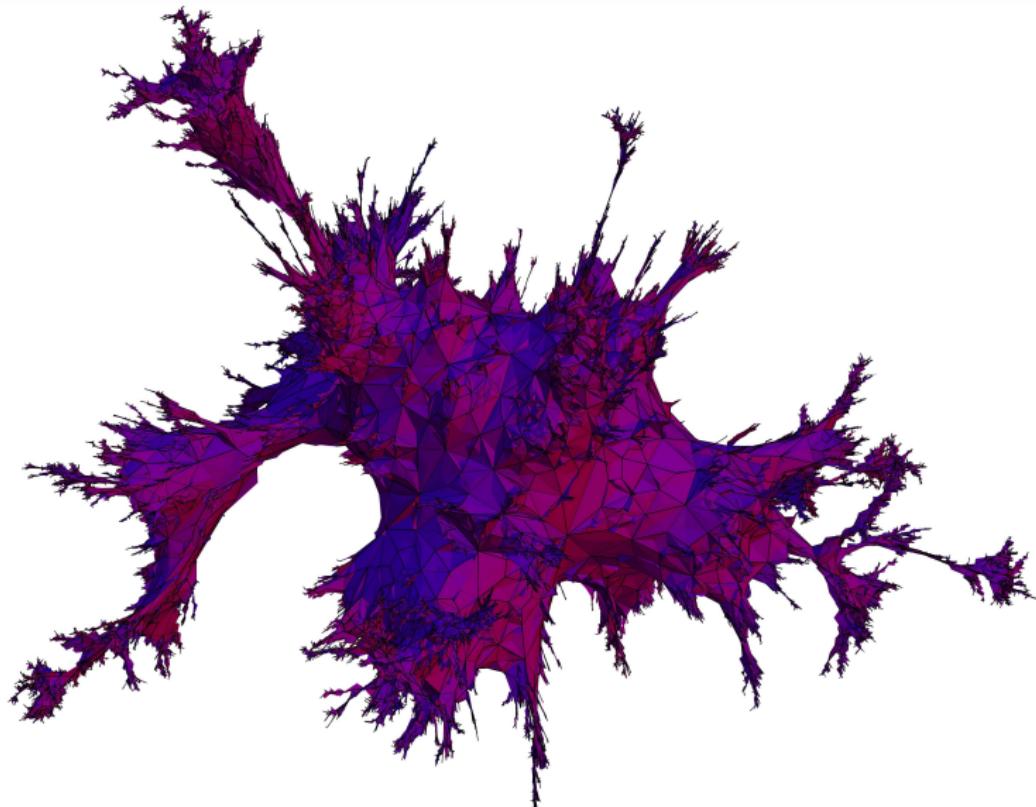
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Bipartite maps
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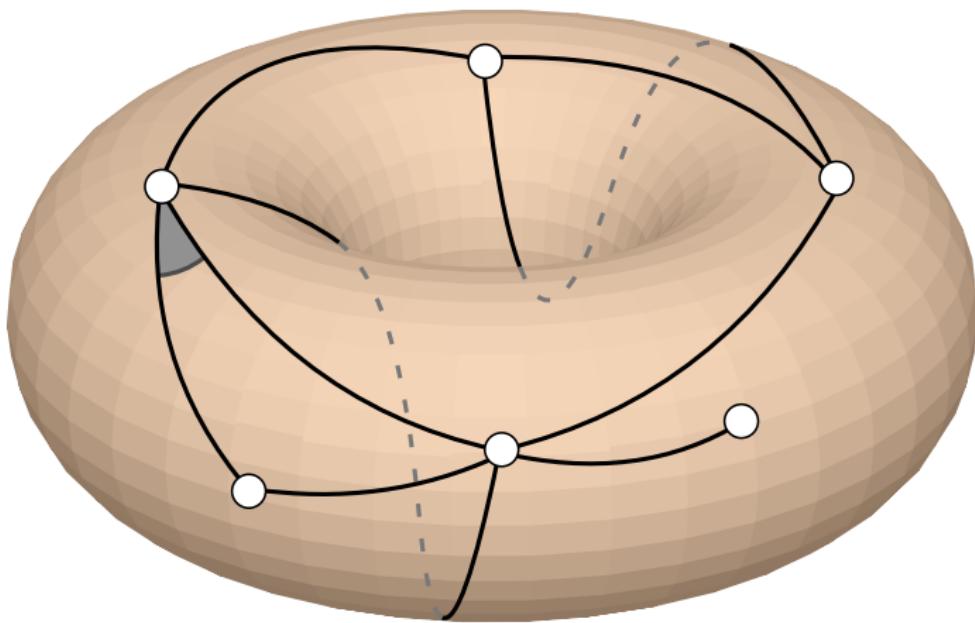
General maps
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Bipartite quadrangulations
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Uniform plane quadrangulation with 50 000 faces

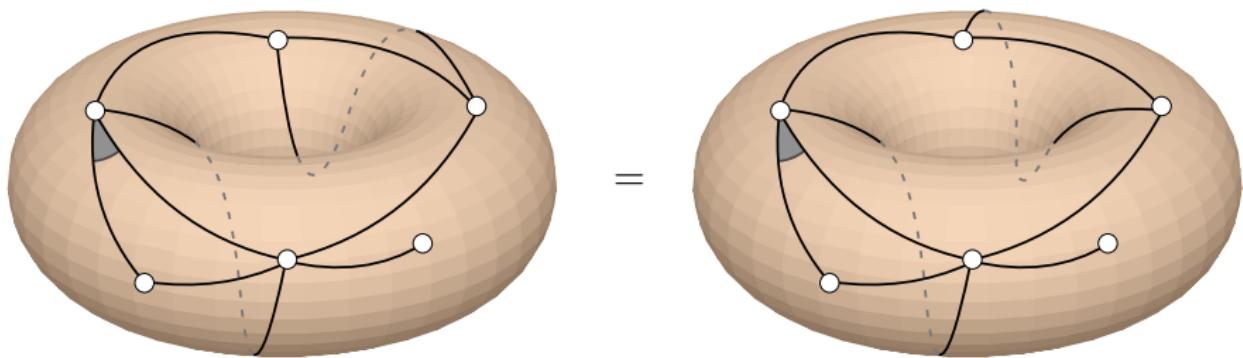


Genus g maps



genus g map: graph embedded in the surface of genus g , in such a way that the faces are homeomorphic to disks

Edge deformation



maps are defined up to direct homeomorphism of the underlying surface

Scaling limit: the Brownian surface of genus g

- We denote by $V(\mathfrak{m})$ the vertex-set of \mathfrak{m} and $d_{\mathfrak{m}}$ the graph metric.

Theorem (B. & Miermont, in prep.)

Let $g \geq 1$ be fixed and \mathfrak{q}_n be a uniform genus g quadrangulation with n faces. The sequence $(V(\mathfrak{q}_n), (8n/9)^{-1/4} d_{\mathfrak{q}_n})_{n \geq 1}$ converges weakly in the sense of the Gromov–Hausdorff topology toward a random compact metric space a.s. homeomorphic to the surface of genus g , and called the *Brownian surface of genus g* .

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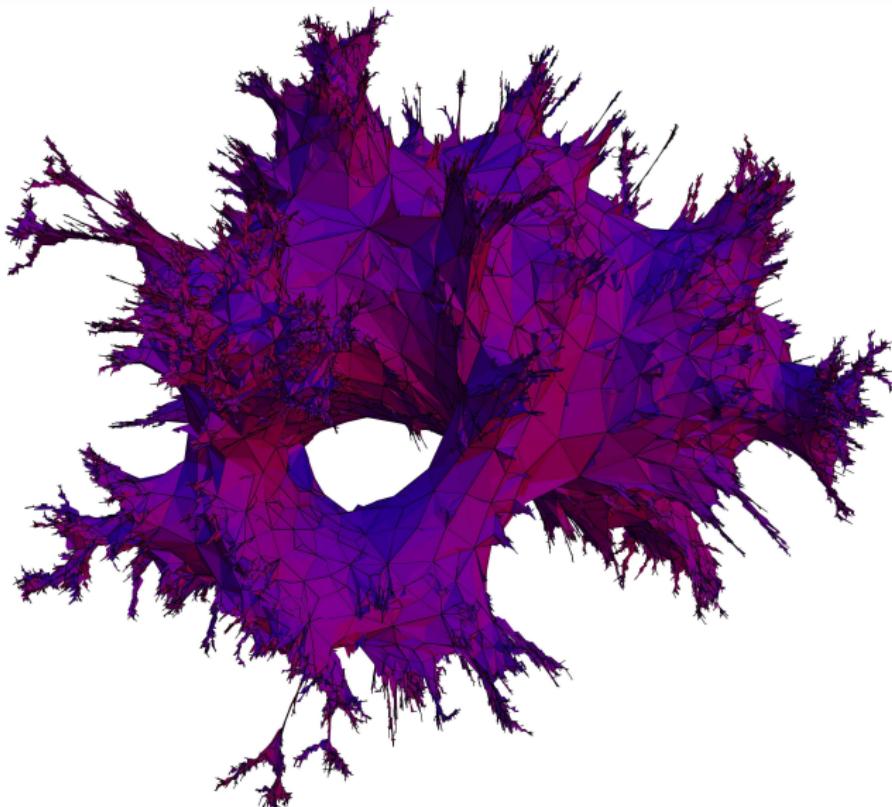
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Bipartite maps
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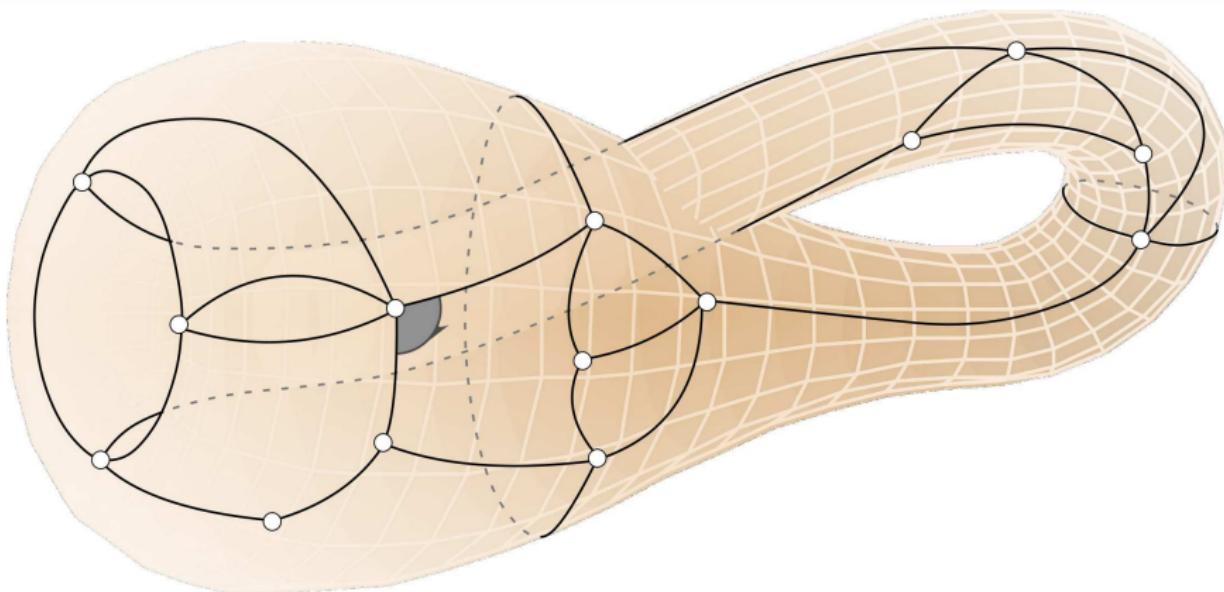
General maps
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Bipartite quadrangulations
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Uniform genus 1 quadrangulation with 50 000 faces



Nonorientable maps



root: distinguished corner given with a local orientation

maps are defined up to homeomorphism of the underlying surface

Scaling limit: Brownian nonorientable surfaces

- We denote by $V(\mathfrak{m})$ the vertex-set of \mathfrak{m} and $d_{\mathfrak{m}}$ the graph metric.

Theorem (Chapuy & Dołęga '17)

Let S be a fixed nonorientable surface and \mathfrak{q}_n be a uniform quadrangulation of S with n faces. *Up to extraction*, the sequence $(V(\mathfrak{q}_n), (8n/9)^{-1/4} d_{\mathfrak{q}_n})_{n \geq 1}$ converges weakly in the sense of the Gromov–Hausdorff topology toward a random compact metric space.

Enumeration results in the case of triangulations

Proposition

The number of (rooted) triangulations of S with $2n$ faces (and thus $3n$ edges and $n + 2 - 2h$ vertices) is asymptotically equivalent to

$$c_S n^{5(h-1)/2} (12\sqrt{3})^n,$$

where h is the type of S and c_S is a constant that depends on S .

h	S	c_S	h	S	c_S
0	sphere	$\frac{\sqrt{6}}{\sqrt{\pi}}$	$\frac{1}{2}$	projective plane	$\frac{2^{-3/4} 3^{5/4}}{\Gamma(3/4)}$
1	torus	$\frac{1}{8}$	1	Klein bottle	$\frac{3}{2}$

Enumeration results in the case of triangulations

Proposition

The gfun of triangulations counted with weight x per vertex is

sphere: $\frac{1}{2}\sigma^3(1 - \sigma)(1 - 4\sigma + 2\sigma^2)$

proj. plane: $\frac{1}{2}(1 - 2\sigma)(1 - \sigma + \sigma^2) - \frac{1}{2}\sqrt{1 - 6\sigma + 6\sigma^2}$

torus: $\frac{1}{2}\sigma(1 - \sigma)(1 - 6\sigma + 6\sigma^2)^{-2}$

Klein bottle:

$$3\sigma(1 - \sigma)(1 - 6\sigma + 6\sigma^2)^{-2} \left(7 - 30\sigma + 30\sigma^2 - 6(1 - 2\sigma)\sqrt{1 - 6\sigma + 6\sigma^2} \right)$$

where σ is given by $x = \frac{1}{2}\sigma(1 - \sigma)(1 - 2\sigma)$ and $\sigma(0) = 0$.

A history of bijections

Encoding of pointed maps

	sphere	orientable	nonorientable
bip. quad.	[CV'81] – [S'98]	[CMS'09]	[CD'17]
general maps	[BDG'04]	[BDG'04]+[CMS'09]	[B'16]

[CV'81]: Cori–Vauquelin

[S'98]: Schaeffer

[BDG'04]: Bouttier–Di Francesco–Guitter

[CMS'09]: Chapuy–Marcus–Schaeffer

[CD'17]: Chapuy–Dołęga

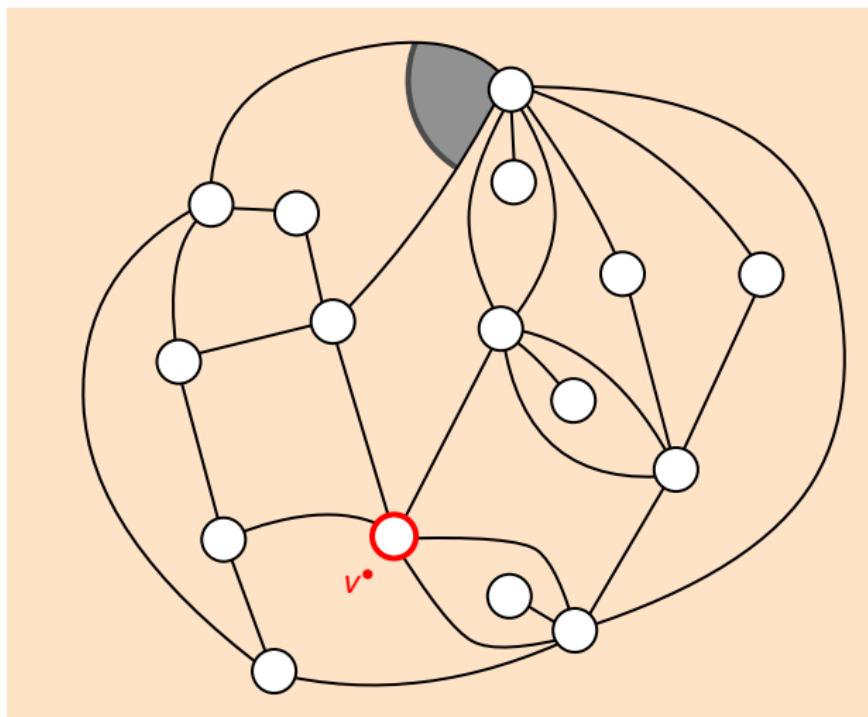
[B'16]: this talk

Similar bijections

Multi-pointed quadrangulations: [Miermont '09]

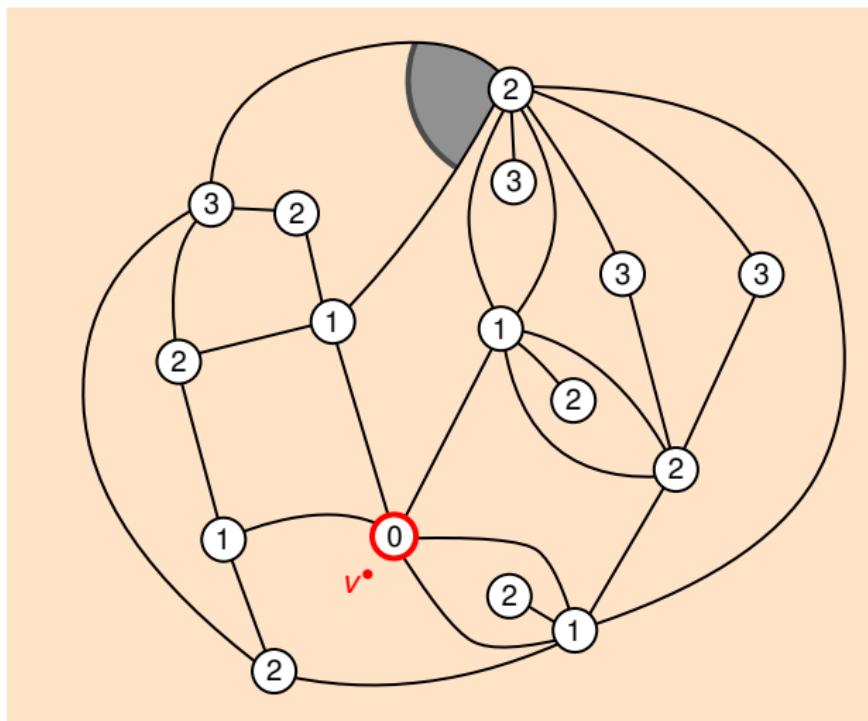
CVS with rules inverted: [Ambjørn–Budd '13]

Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



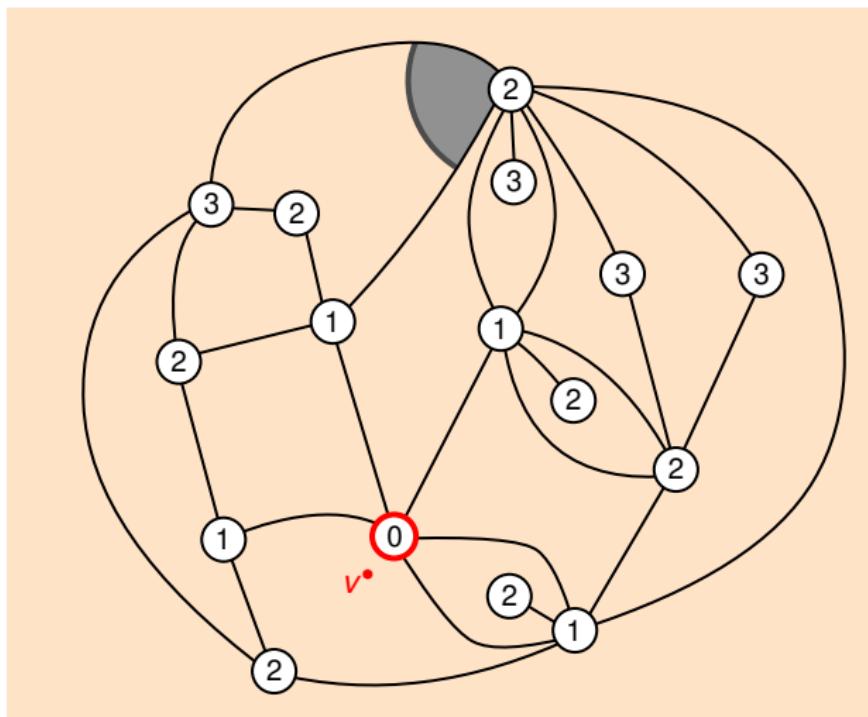
- Start with a pointed quadrangulation.

Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer

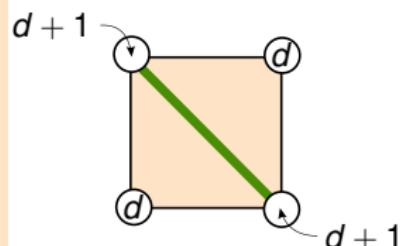
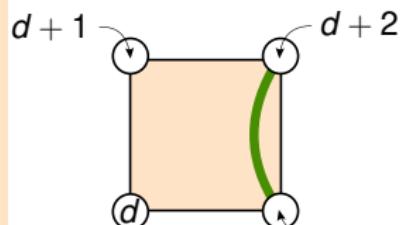


- Start with a pointed quadrangulation.
- Label the vertices with their distance to v^* .

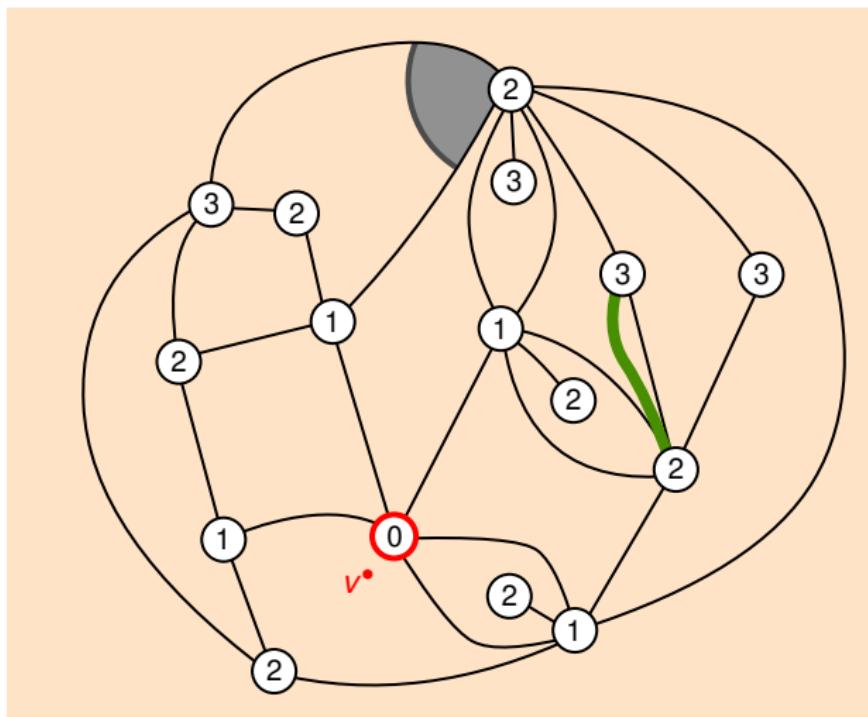
Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



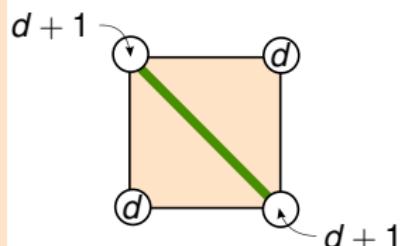
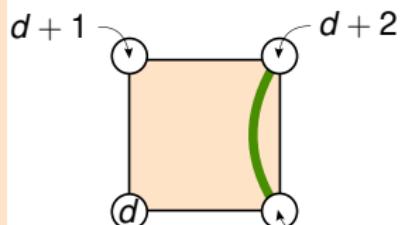
- Apply the rule:



Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



- Apply the rule:



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Orientable case
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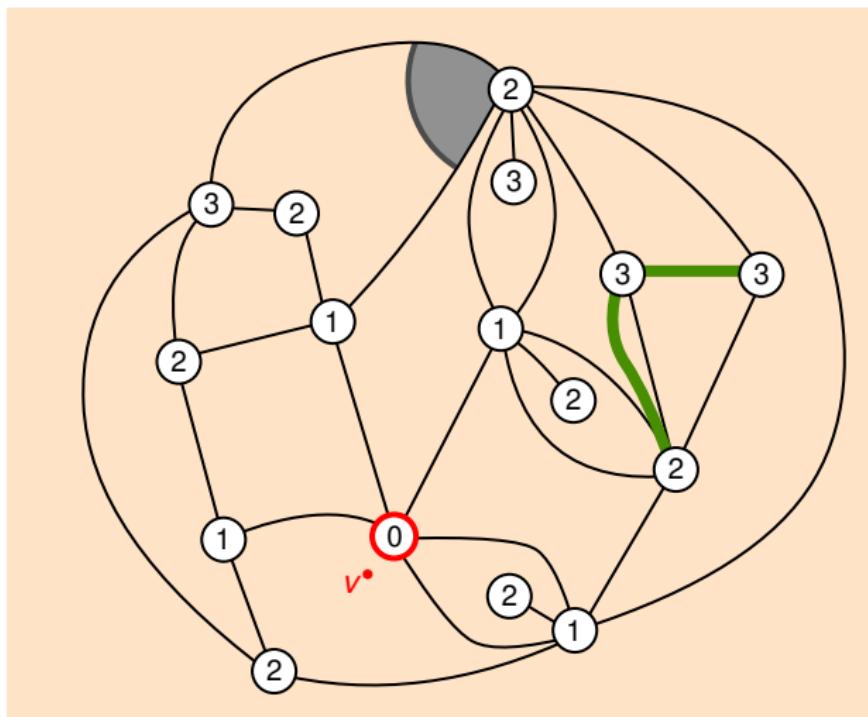
Problem
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Bipartite maps
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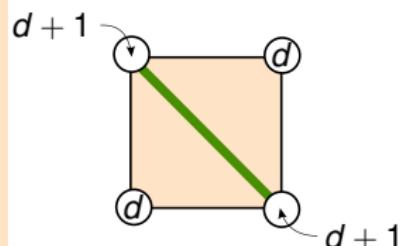
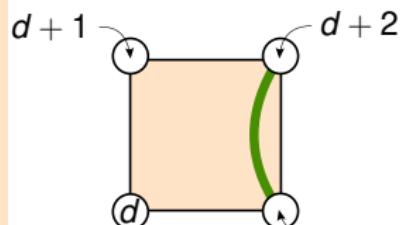
General maps
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Bipartite quadrangulations
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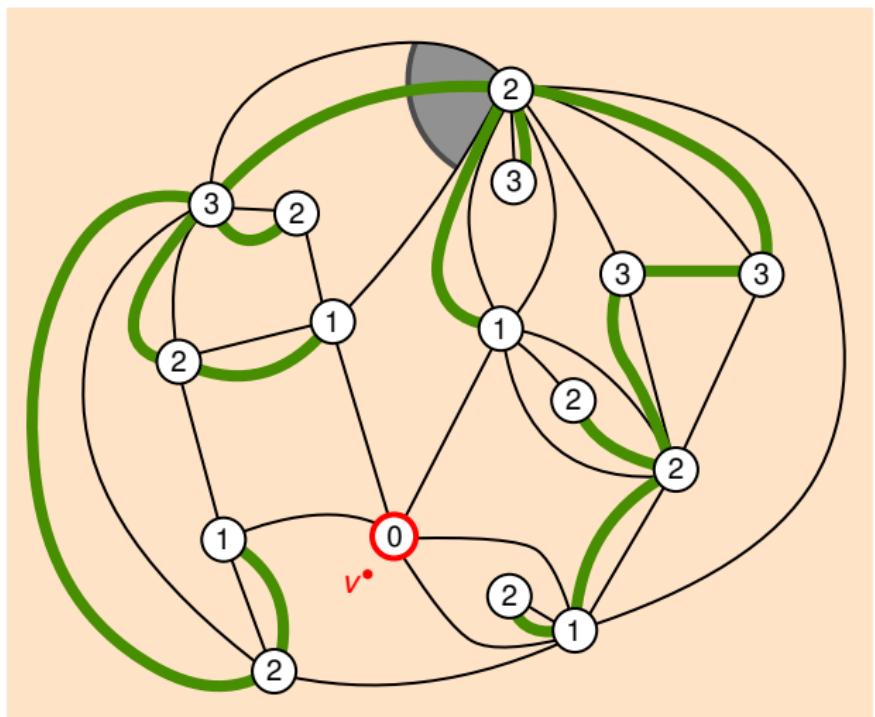
Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



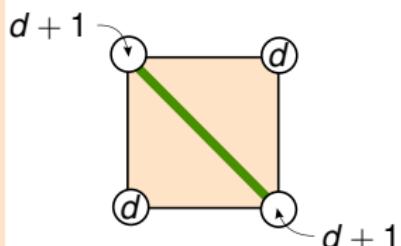
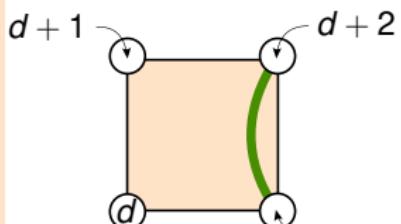
- Apply the rule:



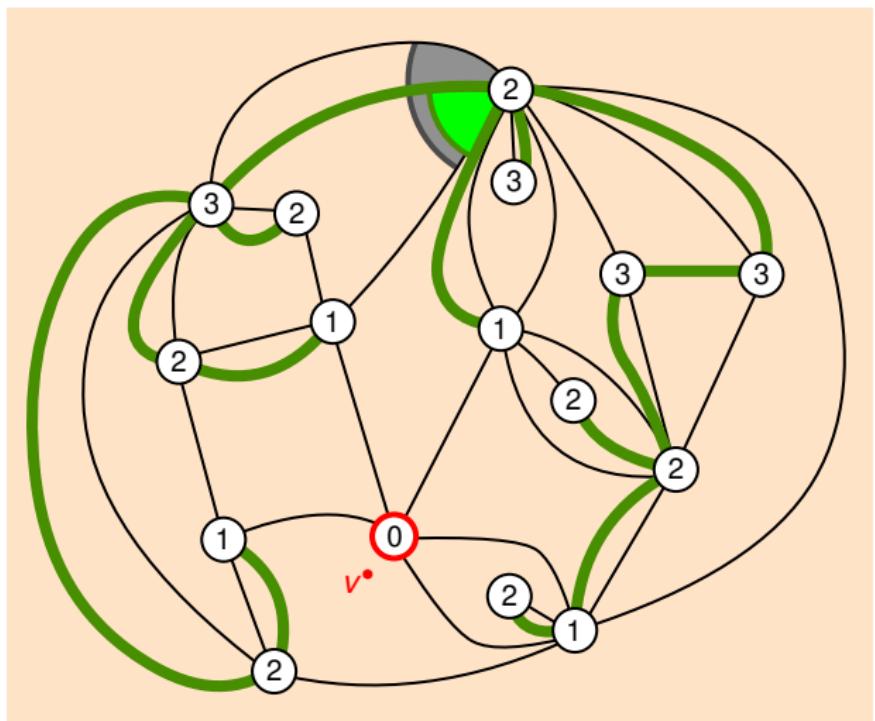
Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



○ Apply the rule:

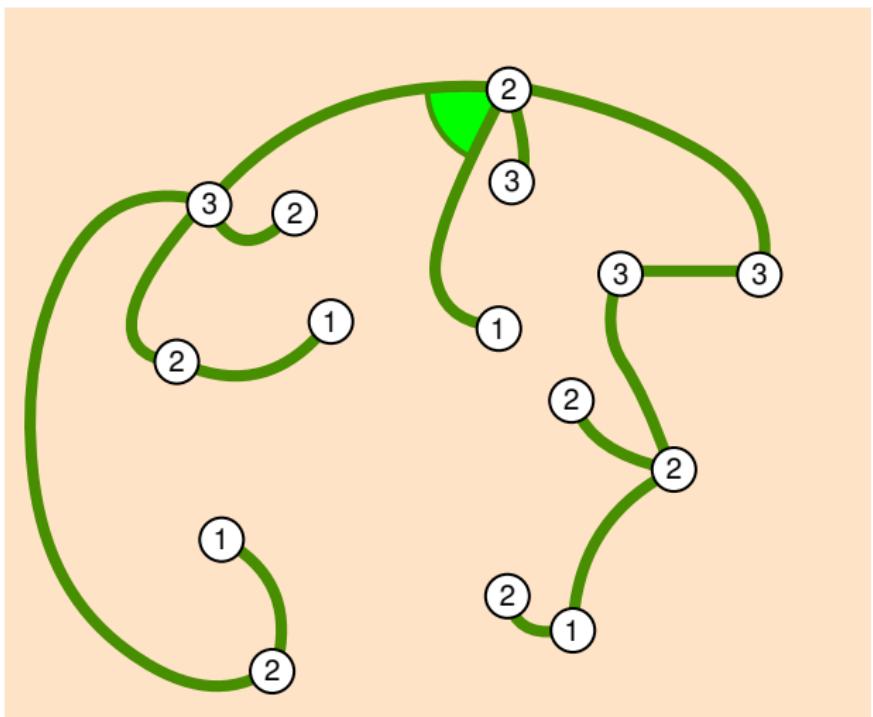


Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



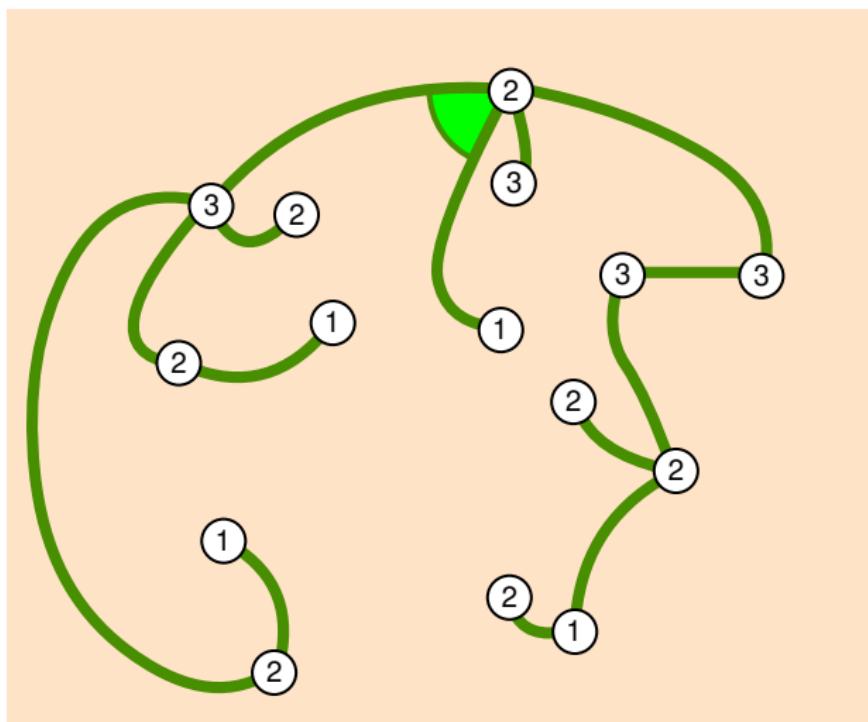
- Start with a pointed quadrangulation.
- Label the vertices with their distance to v^* .
- Apply the rule.
- Root.

Cori–Vauquelin–Schaeffer / Chapuy–Marcus–Schaeffer



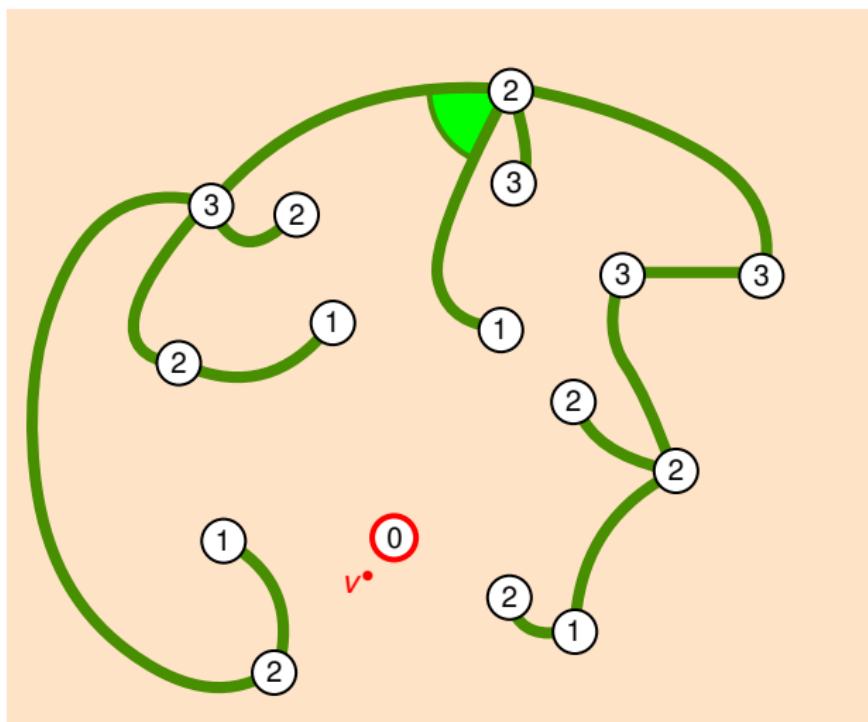
- Start with a pointed quadrangulation.
- Label the vertices with their distance to v^* .
- Apply the rule.
- Root.
- Remove the initial edges and v^* .

Inverse construction



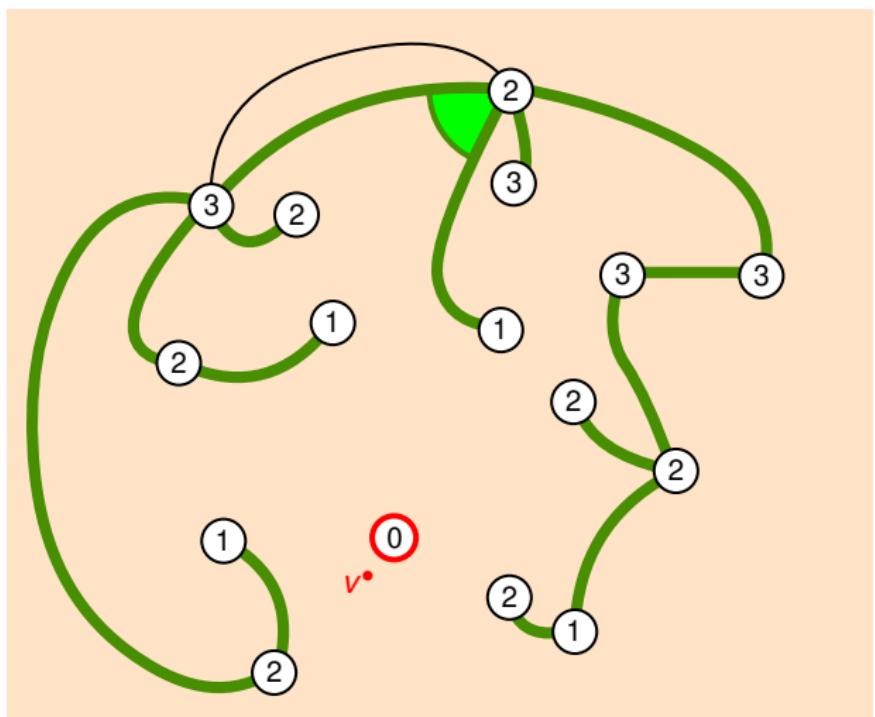
- Take a well-labeled unicellular map.

Inverse construction



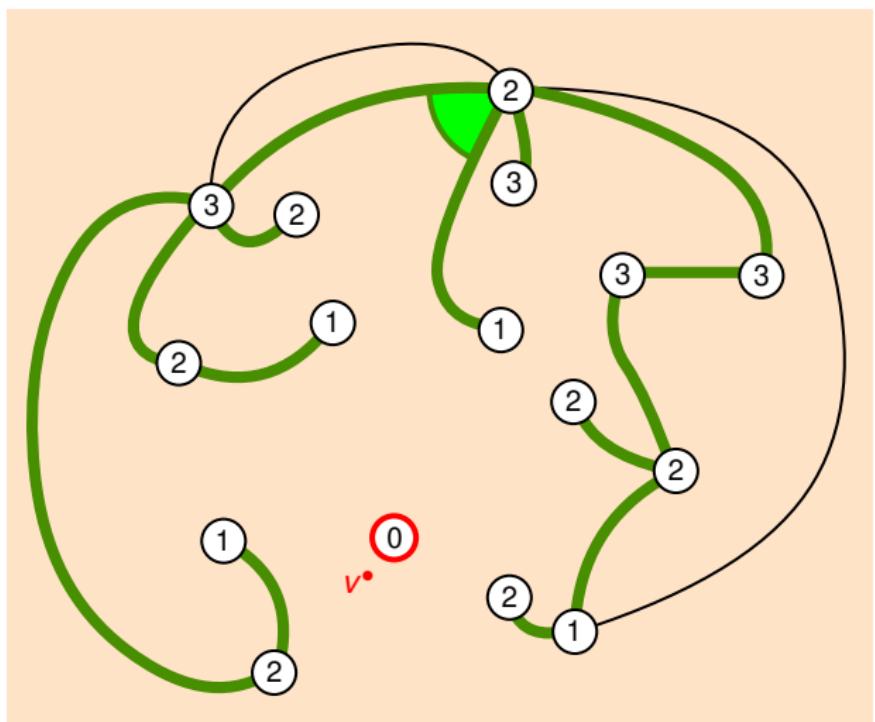
- Take a well-labeled unicellular map.
- Add a vertex $v\bullet$ inside the unique face.

Inverse construction



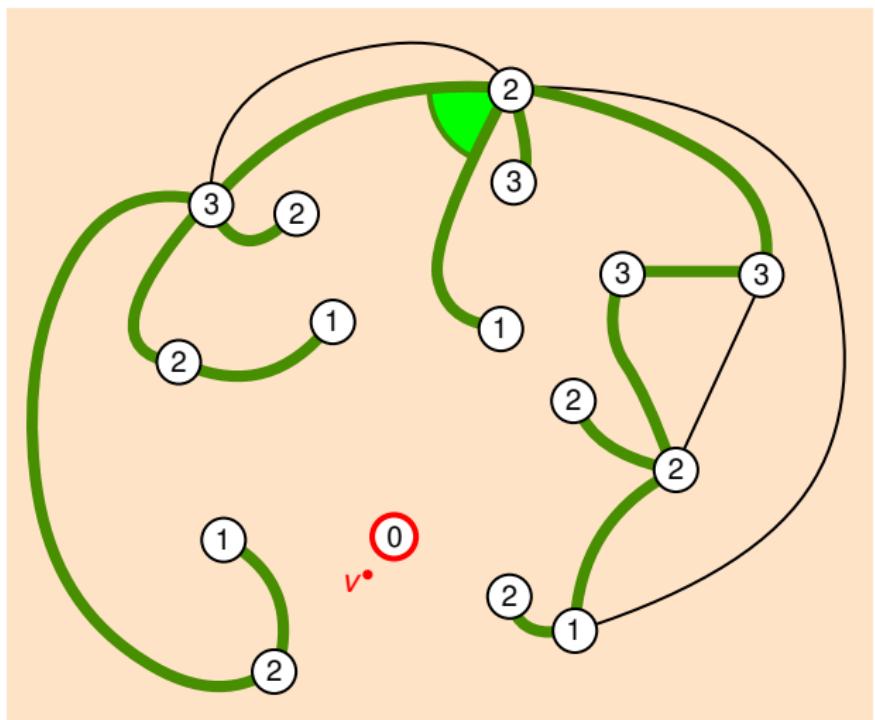
- Take a well-labeled unicellular map.
- Add a vertex v inside the unique face.
- Link every corner to the first subsequent corner having a strictly smaller label.

Inverse construction



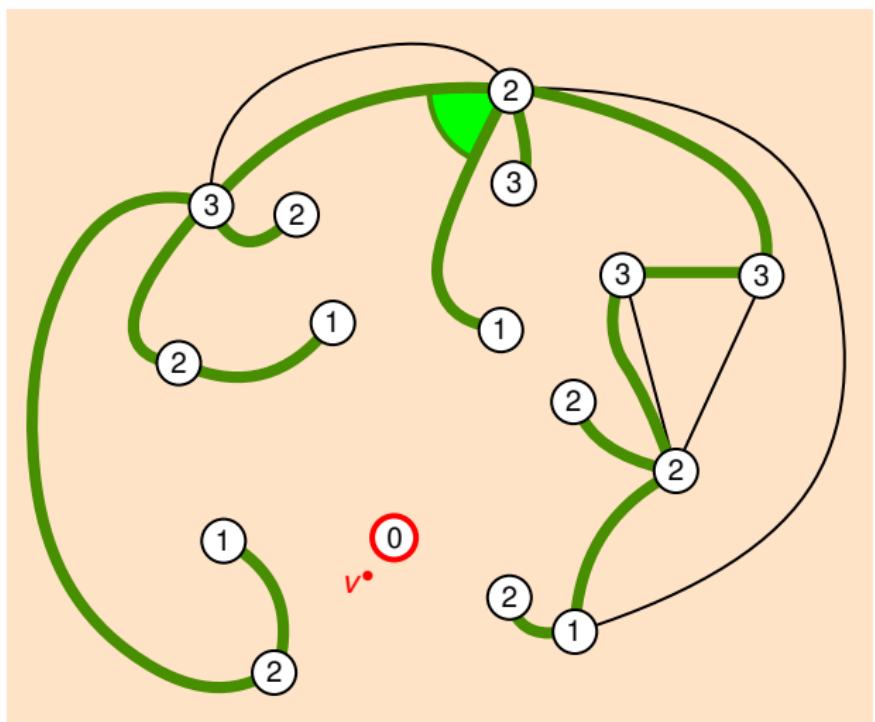
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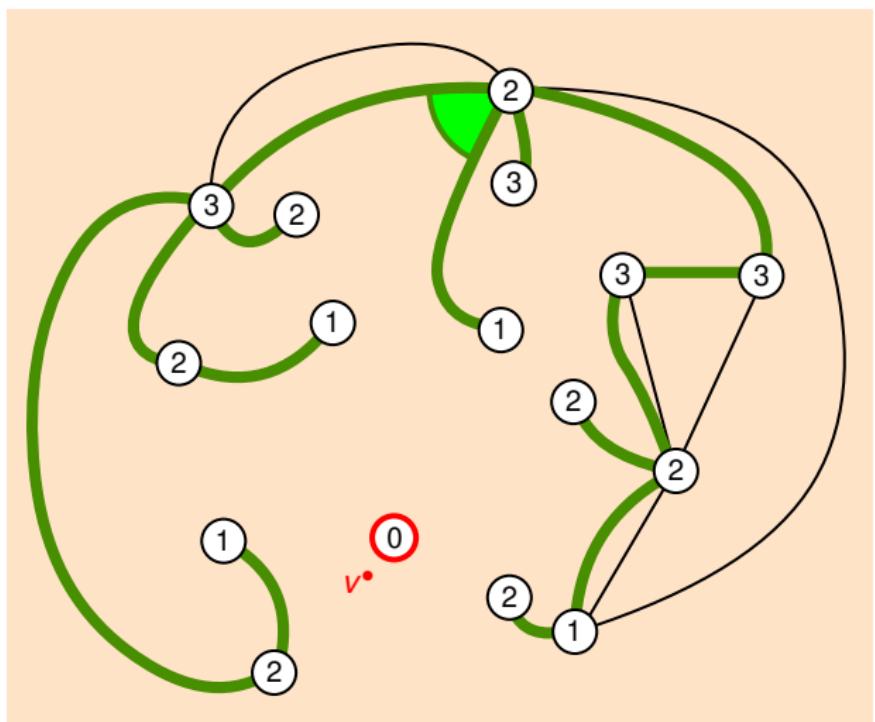
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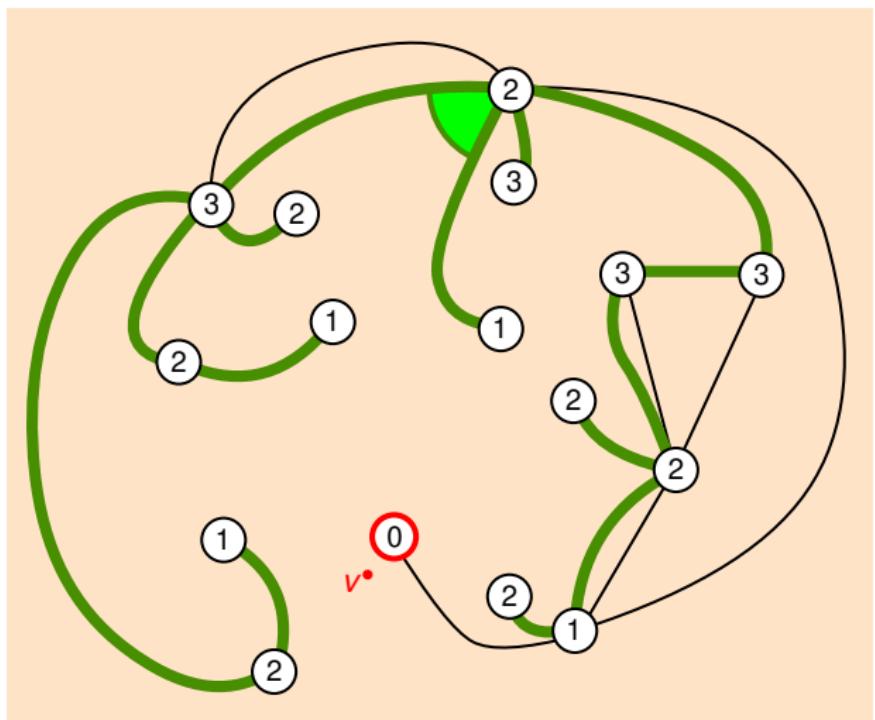
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Inverse construction



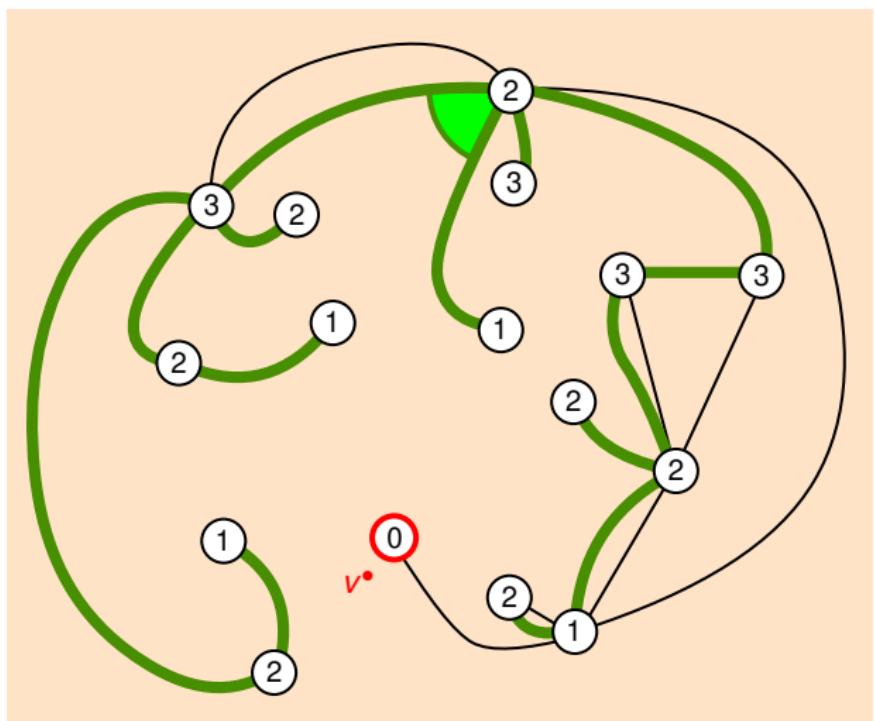
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Inverse construction



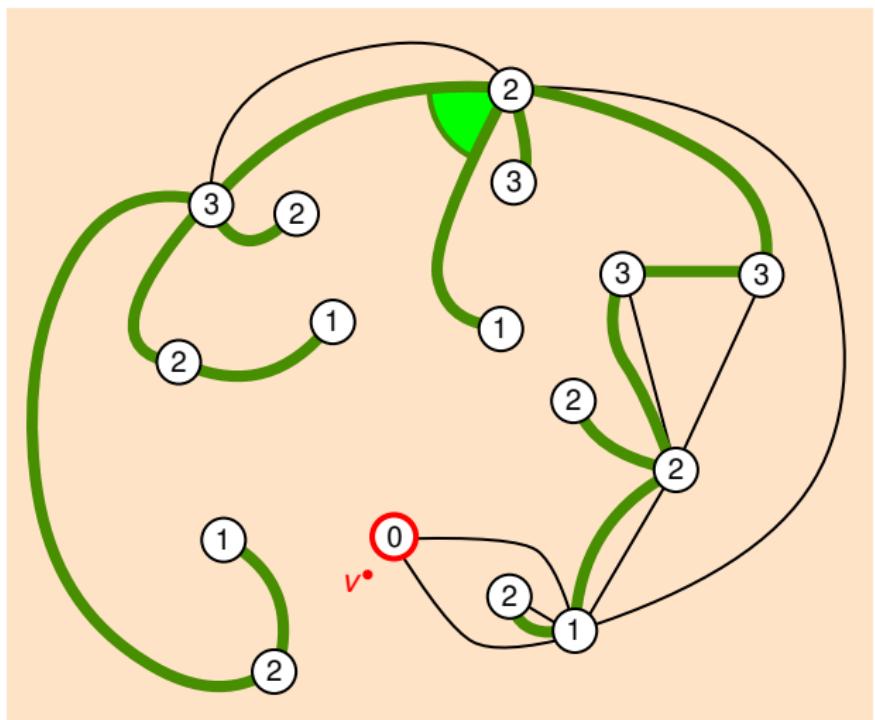
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Inverse construction



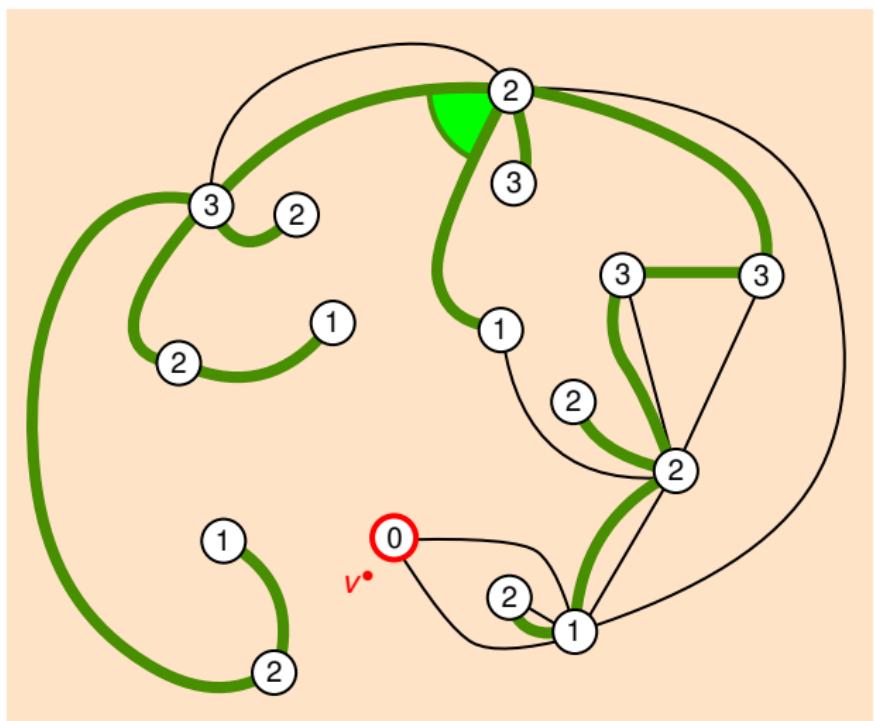
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Inverse construction



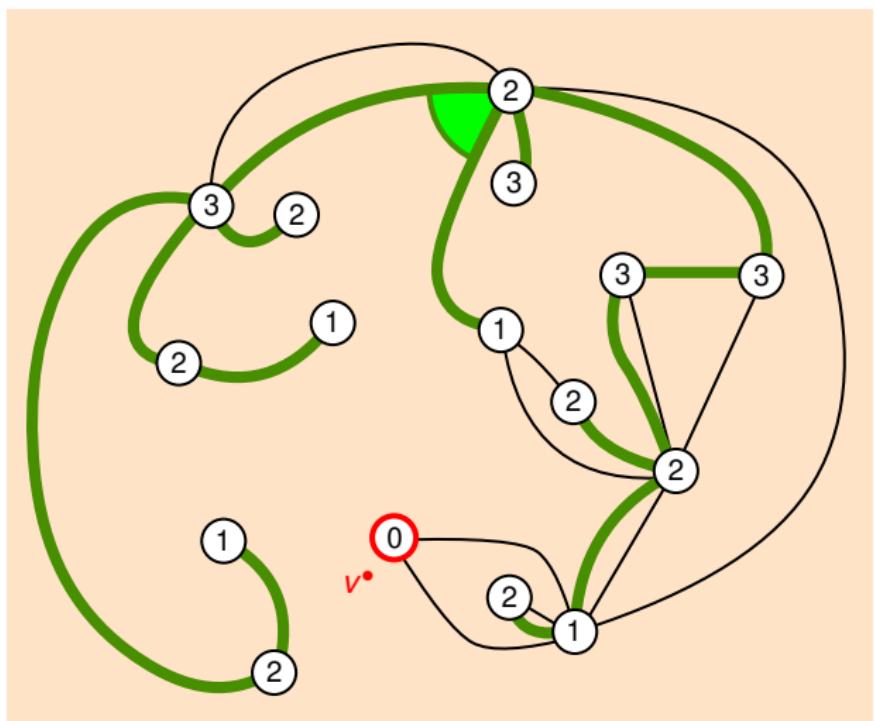
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Inverse construction



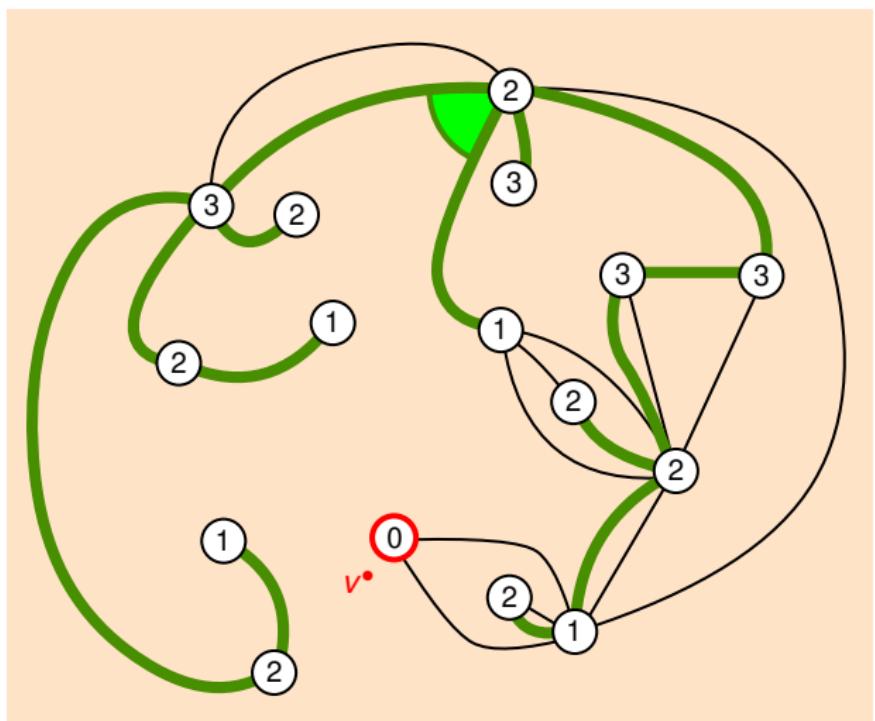
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Inverse construction



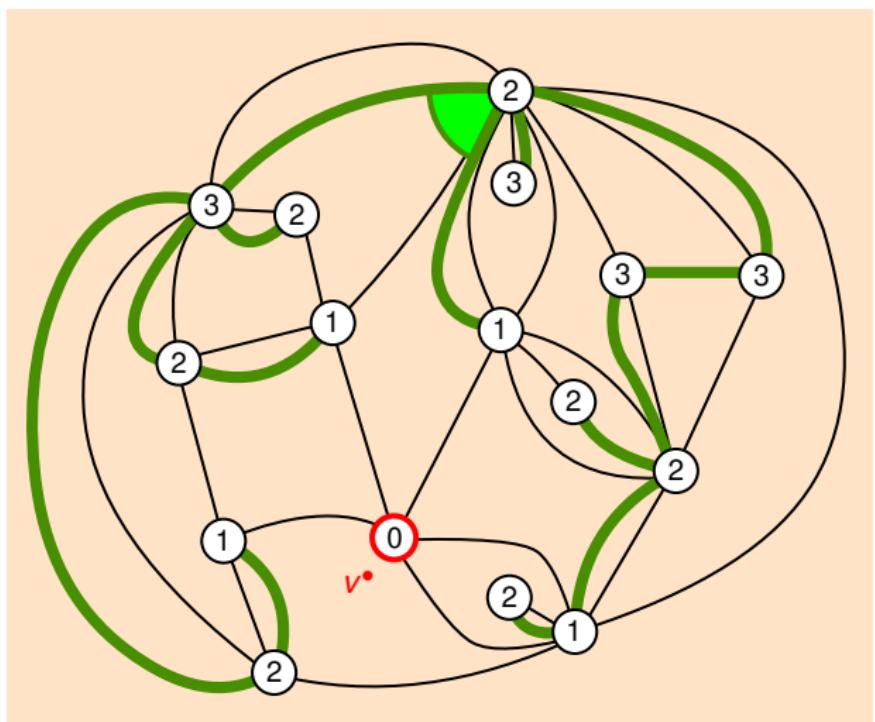
- Take a well-labeled unicellular map.
- Add a vertex v^* inside the unique face.
- Link every corner to the first subsequent corner having a strictly smaller label.

Inverse construction



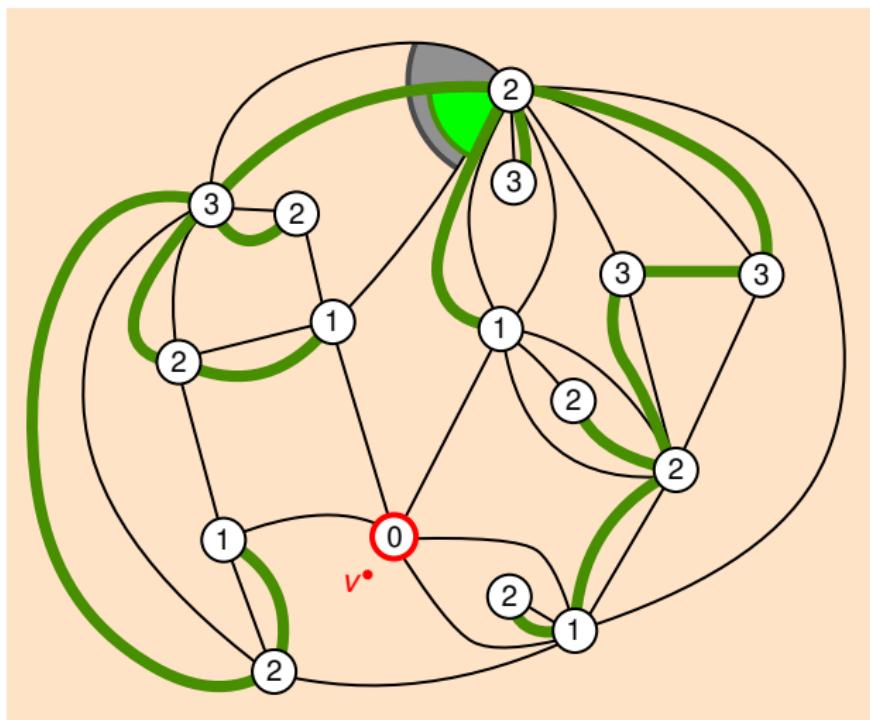
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Inverse construction



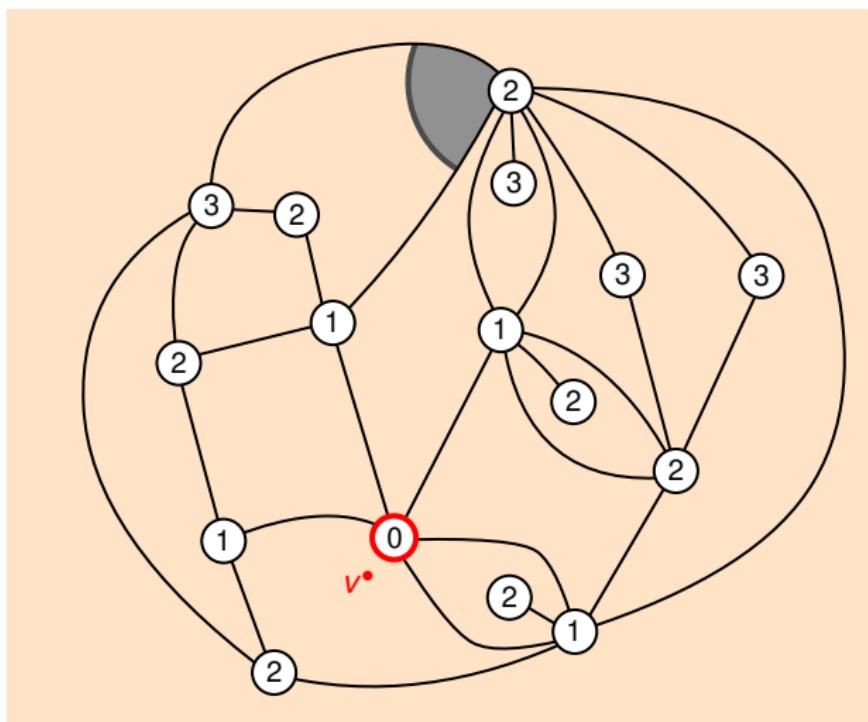
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- Add a vertex v^* inside the unique face.
- Link every corner to the first subsequent corner having a strictly smaller label.

Inverse construction



- Take a well-labeled unicellular map.
- Add a vertex v^* inside the unique face.
- Link every corner to the first subsequent corner having a strictly smaller label.
- Root and remove the initial edges.

Inverse construction



- Take a well-labeled unicellular map.
- Add a vertex v^* inside the unique face.
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- Root and remove the initial edges.

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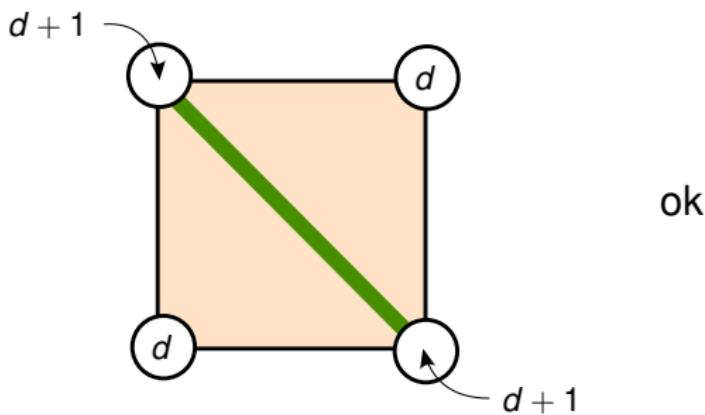
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What could go wrong with nonorientable maps?

From quadrangulations to unicellular maps



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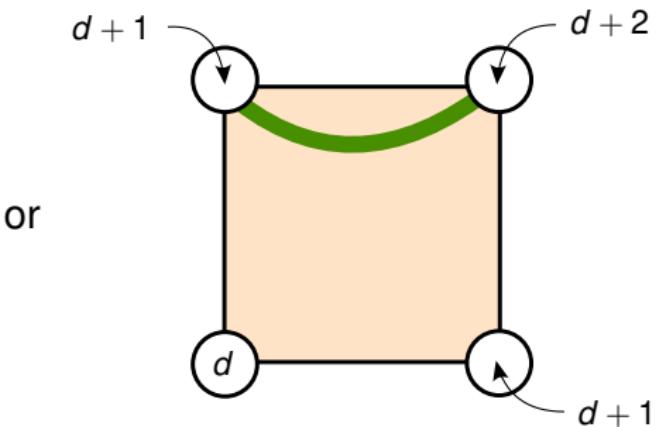
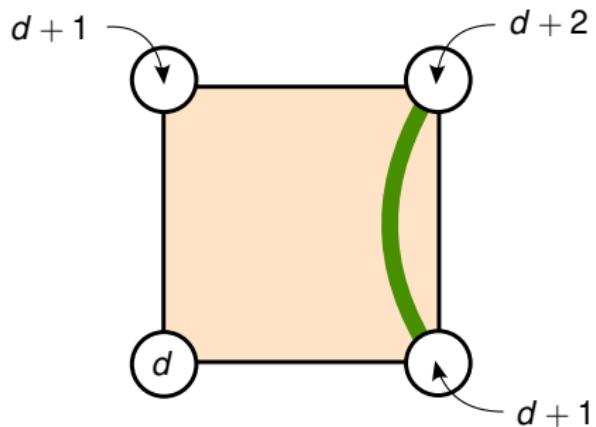
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From quadrangulations to unicellular maps



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From unicellular maps to quadrangulations



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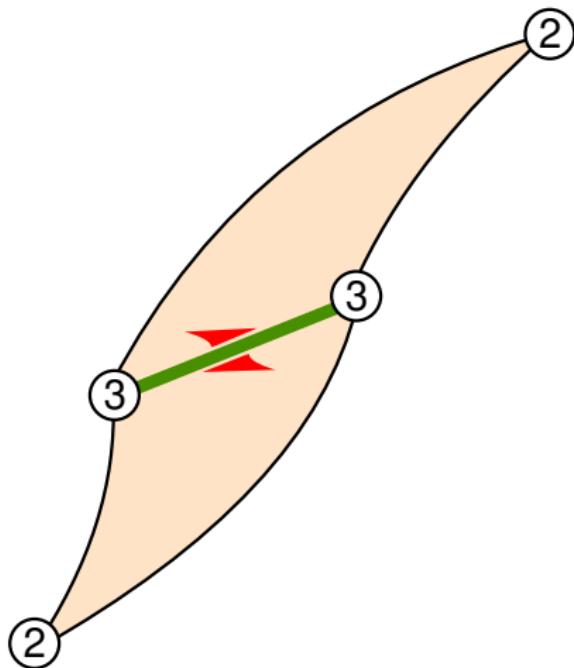
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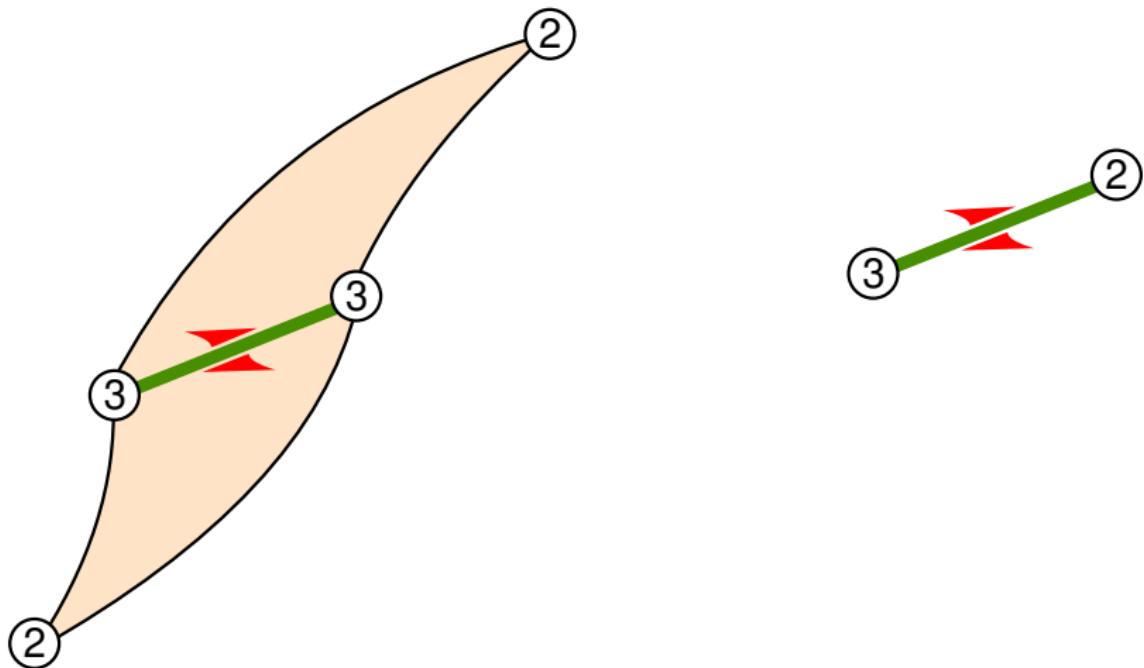
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Bipartite quadrangulations
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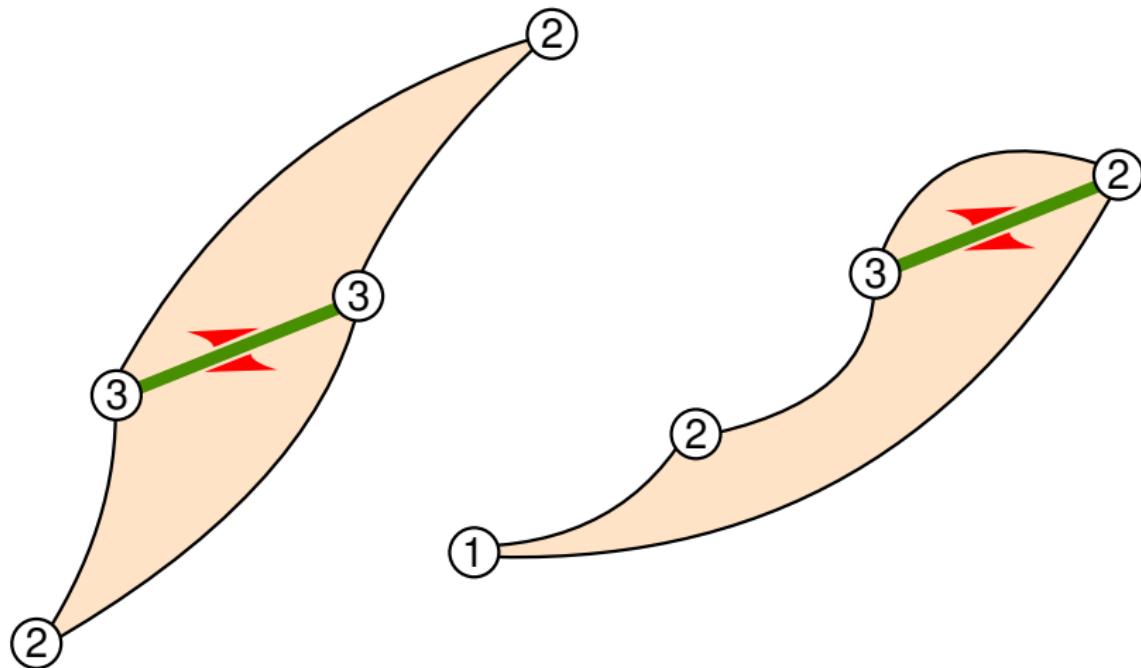
What could go wrong with nonorientable maps?

From unicellular maps to quadrangulations



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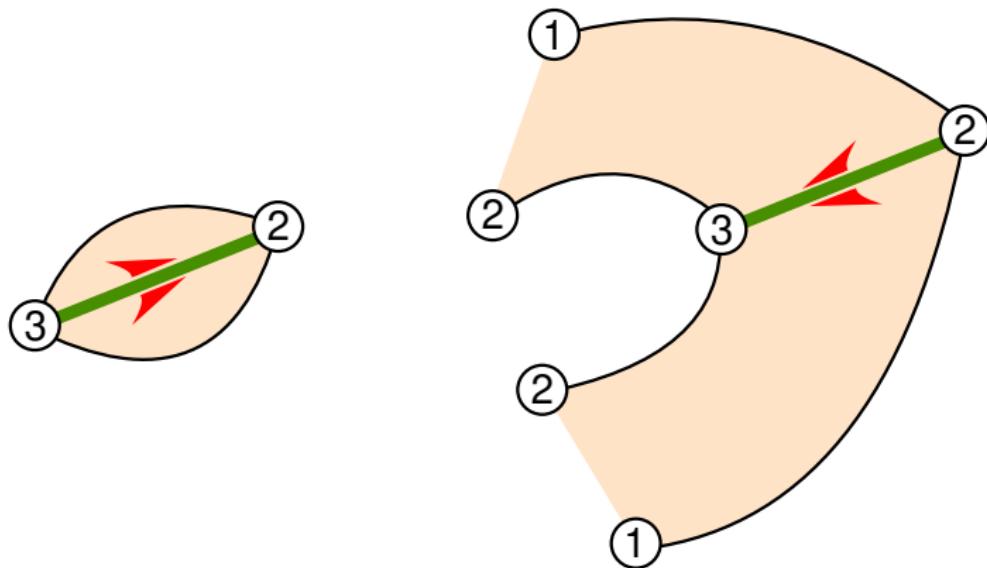
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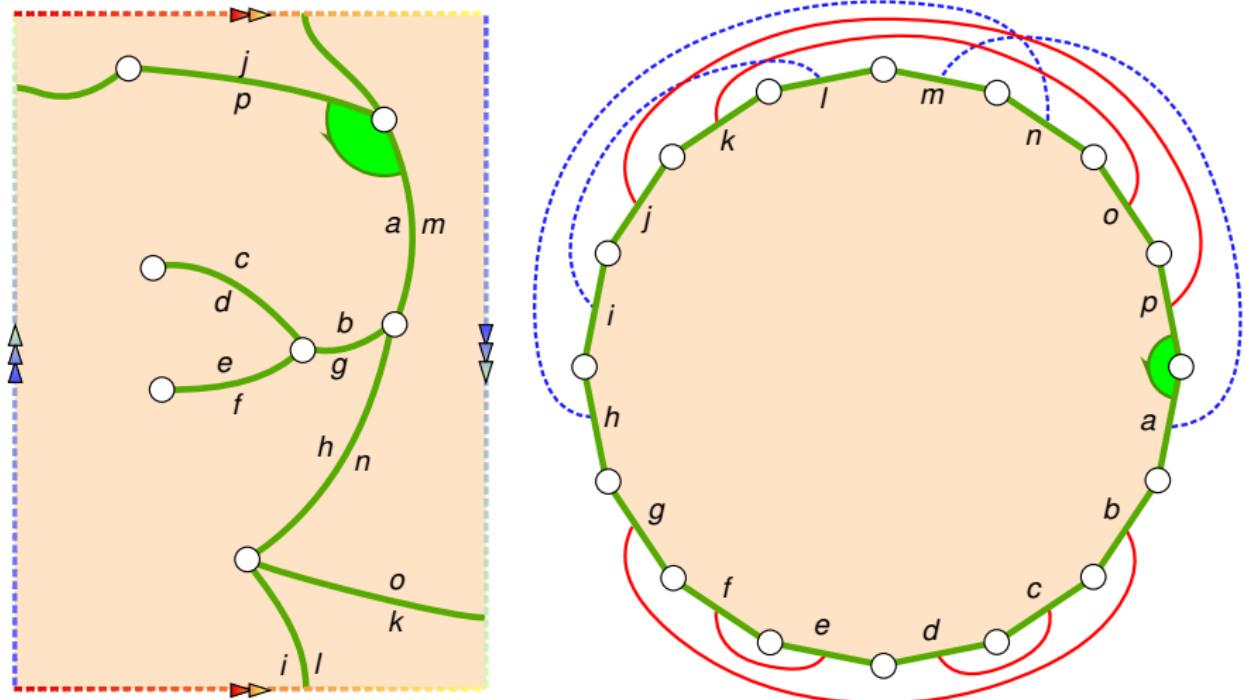
Bipartite quadrangulations
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What could go wrong with nonorientable maps?

From unicellular maps to quadrangulations



Unicellular maps seen as polygons with paired sides



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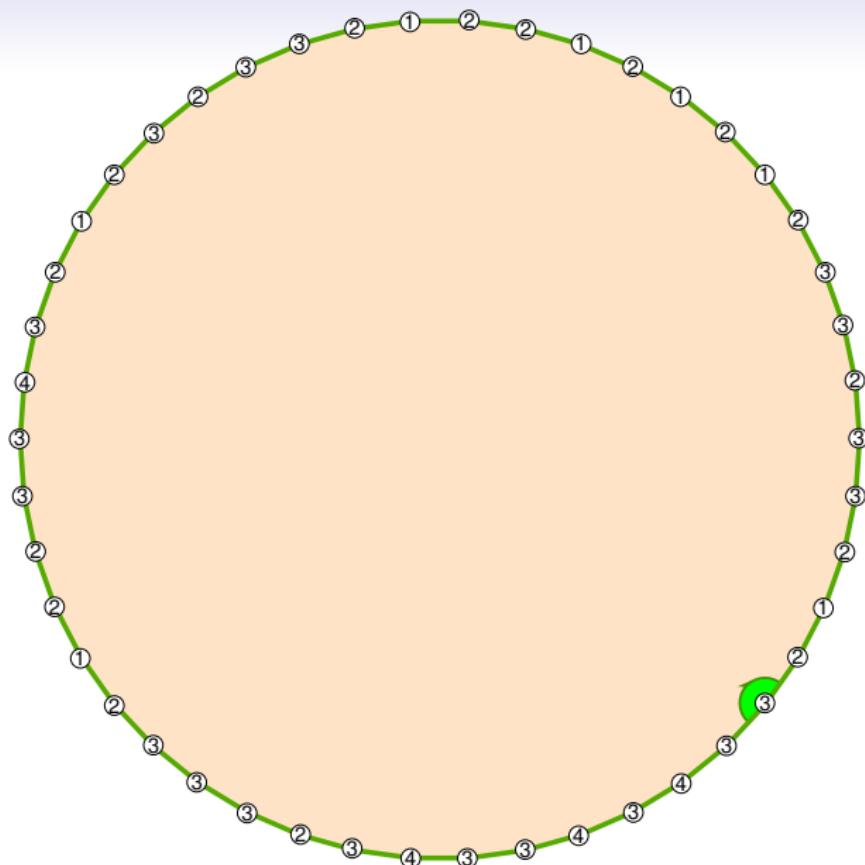
Orientable case
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A bijection for nonorientable maps

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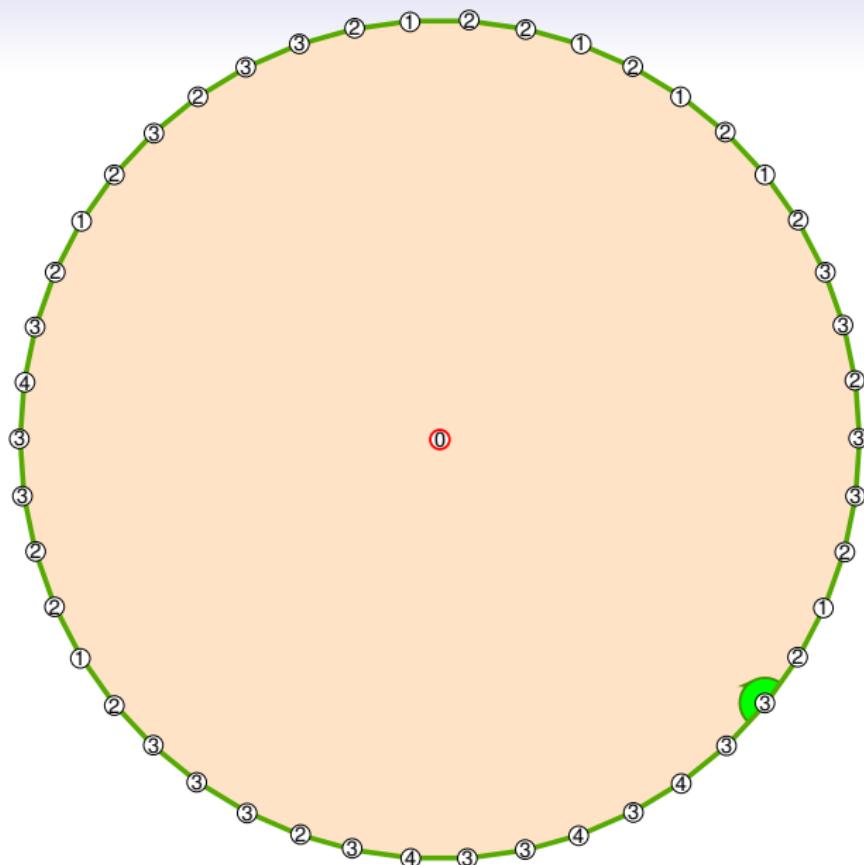
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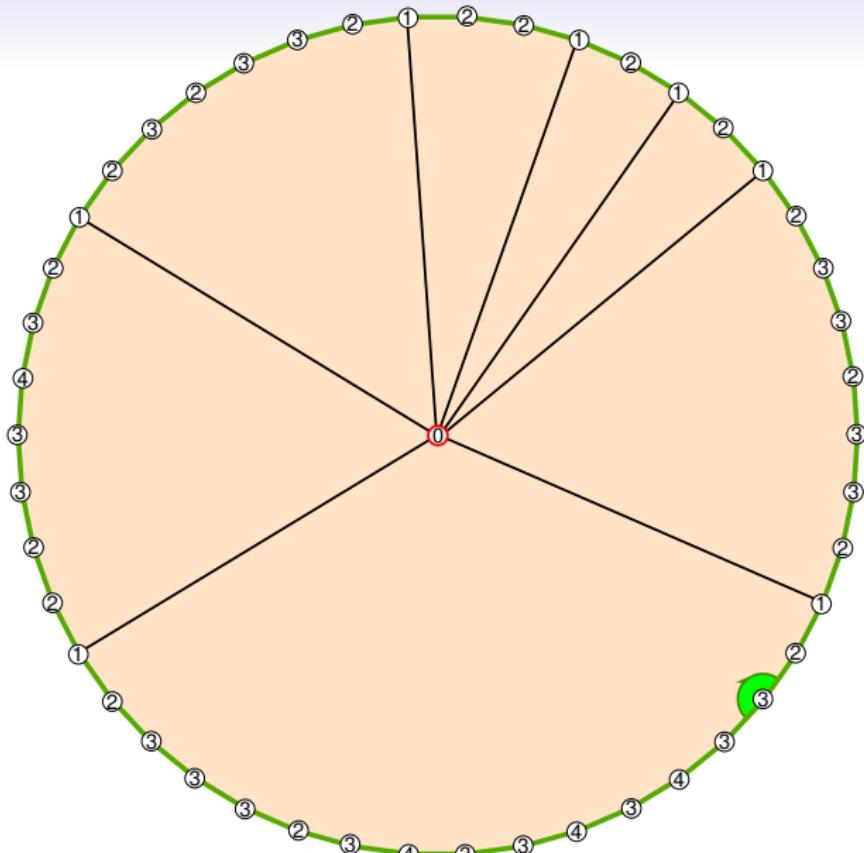
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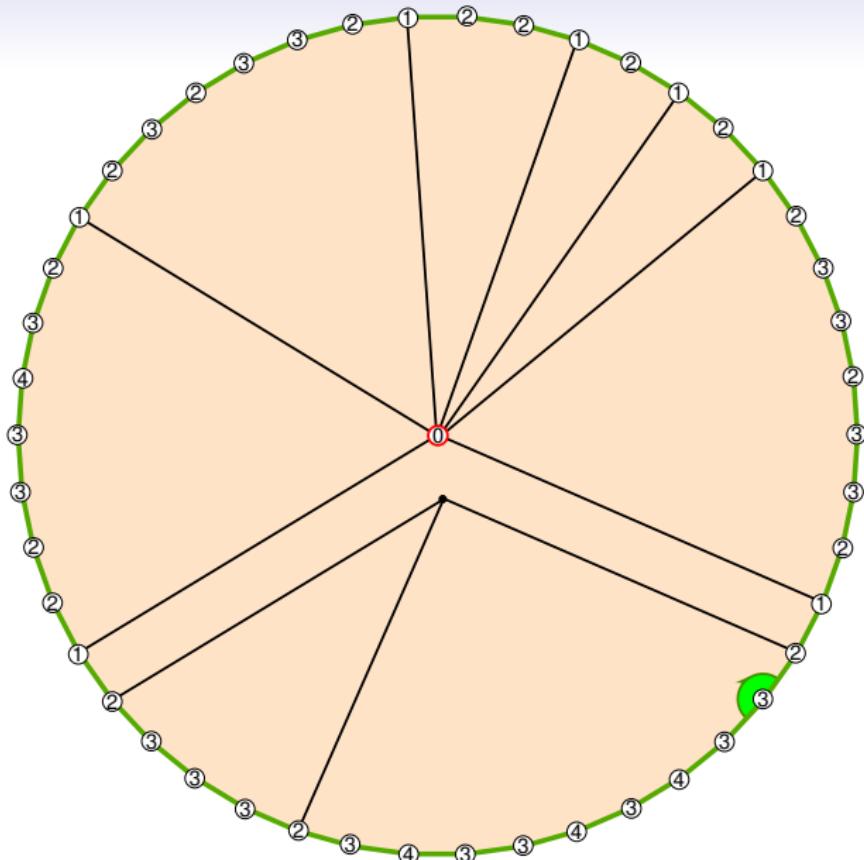
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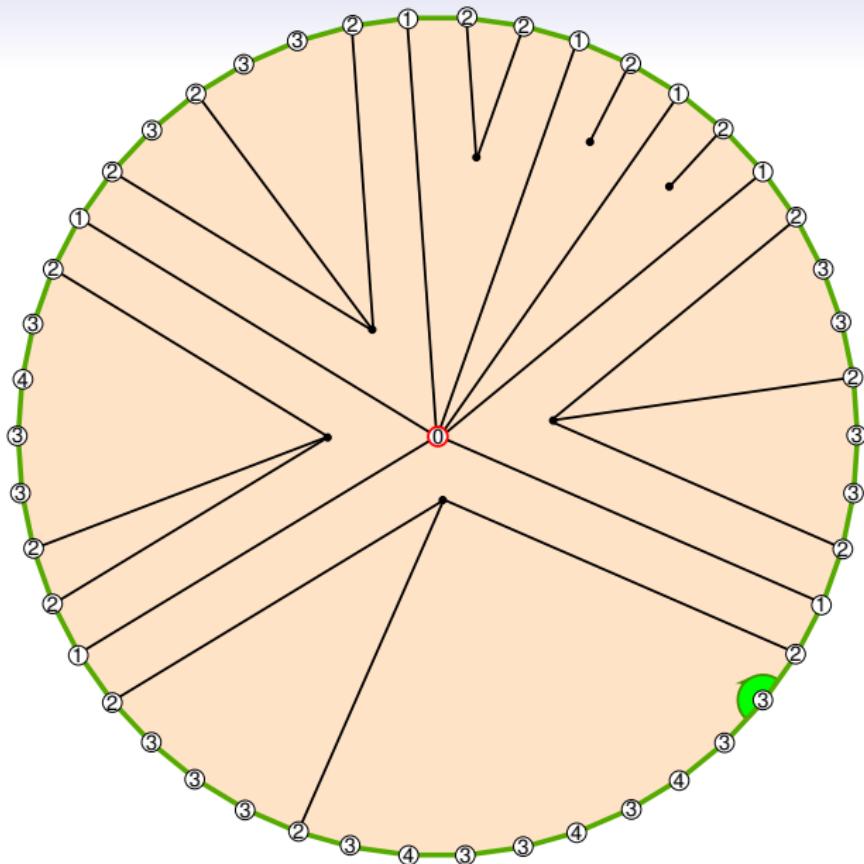
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A bijection for nonorientable maps

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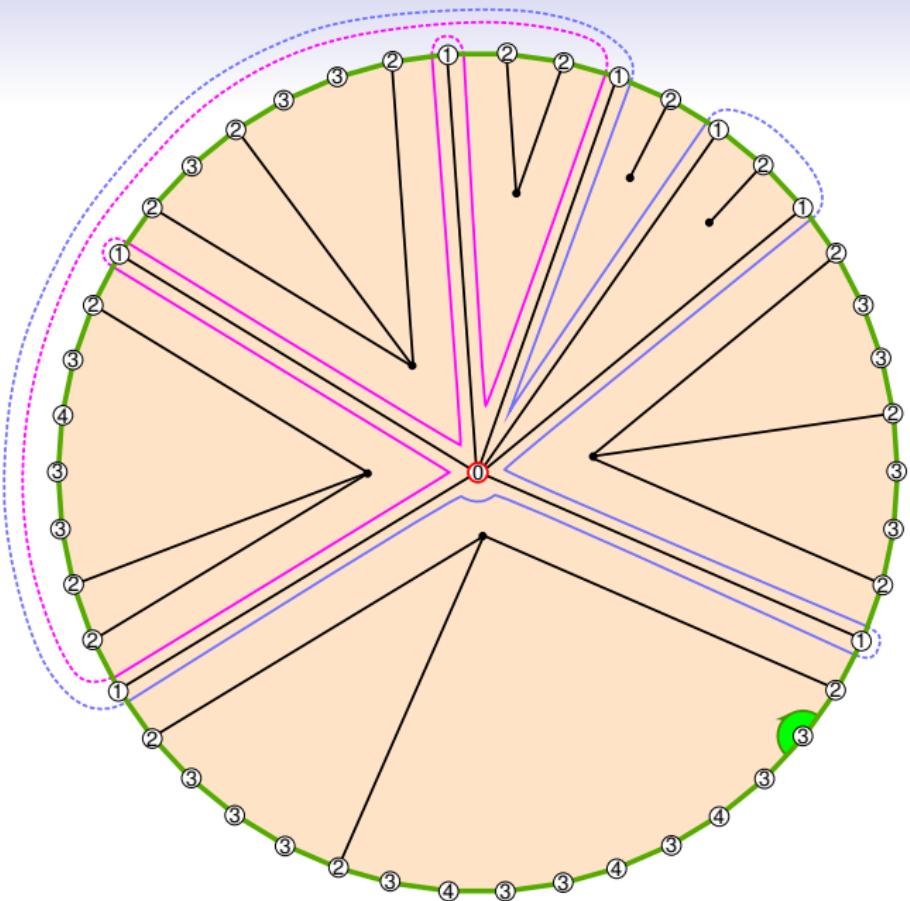
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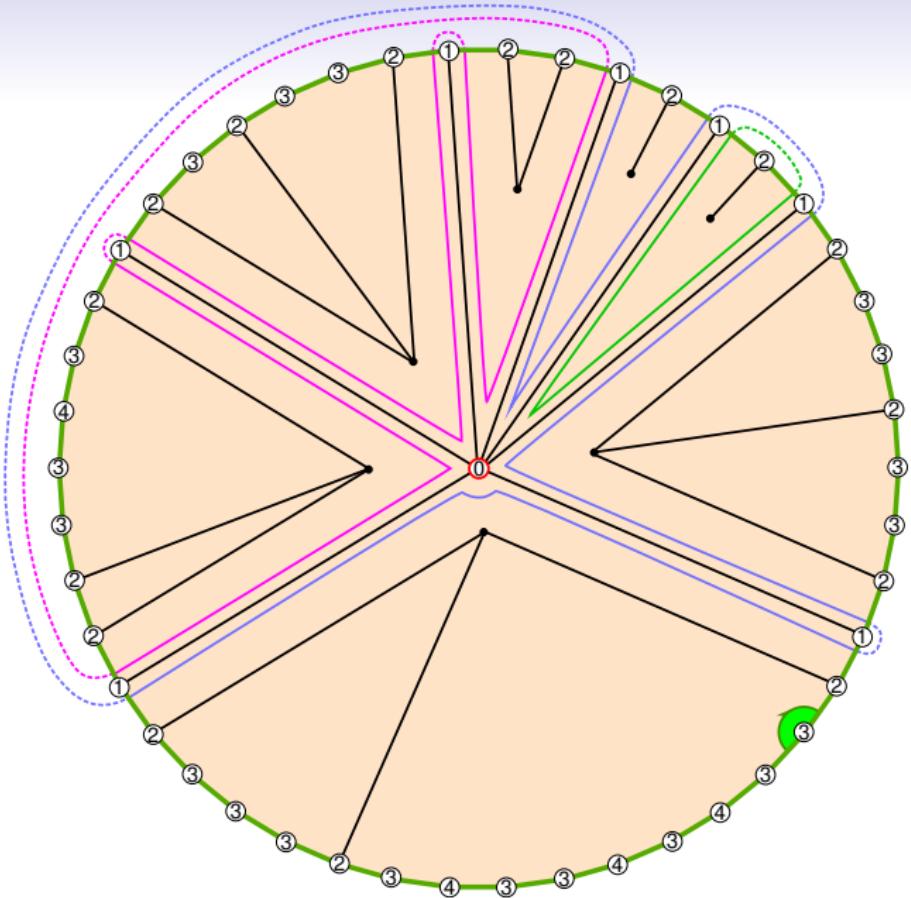
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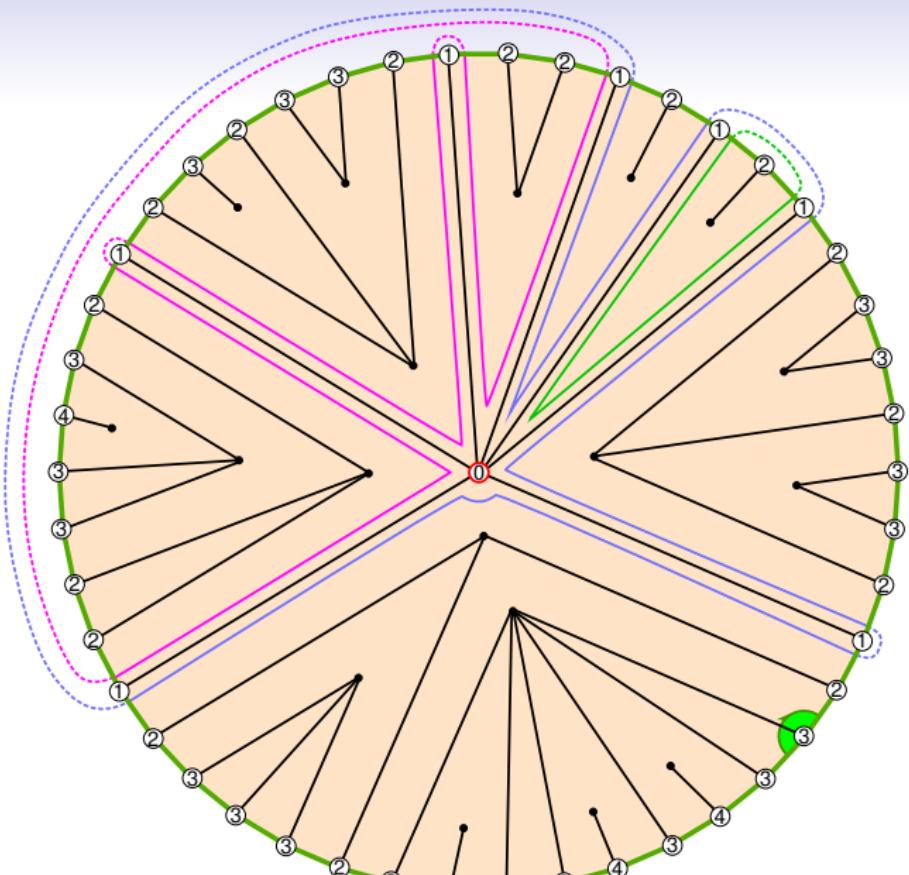
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Labeled unicellular mobiles

Definition (Labeled unicellular mobile)

A **labeled unicellular mobile** is a pair $(\textcolor{brown}{u}, \mathfrak{l})$ such that

- $\textcolor{brown}{u}$ is a one-face map with vertex set $V_\bullet(\textcolor{brown}{u}) \sqcup V_\circ(\textcolor{brown}{u})$ and only edges linking vertices from $V_\bullet(\textcolor{brown}{u})$ to vertices from $V_\circ(\textcolor{brown}{u})$;
- $\mathfrak{l} : V_\circ(\textcolor{brown}{u}) \rightarrow \mathbb{N}$ is a function with minimum 1;
- the root vertex belongs to $V_\circ(\textcolor{brown}{u})$.

Labeled unicellular mobiles

Definition (Labeled unicellular mobile)

A **labeled unicellular mobile** is a pair (u, l) such that

- u is a one-face map with vertex set $V_\bullet(u) \sqcup V_o(u)$ and only edges linking vertices from $V_\bullet(u)$ to vertices from $V_o(u)$;
- $l : V_o(u) \rightarrow \mathbb{N}$ is a function with minimum 1;
- the root vertex belongs to $V_o(u)$.

Definition (Well-labeled unicellular mobile **in the orientable case**)

The mobile (u, l) is **well labeled** if, for every white corner \mathcal{C} , the label of the first subsequent corner is $\geq l(\mathcal{C}) - 1$.

Labeled unicellular mobiles

Definition (Labeled unicellular mobile)

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Definition (Well-labeled unicellular mobile **in the orientable case**)

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Labeled unicellular mobiles

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Orientable case
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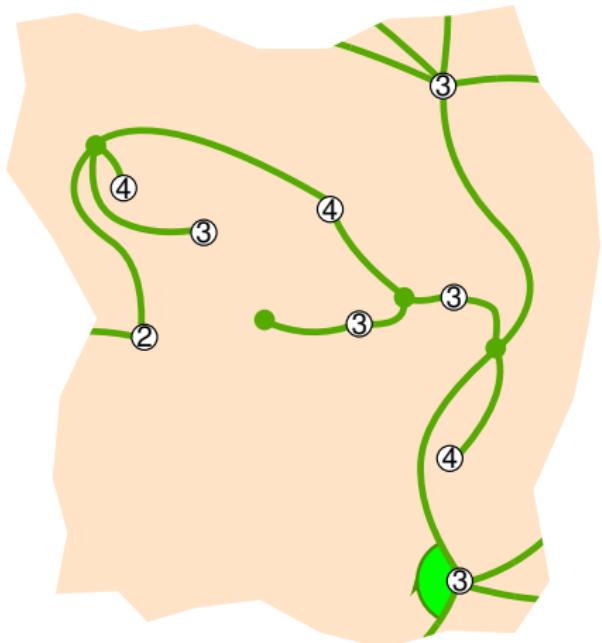
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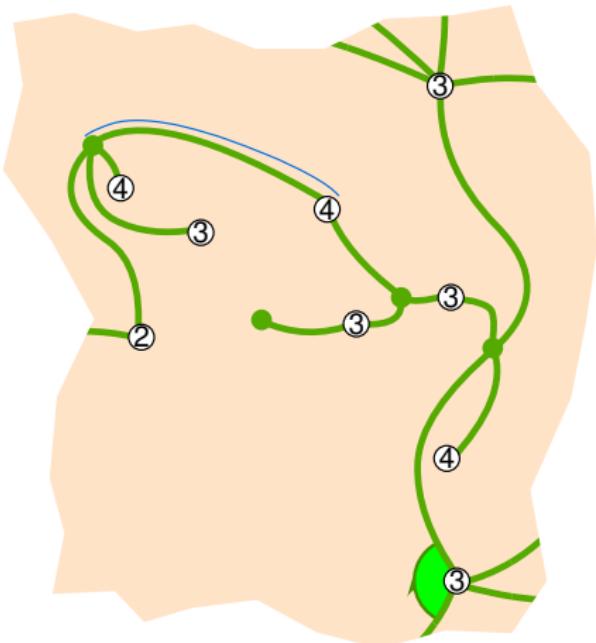
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Coherent orientation of the corners

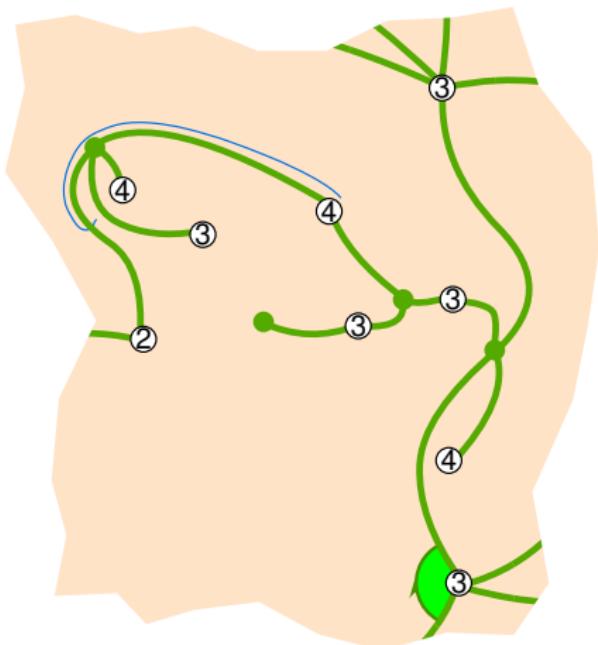


Coherent orientation of the corners



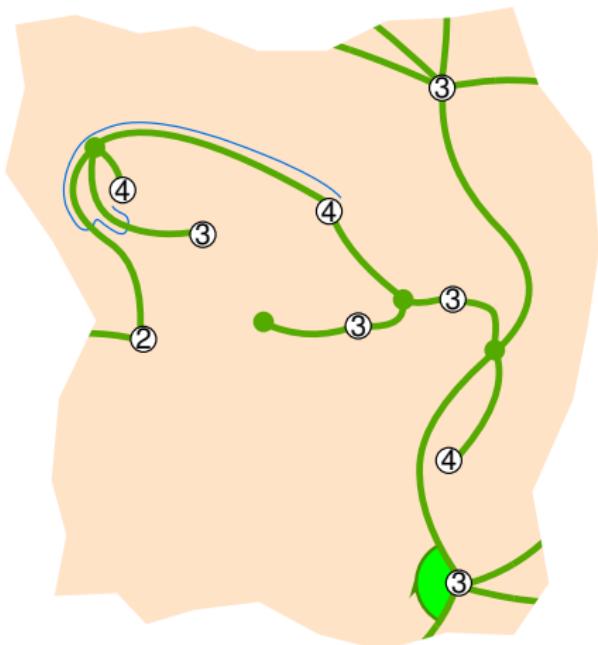
- Start from a white corner \circ , arbitrarily oriented, and move to the next green corner.

Coherent orientation of the corners



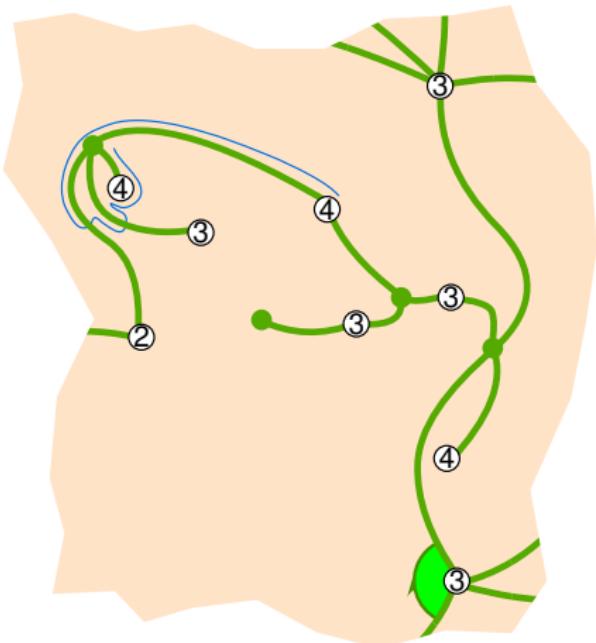
- Start from a white corner \mathcal{C} , arbitrarily oriented, and move to the next green corner.
- Look at the next white corner:
 - if its label is $< l(\mathcal{C})$, cross the green edge;

Coherent orientation of the corners



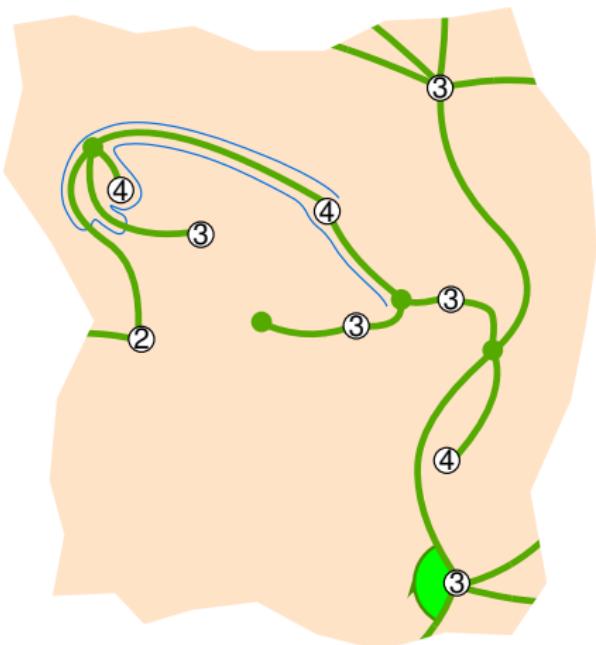
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Coherent orientation of the corners



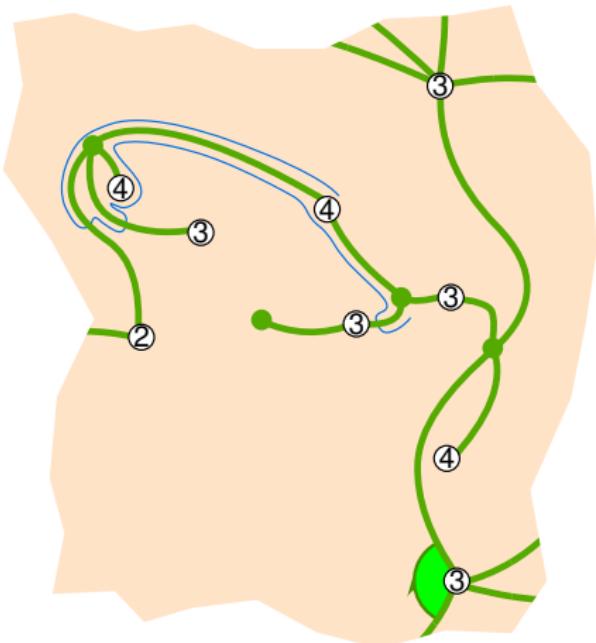
- Start from a white corner \mathcal{C} , arbitrarily oriented, and move to the next green corner.
- Look at the next white corner:
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Coherent orientation of the corners



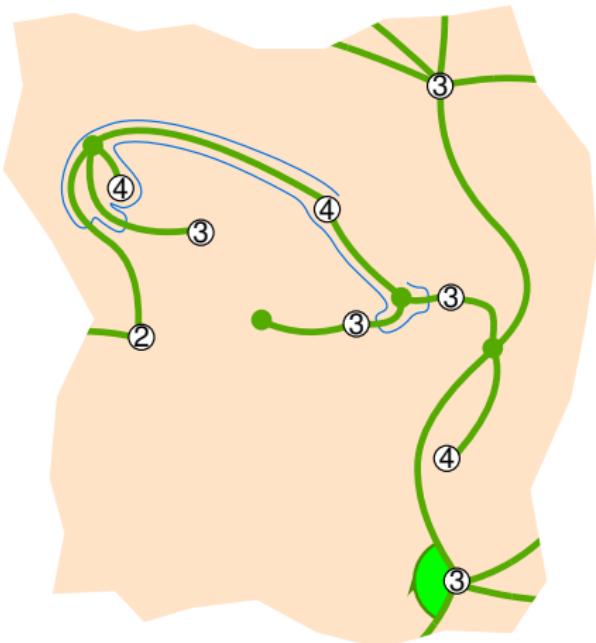
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Coherent orientation of the corners



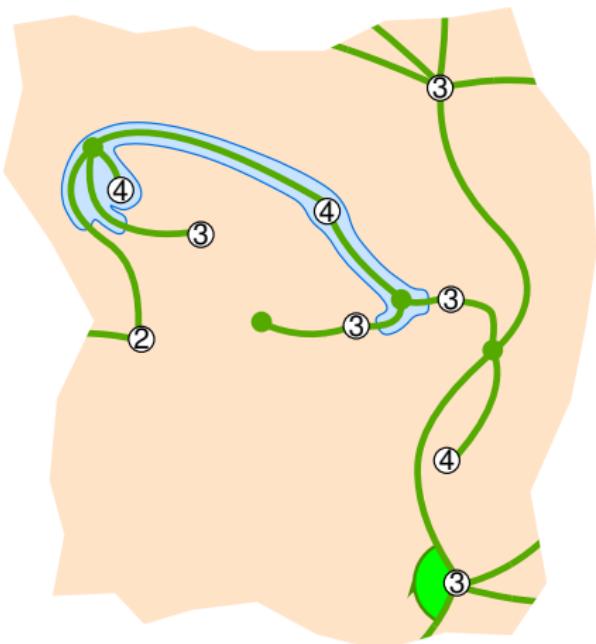
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Coherent orientation of the corners



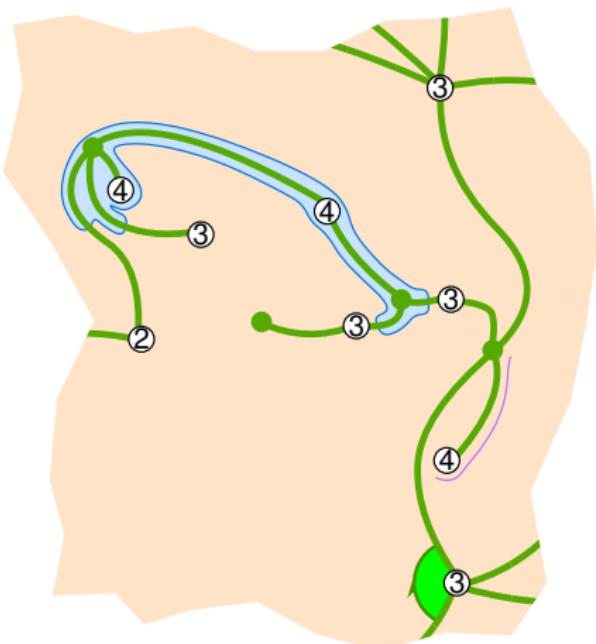
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Coherent orientation of the corners



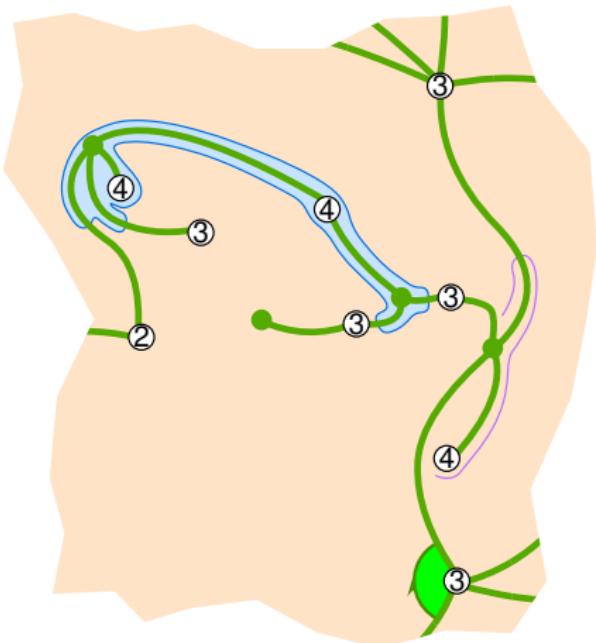
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- Get a **corner cycle**.

Coherent orientation of the corners



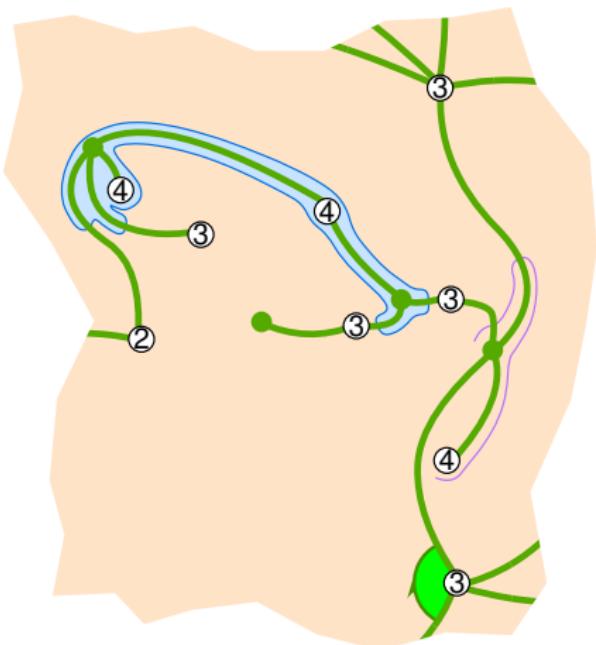
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Coherent orientation of the corners



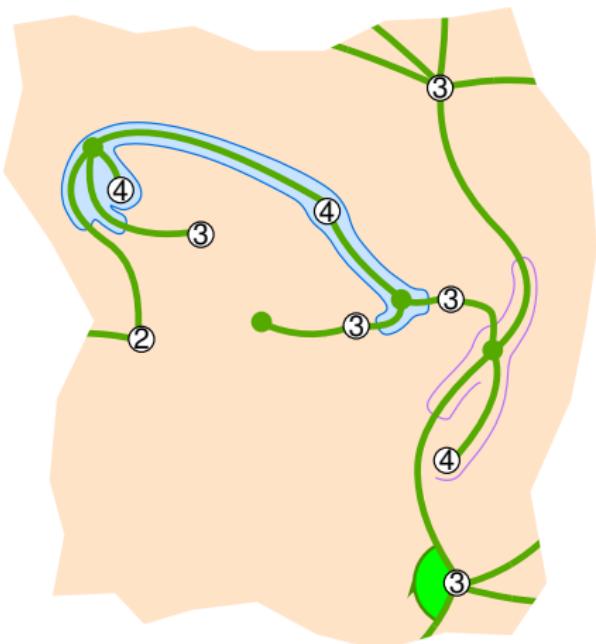
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Coherent orientation of the corners



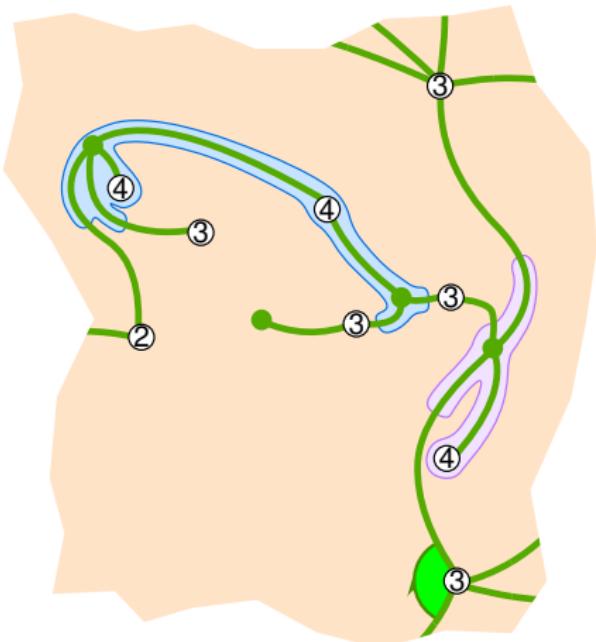
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Coherent orientation of the corners



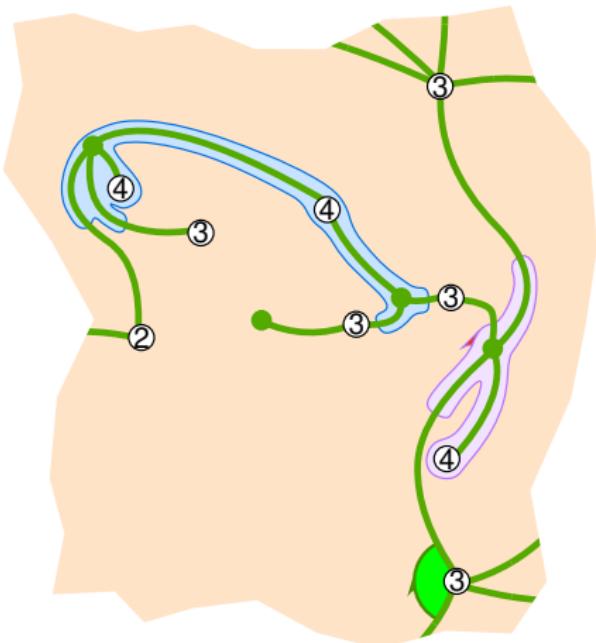
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Coherent orientation of the corners



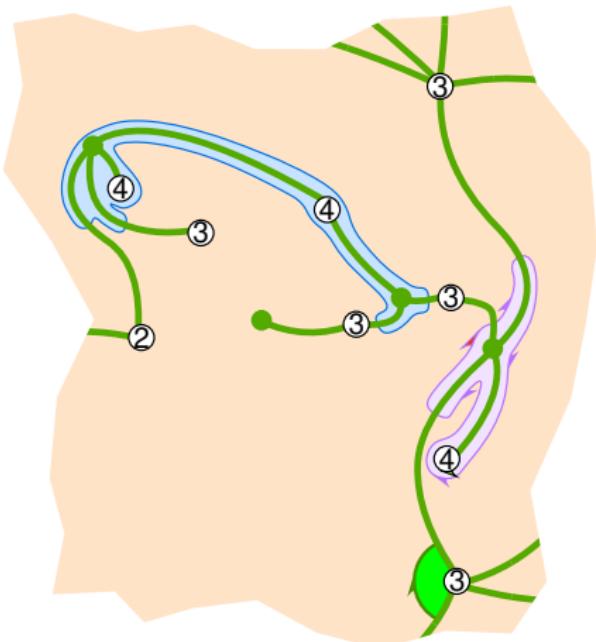
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Coherent orientation of the corners



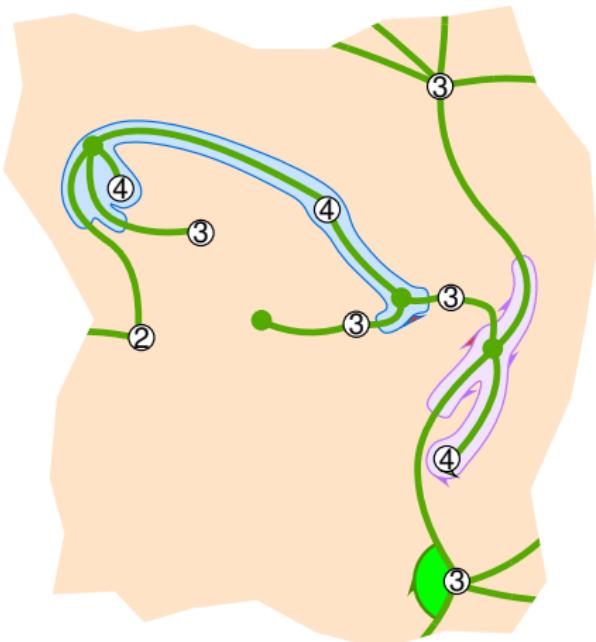
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- Get a **corner cycle**.
- Consider the first subsequent corner of the root in the cycle.

Coherent orientation of the corners



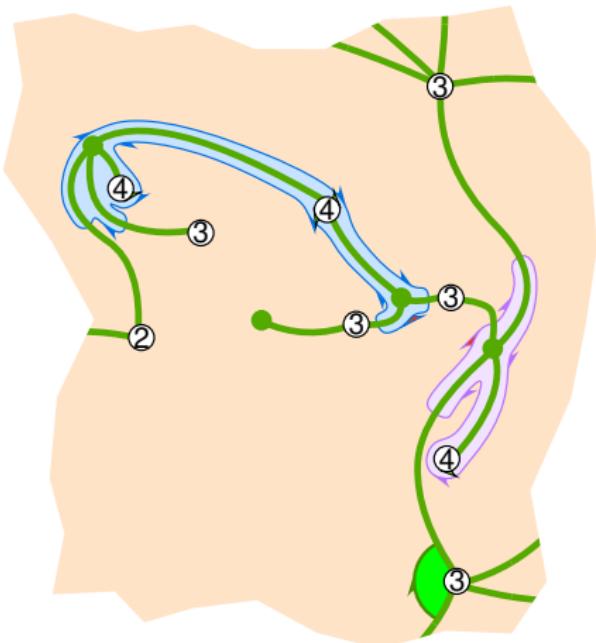
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- Get a **corner cycle**.
- Consider the first subsequent corner of the root in the cycle.
- Orient the cycle and \mathcal{C} .

Coherent orientation of the corners



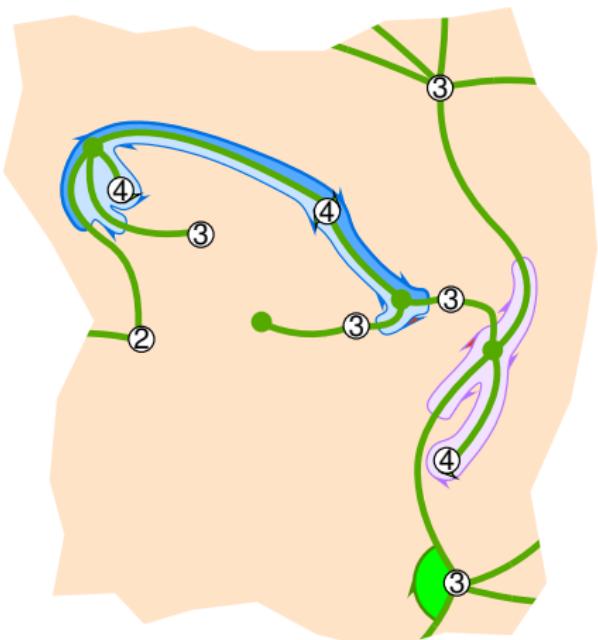
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- Get a **corner cycle**.
- Consider the first subsequent corner of the root in the cycle.
- Orient the cycle and \mathcal{C} .

Coherent orientation of the corners



- Start from a white corner \mathcal{C} , arbitrarily oriented, and move to the next green corner.
- Look at the next white corner:
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 - if its label is $\geq l(\mathcal{C})$, move to it then to the next green corner.
- Get a **corner cycle**.
- Consider the first subsequent corner of the root in the cycle.
- Orient the cycle and \mathcal{C} .

Coherent orientation of the corners



- Start from a white corner \mathcal{C} , arbitrarily oriented, and move to the next green corner.
- Look at the next white corner:
 - if its label is $< l(\mathcal{C})$, cross the green edge;
 - if its label is $\geq l(\mathcal{C})$, move to it then to the next green corner.
- Get a **corner cycle**.
- Consider the first subsequent corner of the root in the cycle.
- Orient the cycle and \mathcal{C} .
- A **corner run**.

Well-labeled unicellular mobiles

Definition (Successor)

Let \mathcal{C} be a white corner with label $l(\mathcal{C}) \geq 2$. In the order given by the coherent orientation of \mathcal{C} , the first subsequent corner with label strictly smaller than $l(\mathcal{C})$ is called the **successor** of \mathcal{C} ; it is denoted by $\text{succ}(\mathcal{C})$.

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Well-labeled unicellular mobiles

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A **well-labeled unicellular mobile** is a labeled unicellular mobile such that, for every white corner \mathcal{C} with label $l(\mathcal{C}) \geq 2$,

$$l(\text{succ}(\mathcal{C})) = l(\mathcal{C}) - 1.$$

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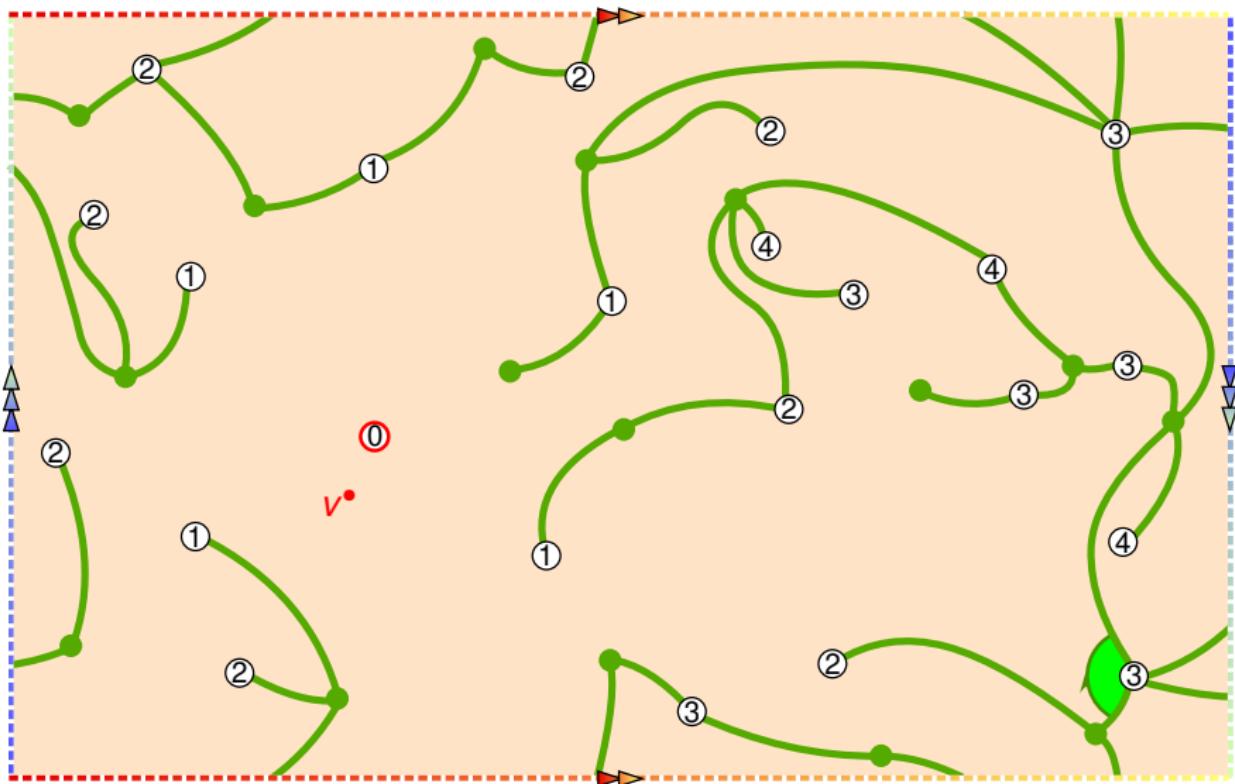
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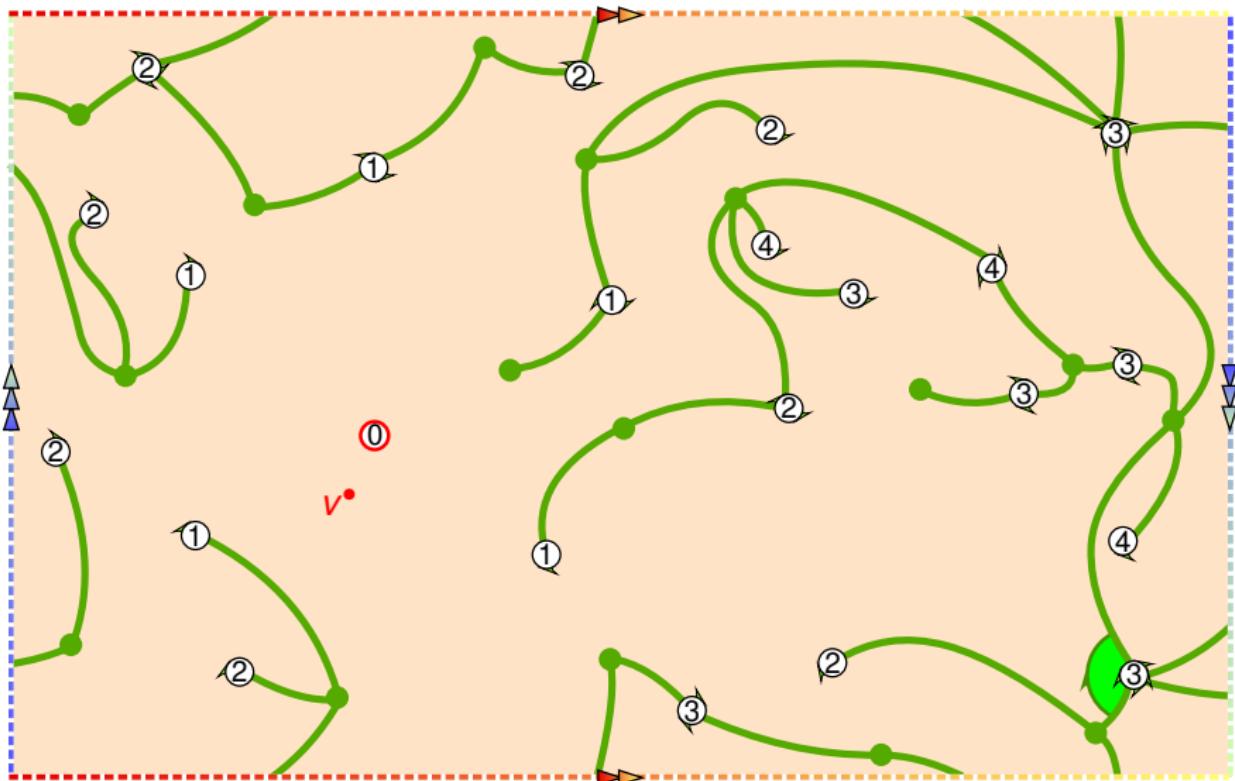
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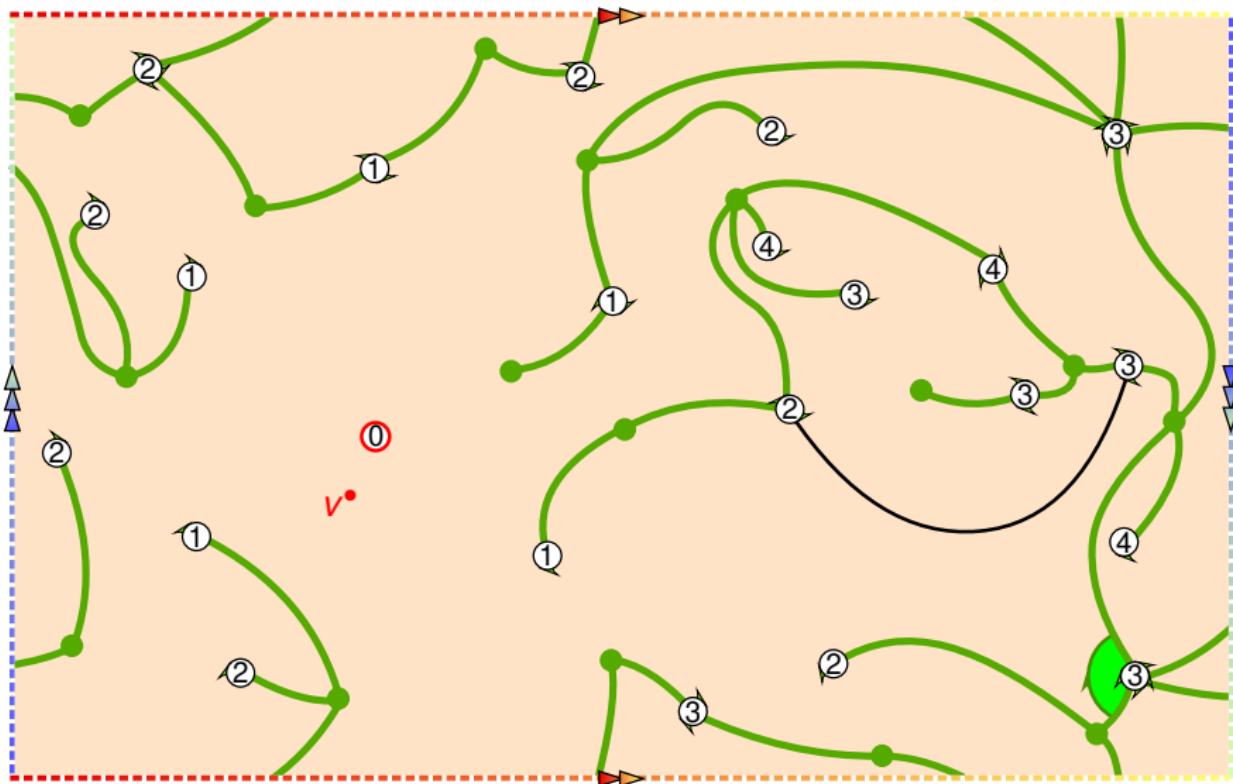
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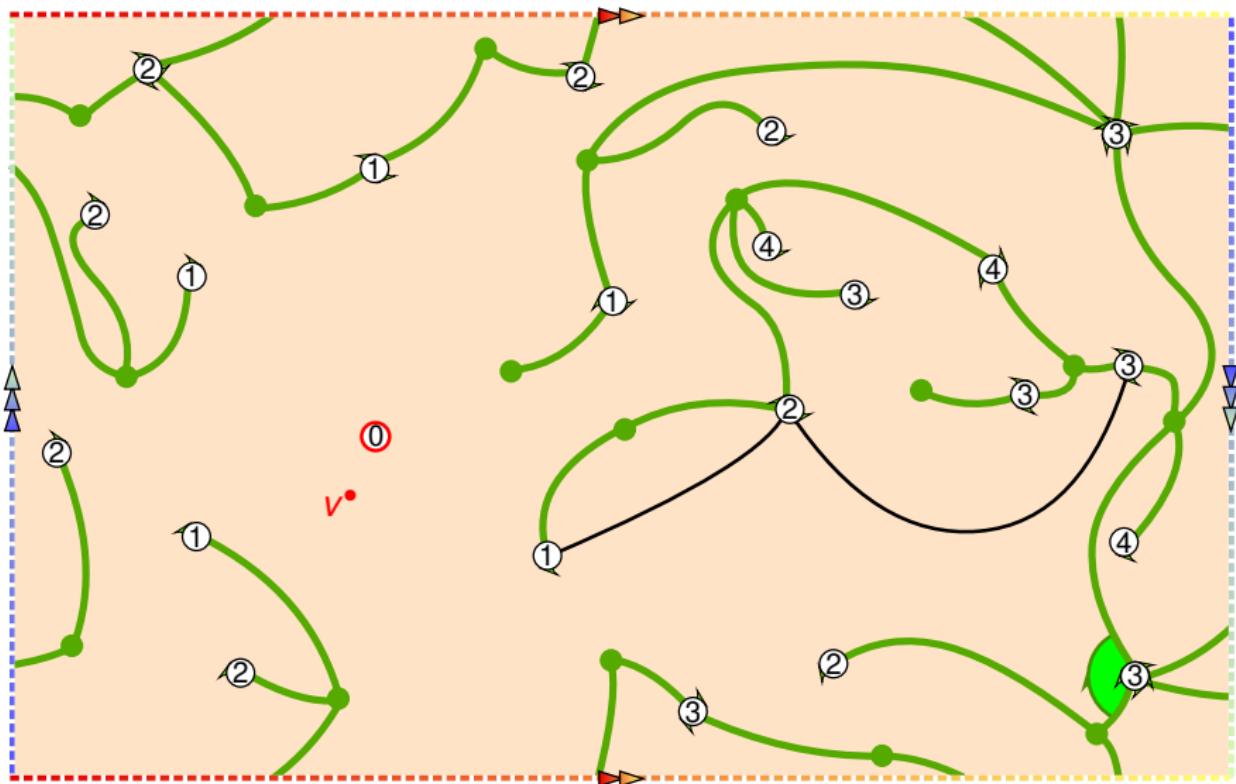
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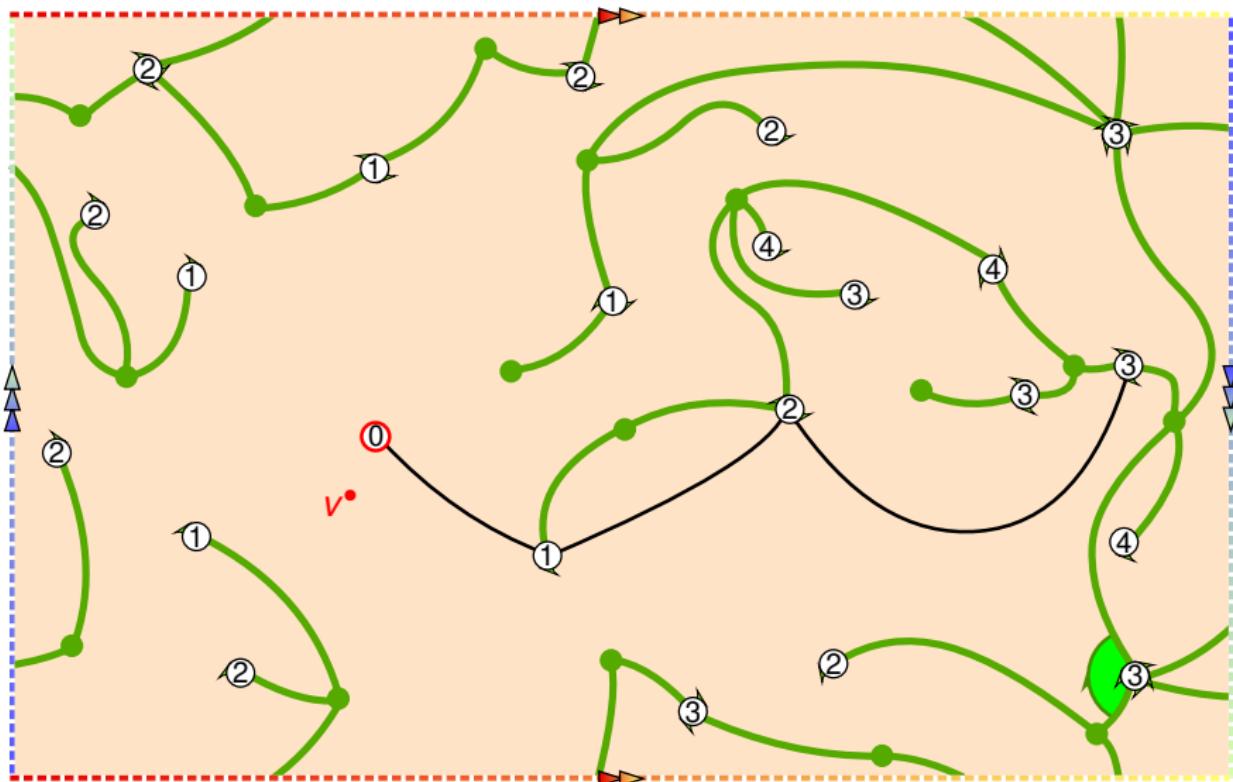
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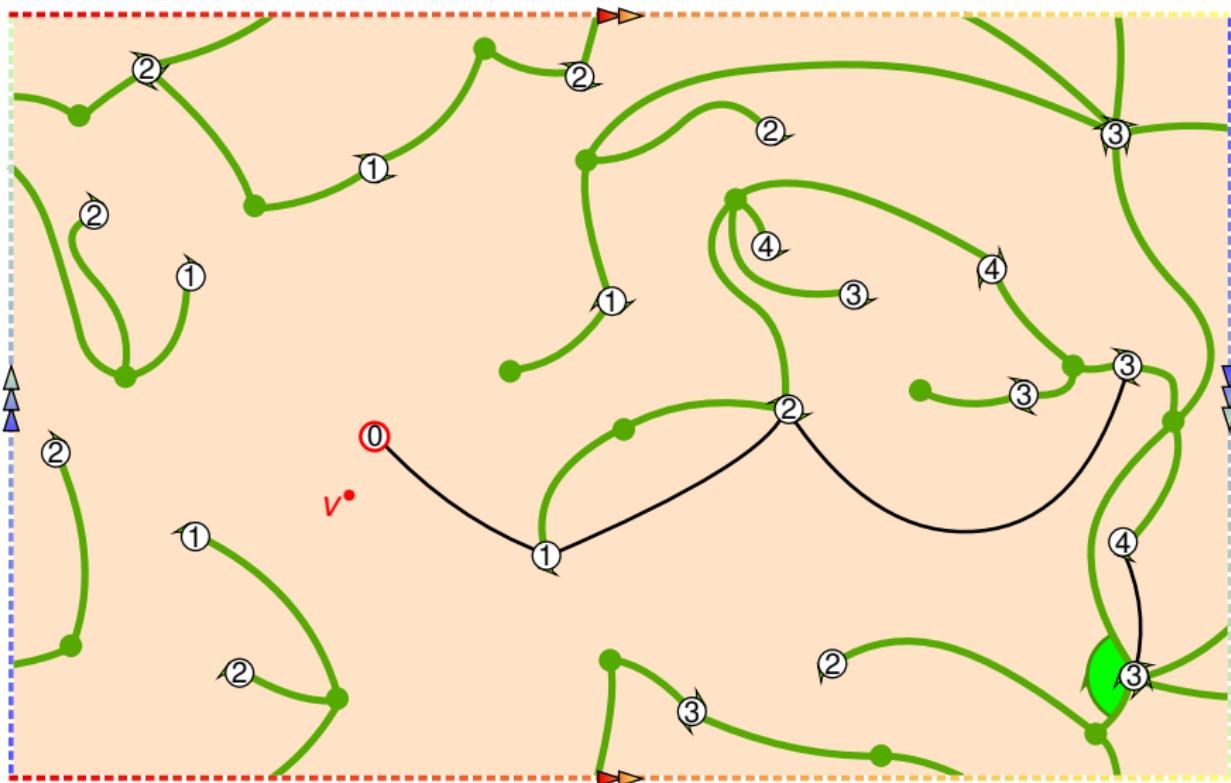
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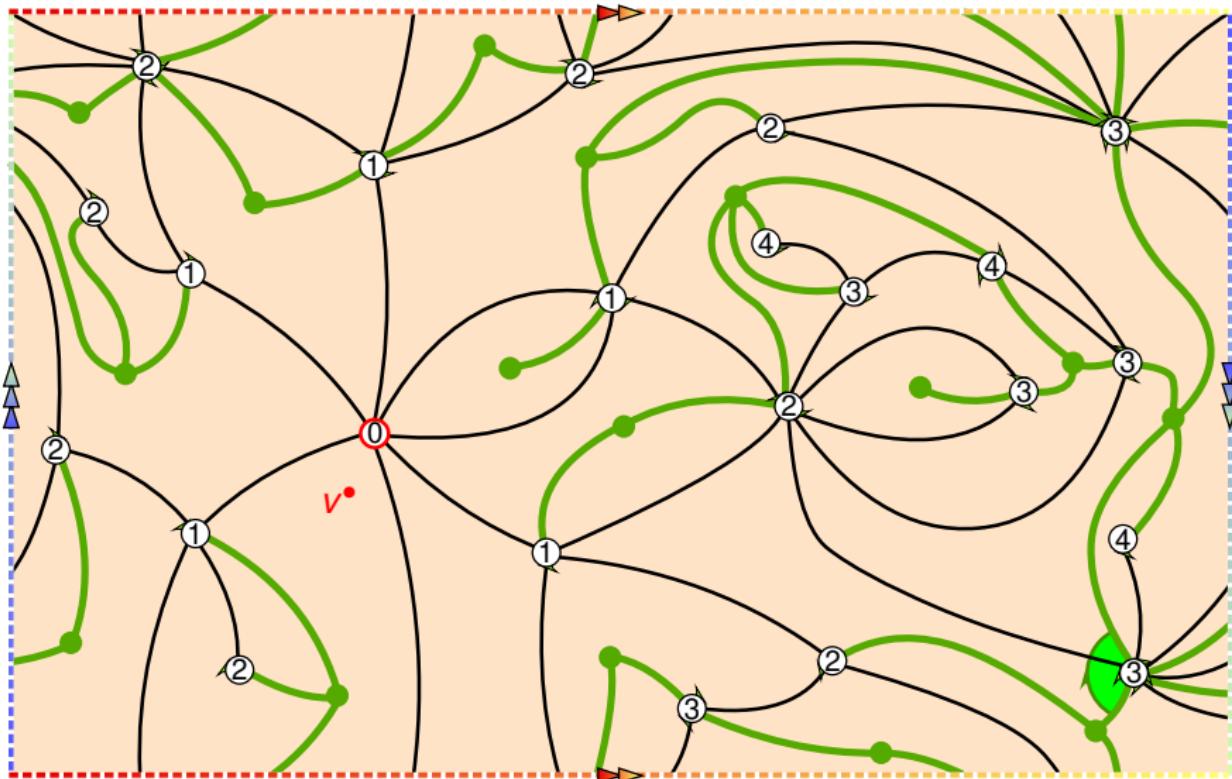
From unicellular mobiles to pointed bipartite maps



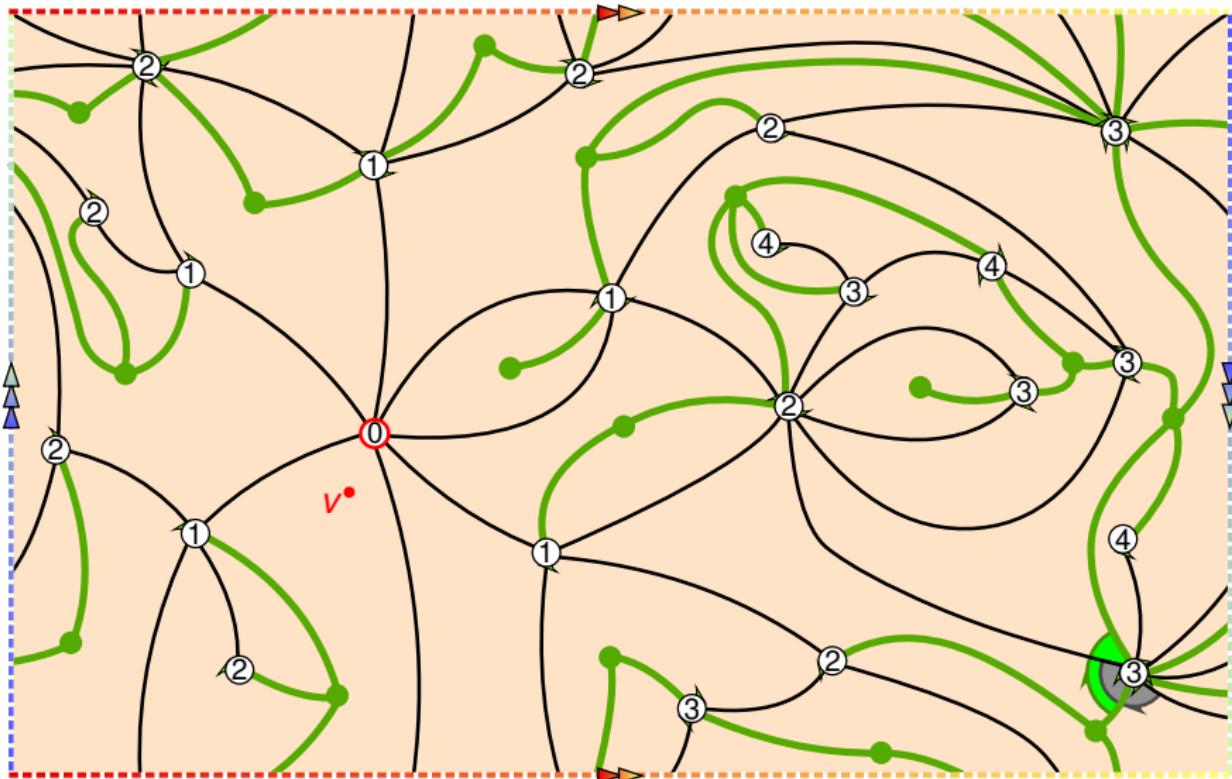
From unicellular mobiles to pointed bipartite maps



From unicellular mobiles to pointed bipartite maps



From unicellular mobiles to pointed bipartite maps



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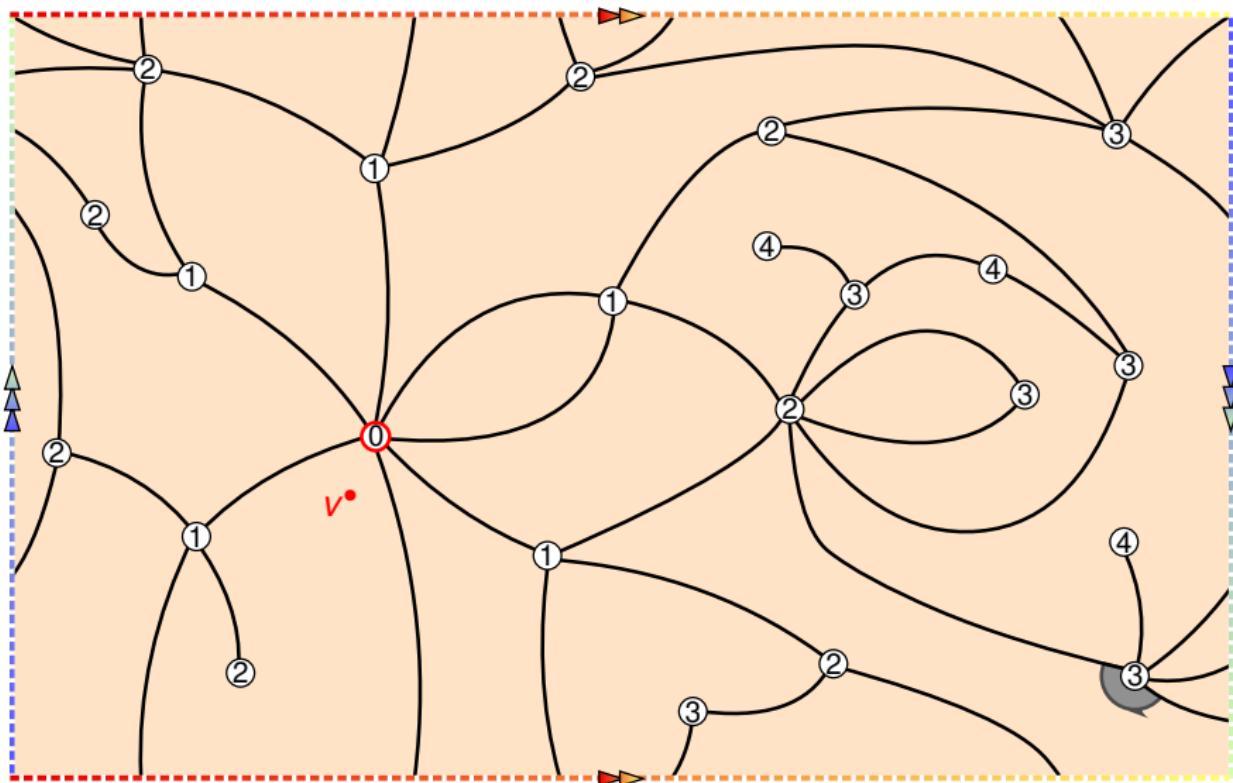
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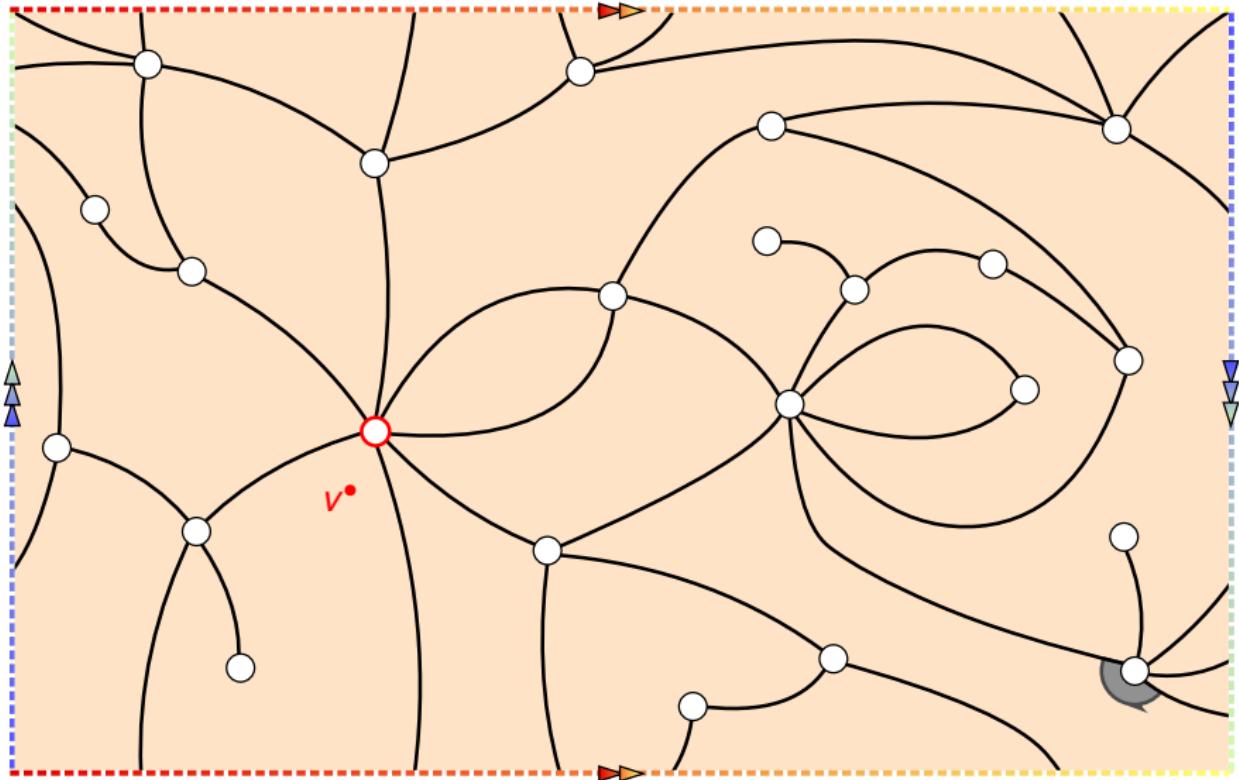
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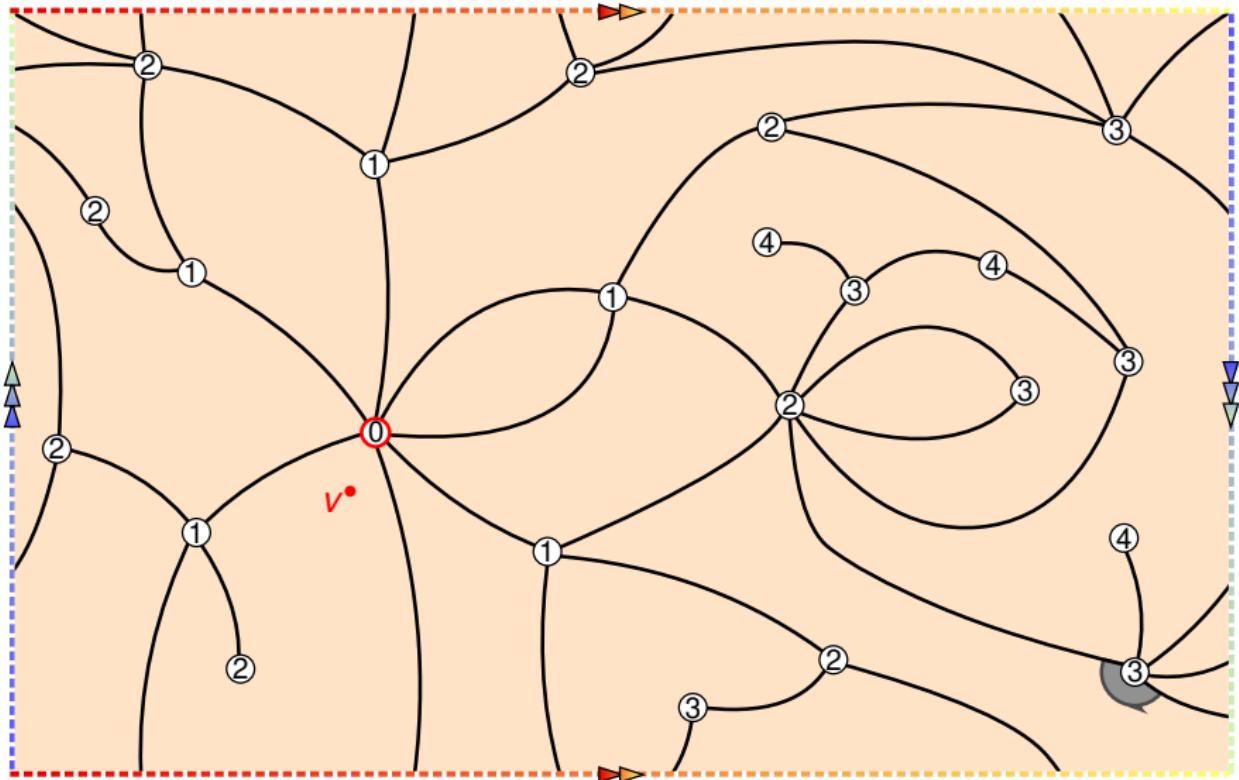
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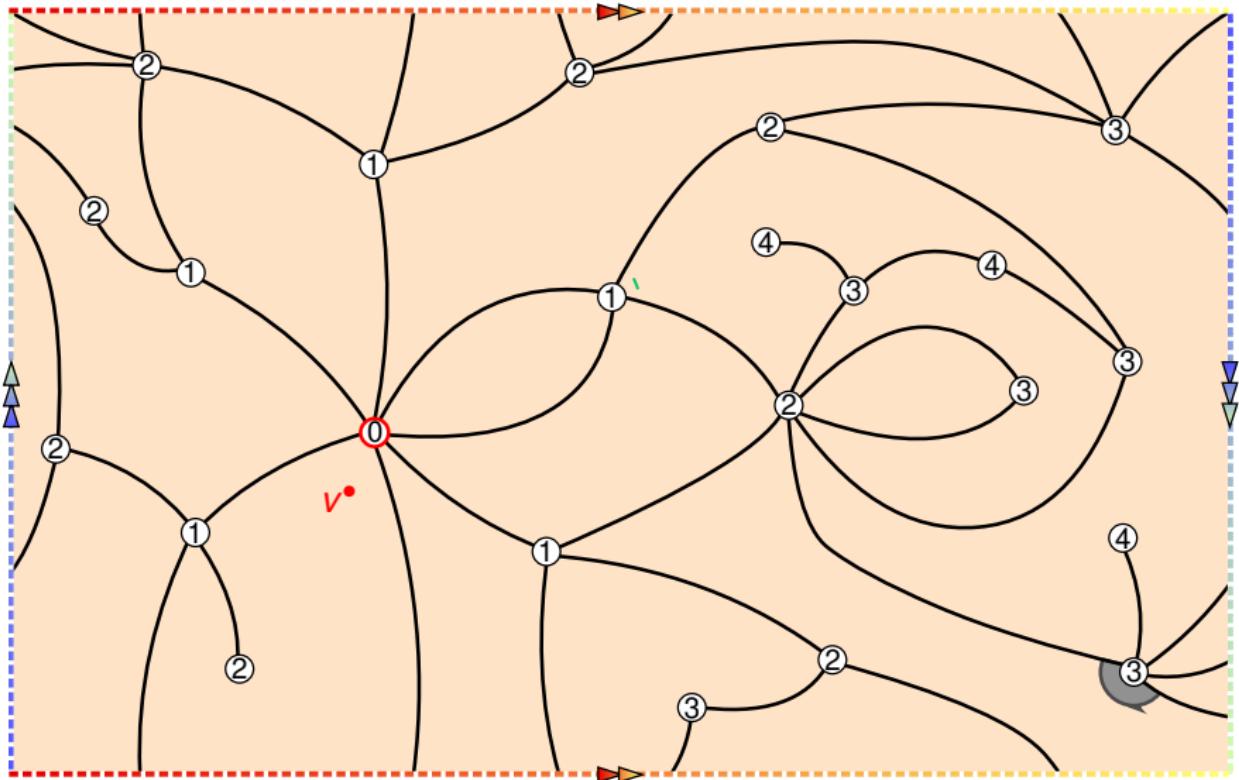
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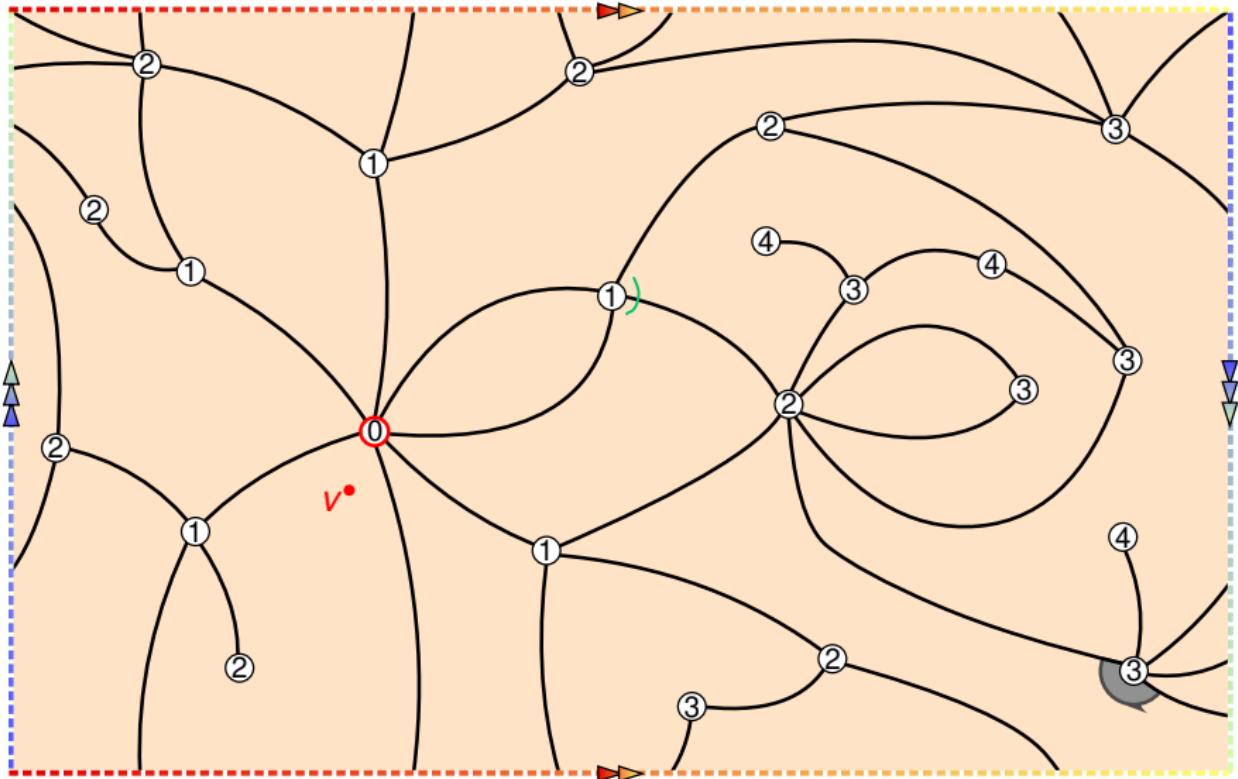
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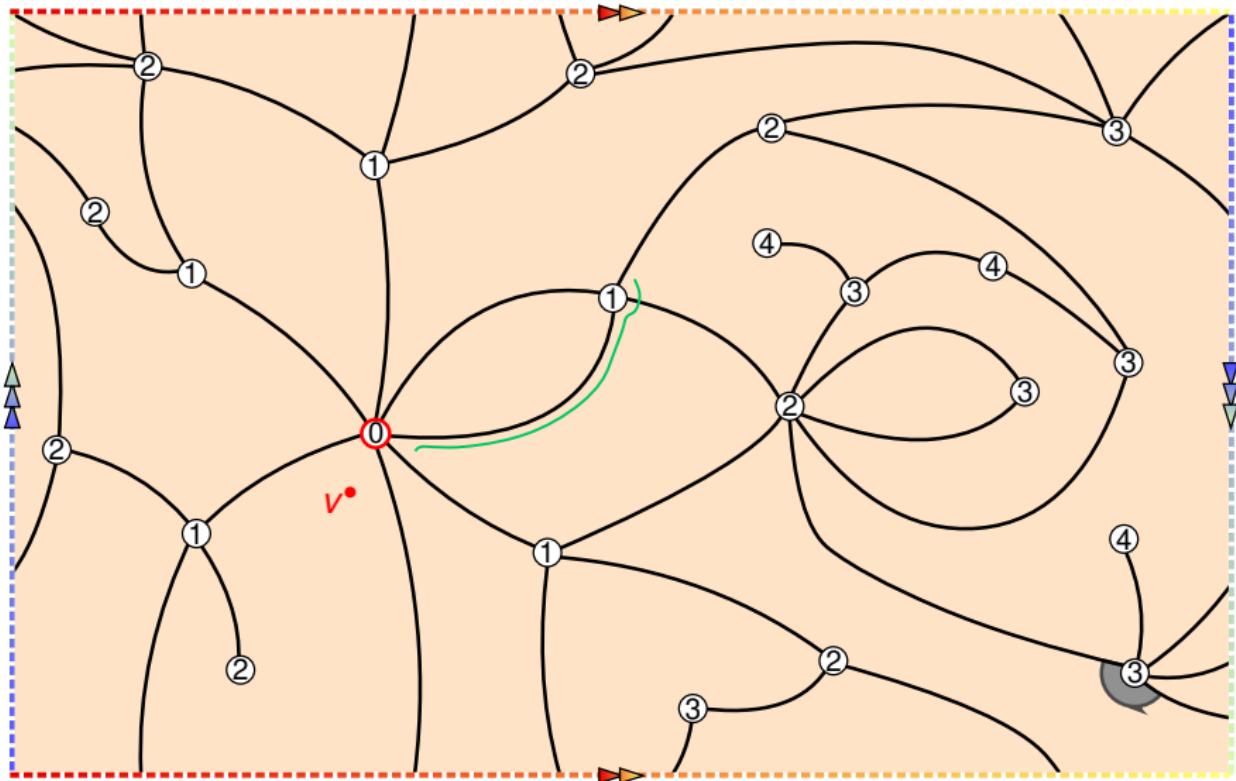
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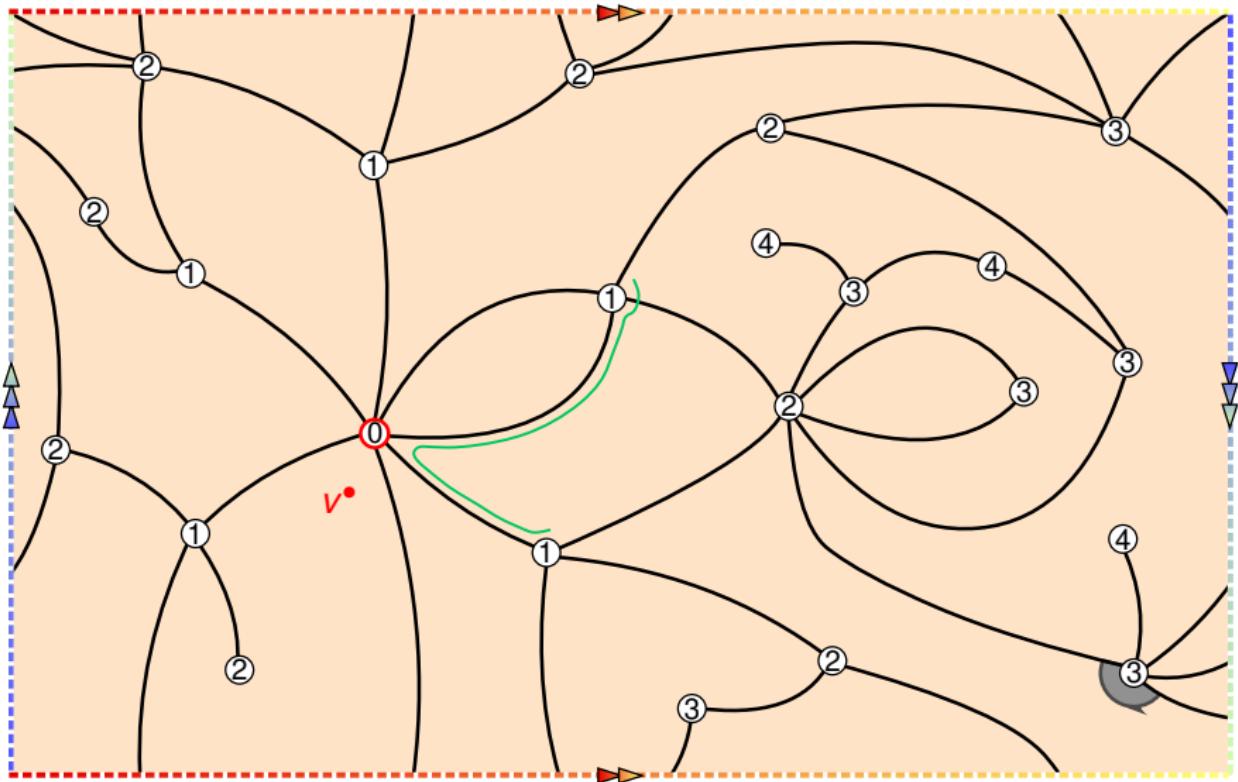
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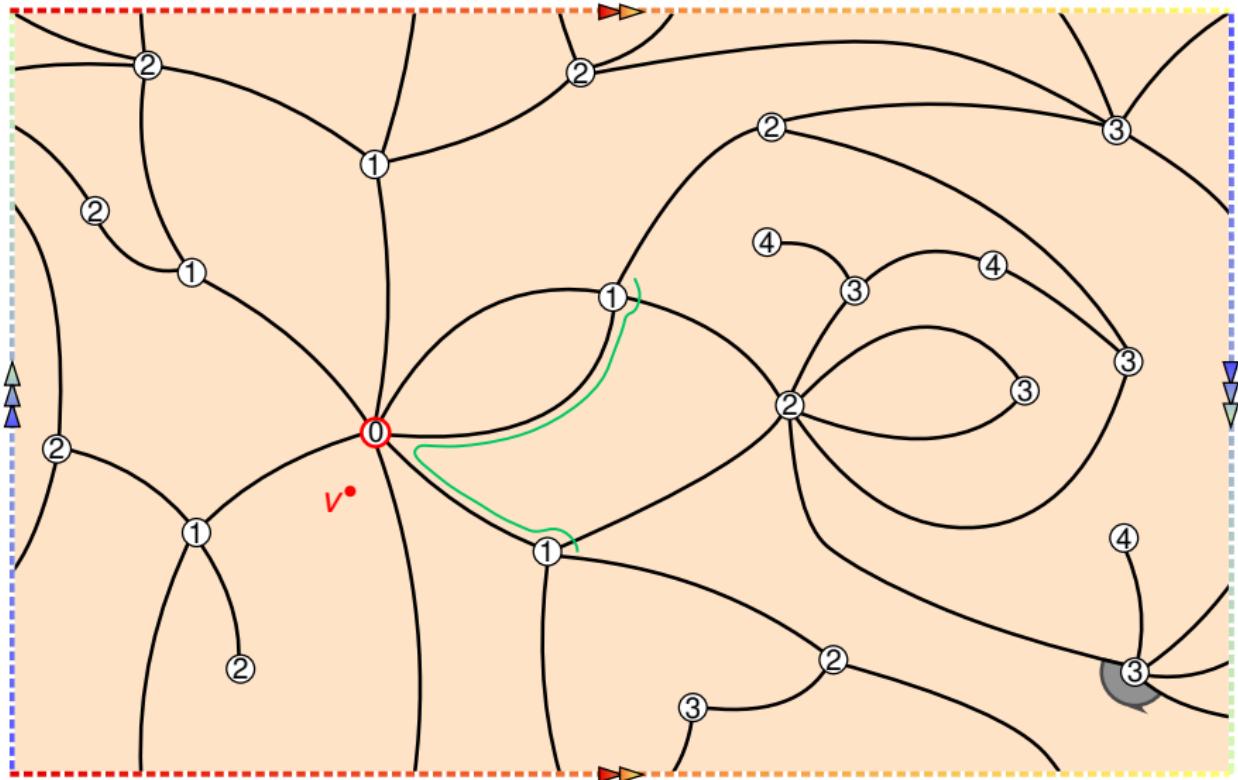
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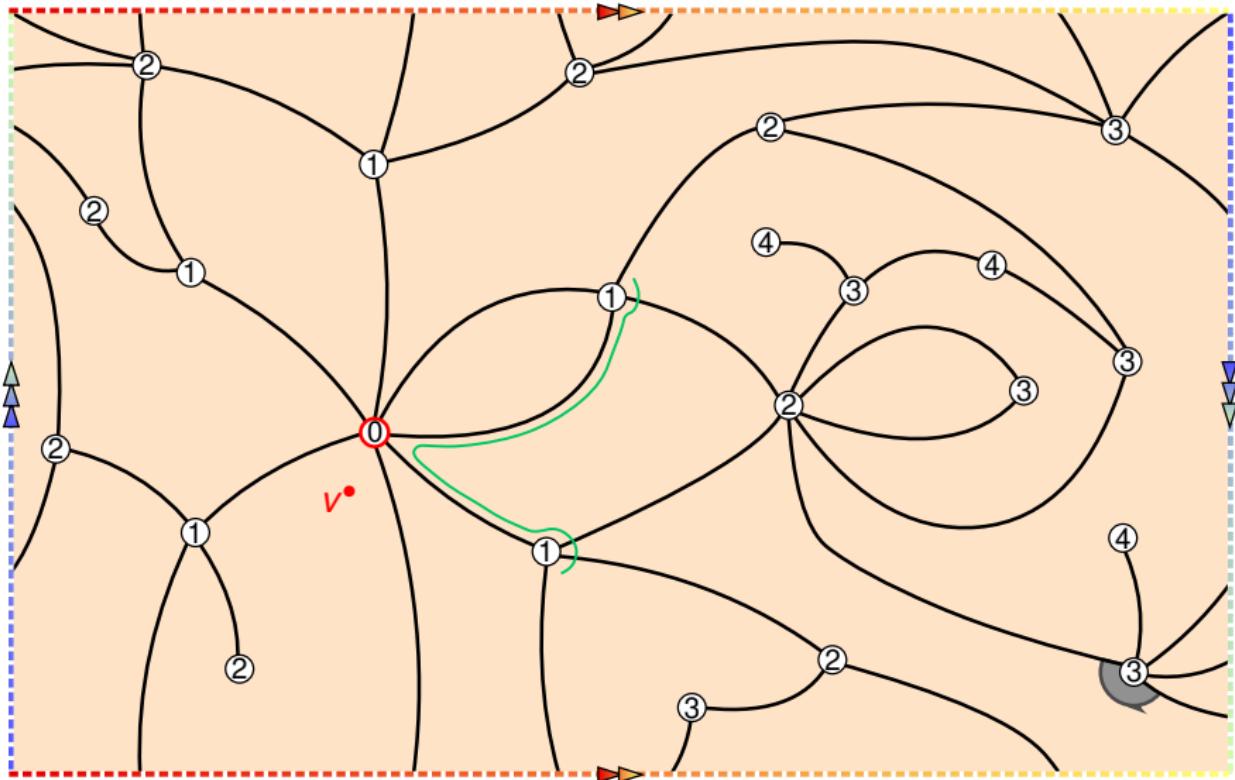
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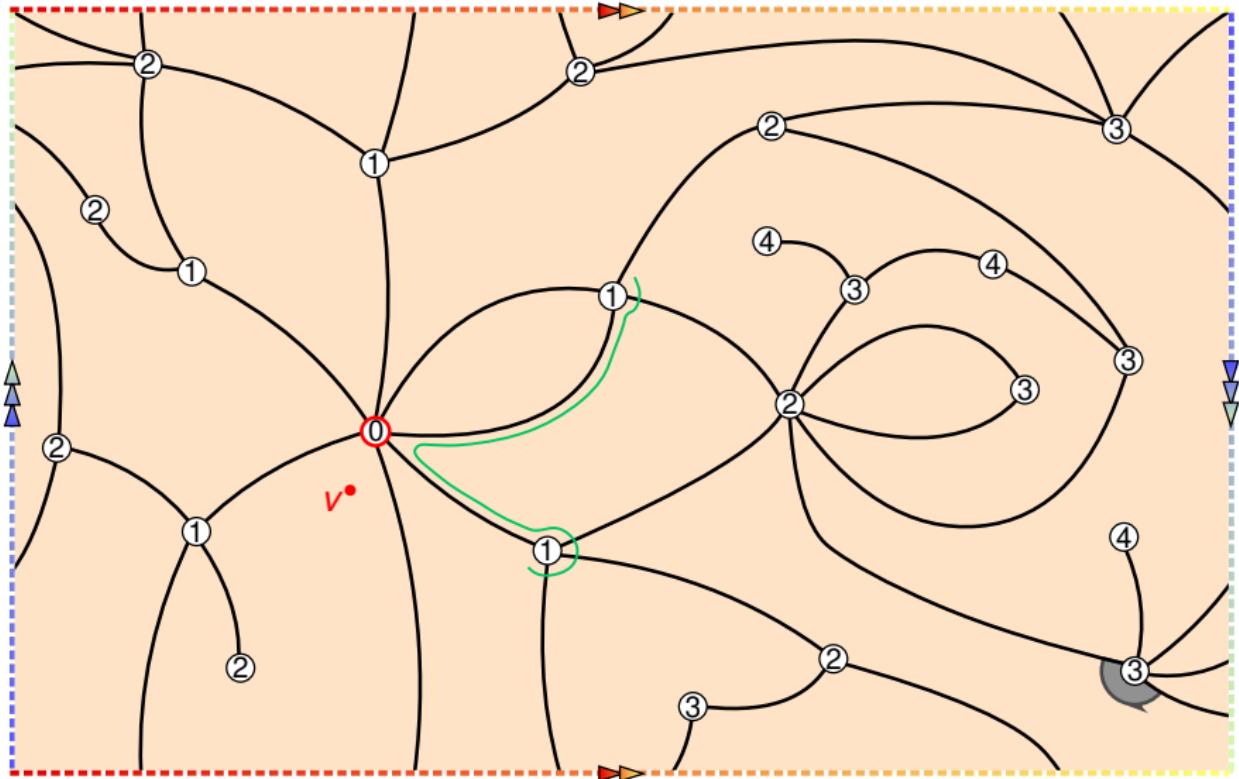
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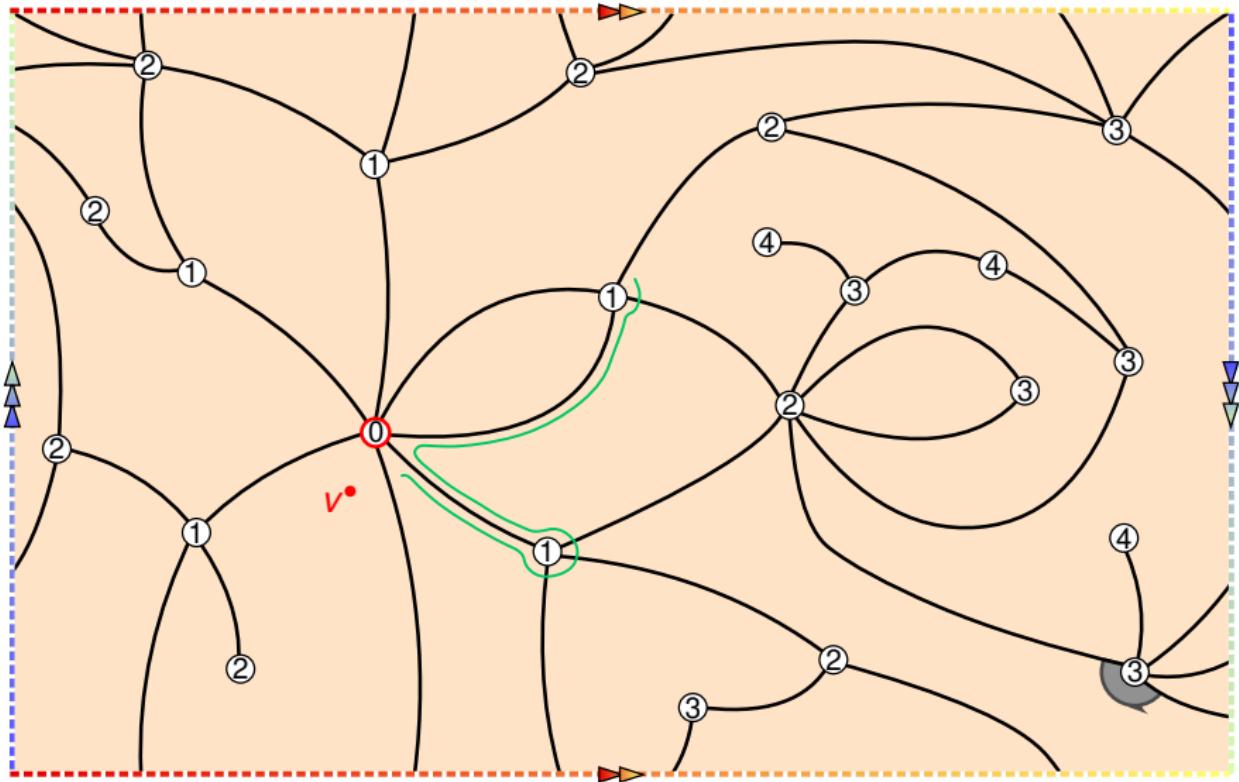
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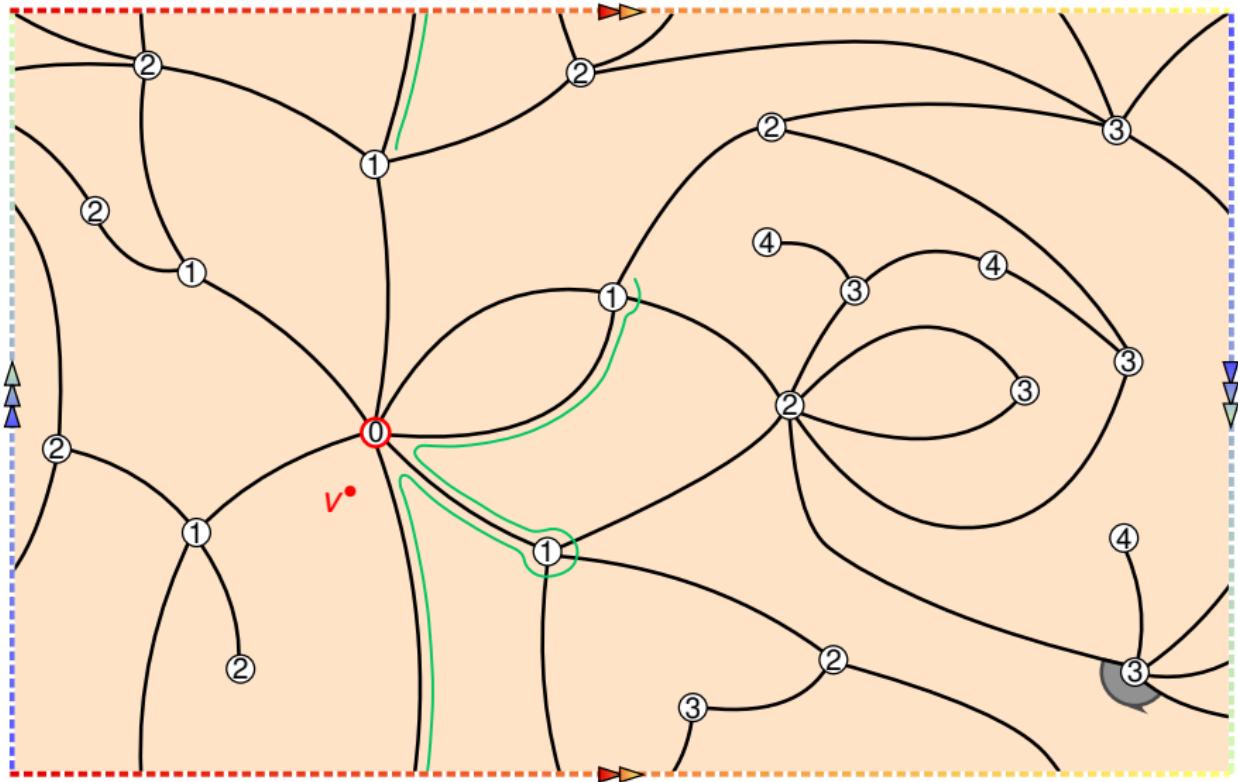
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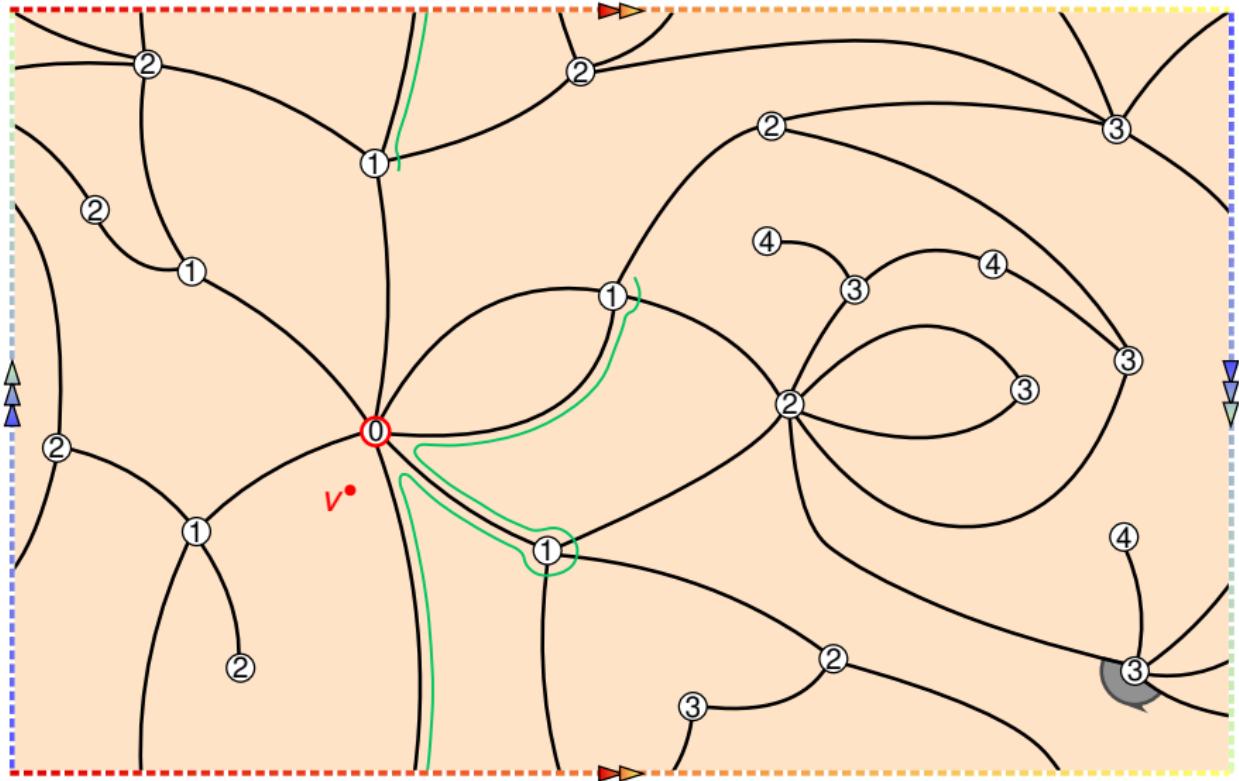
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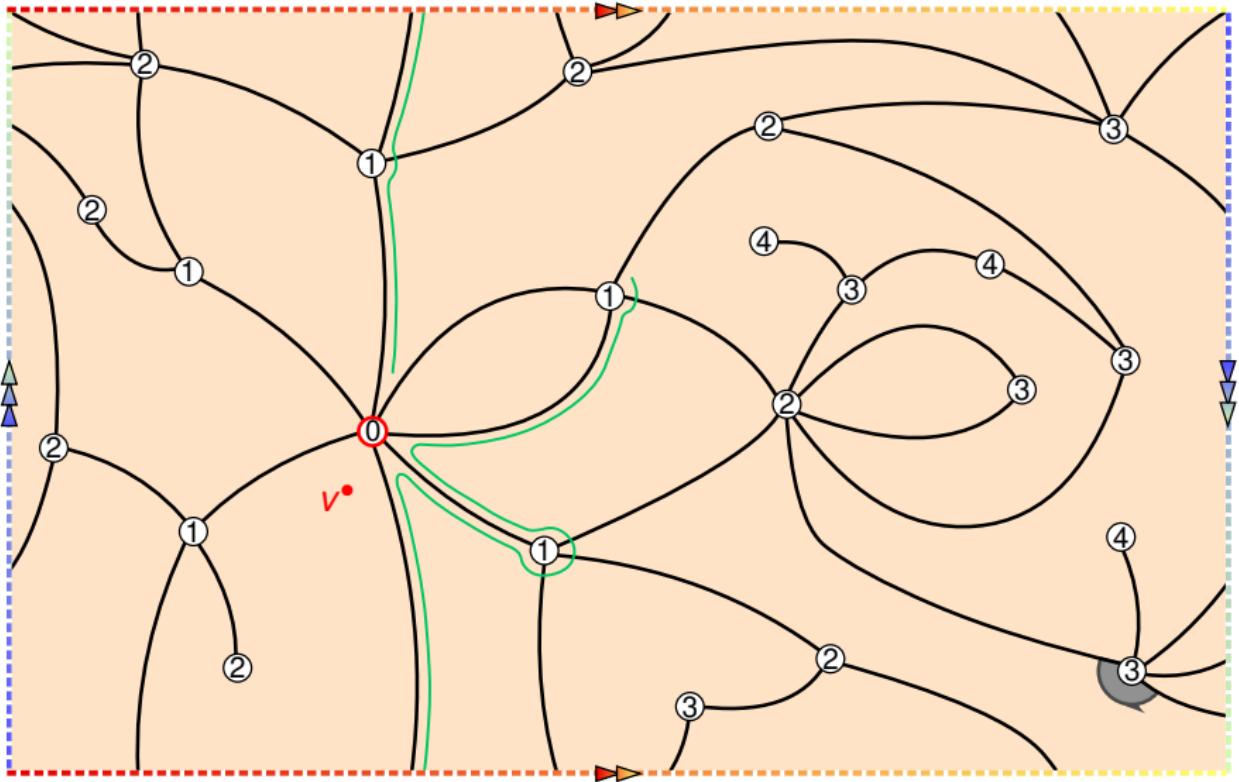
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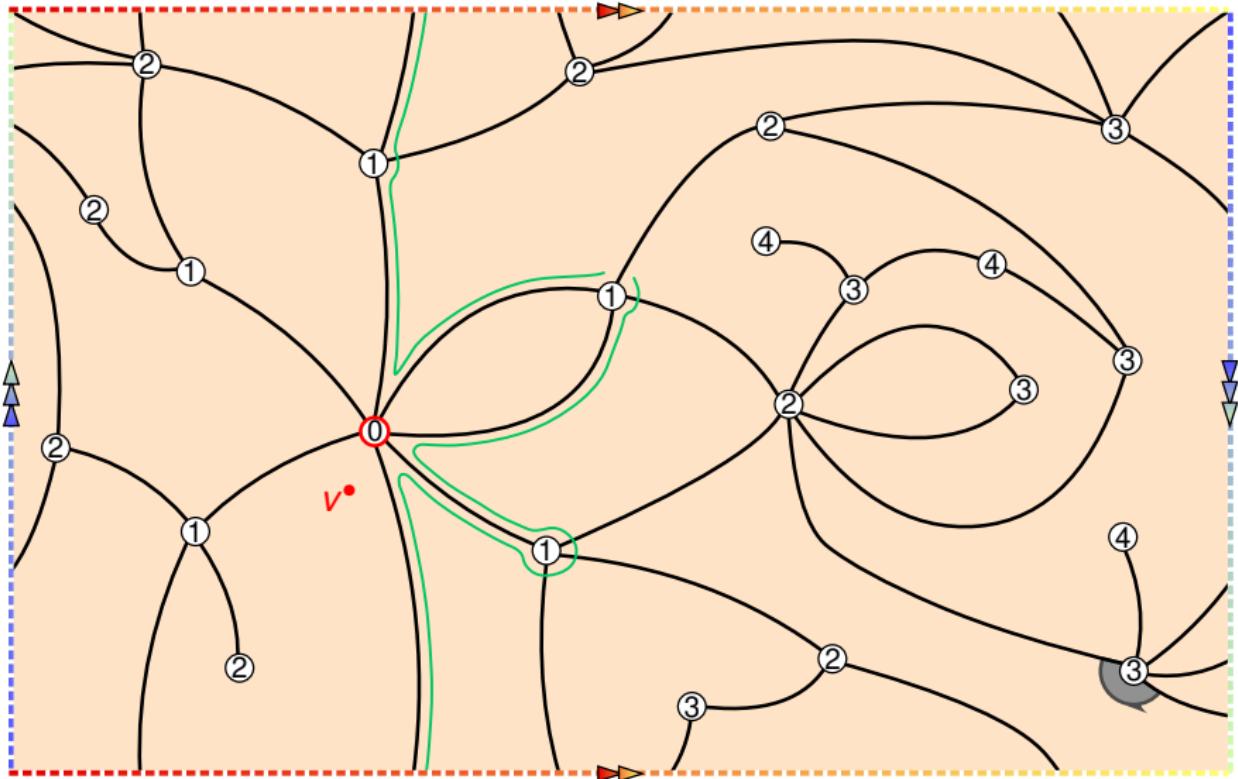
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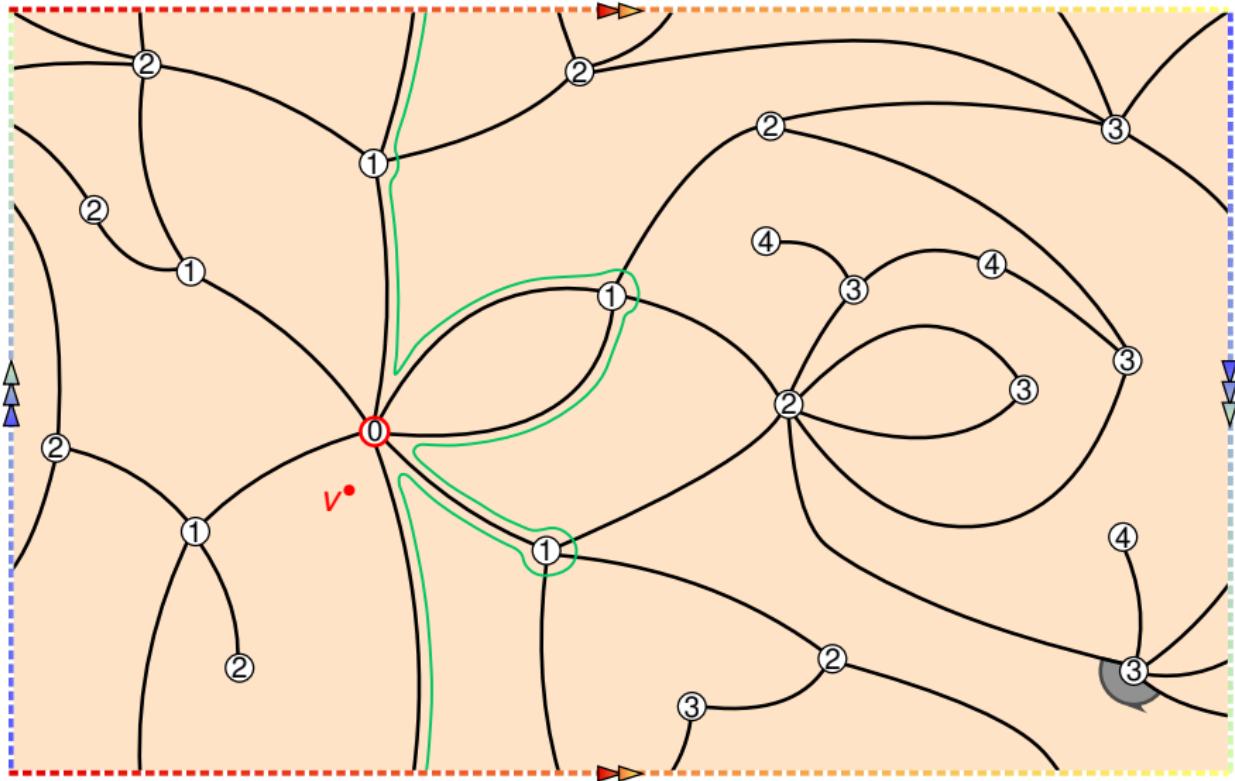
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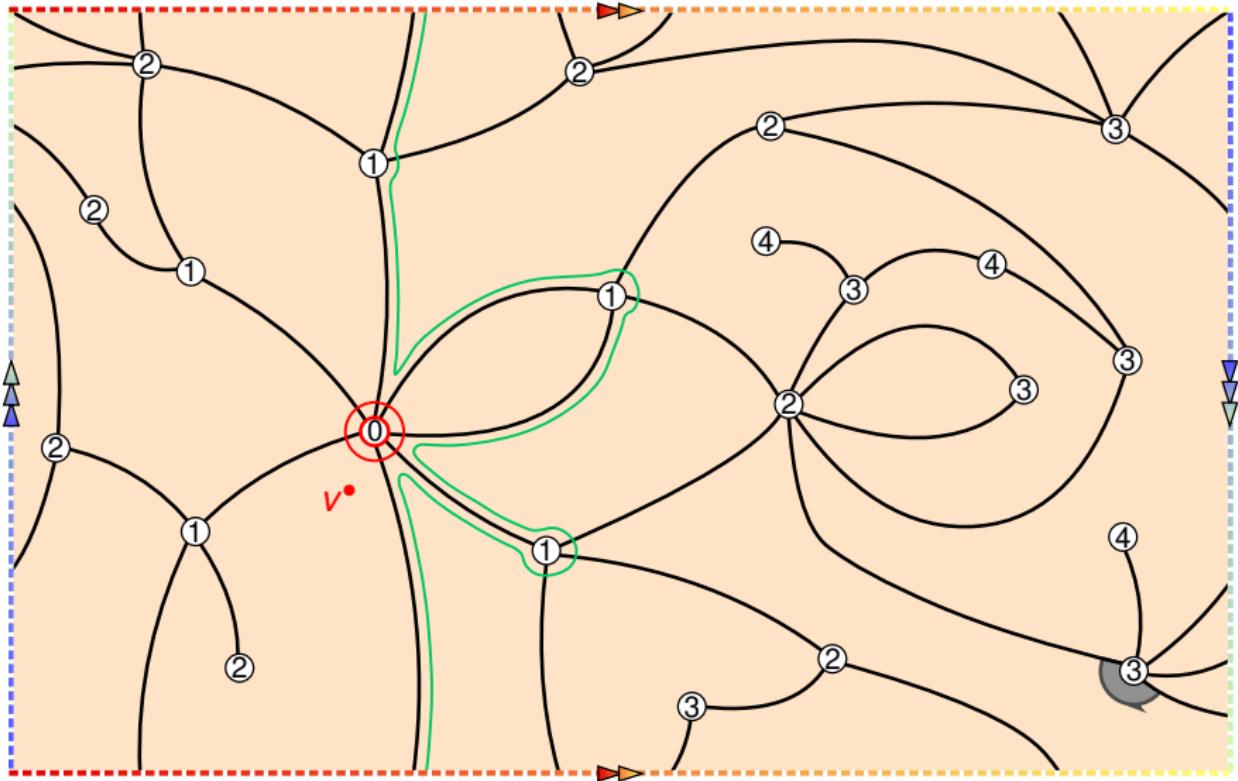
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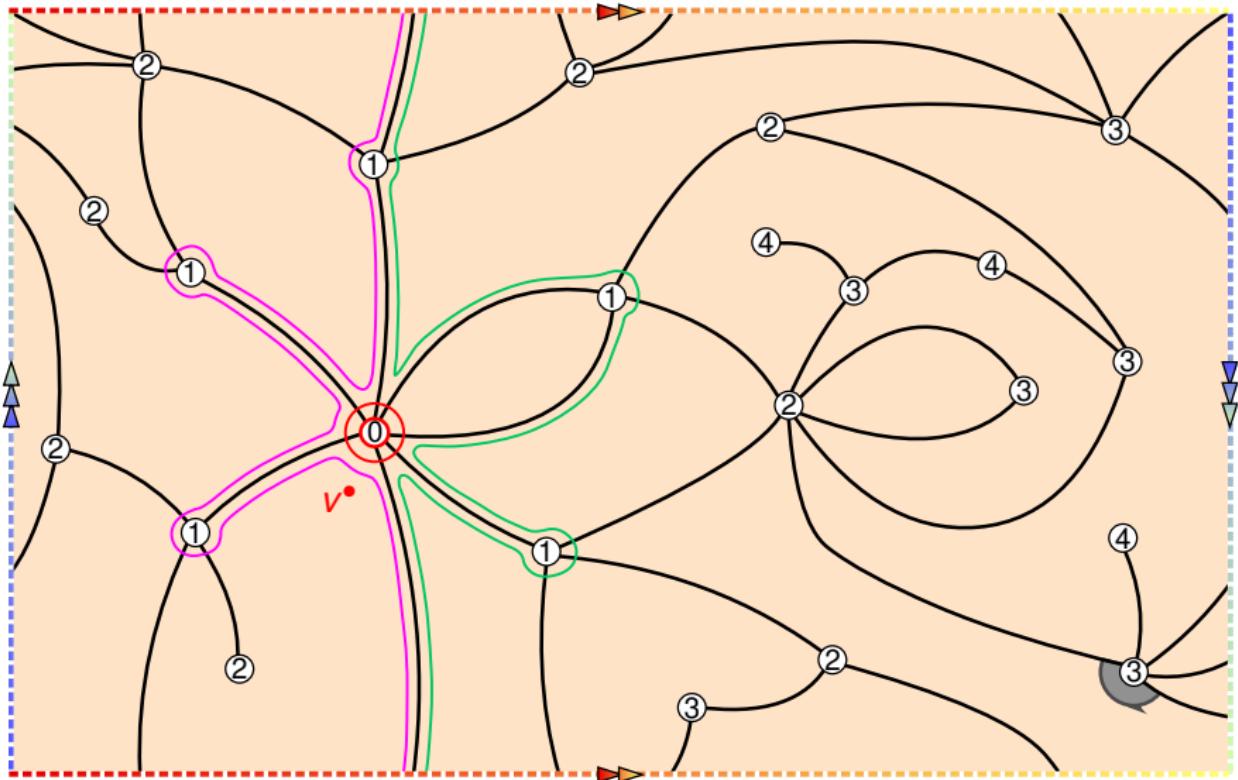
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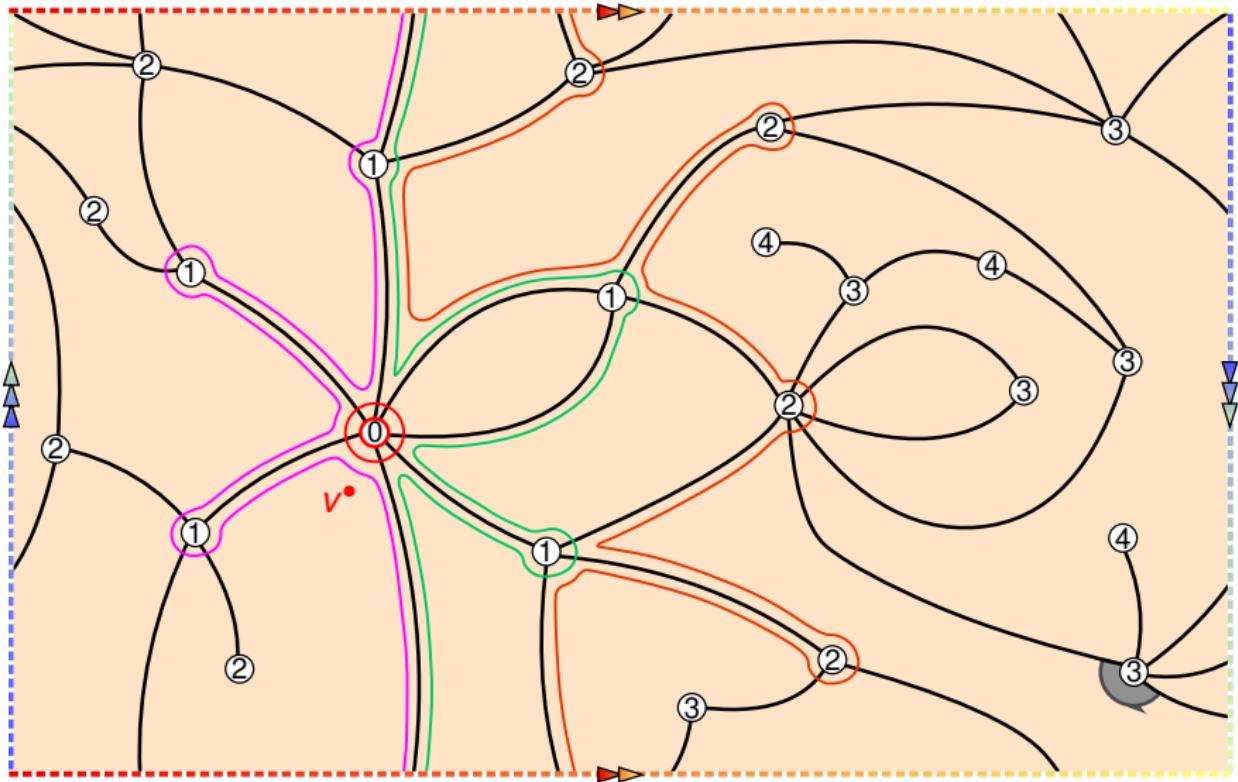
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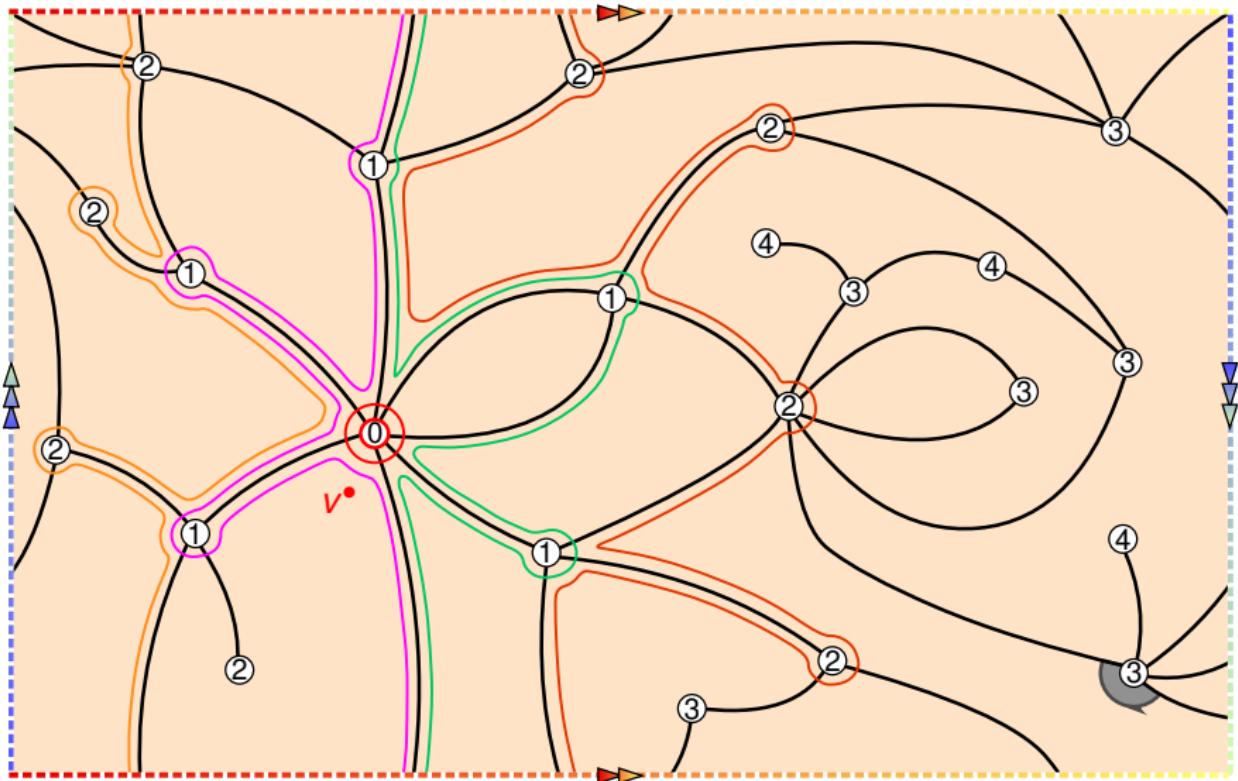
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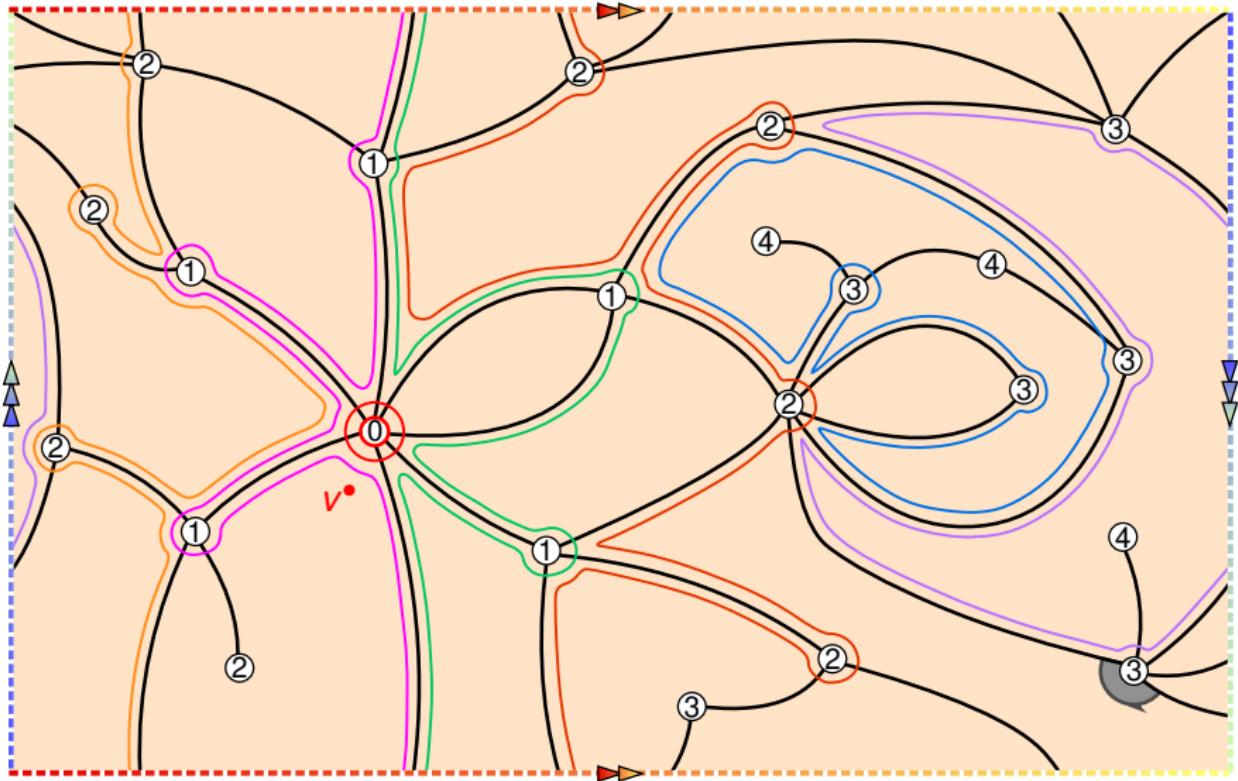
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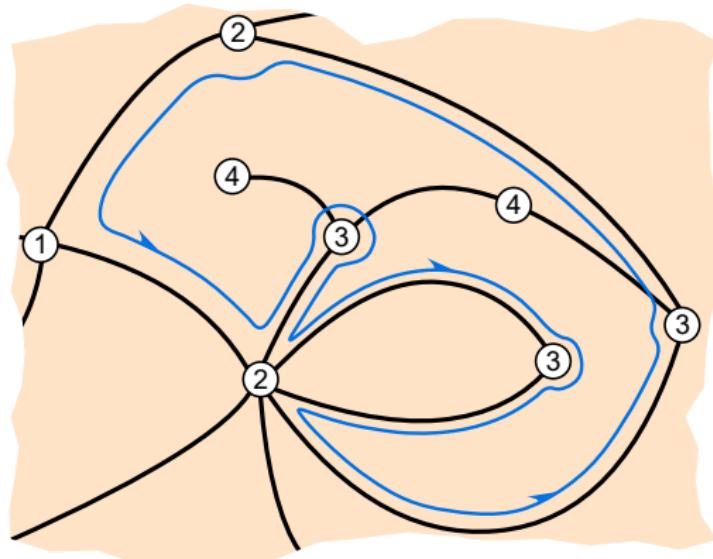
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Definition of stops after orientation



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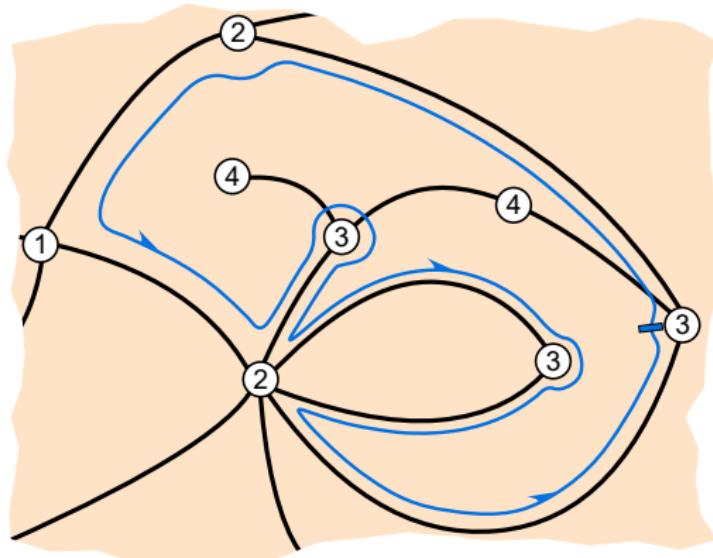
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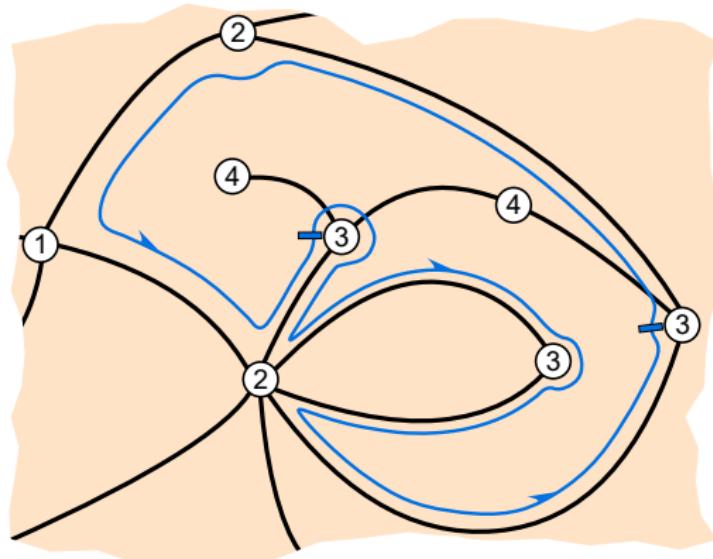
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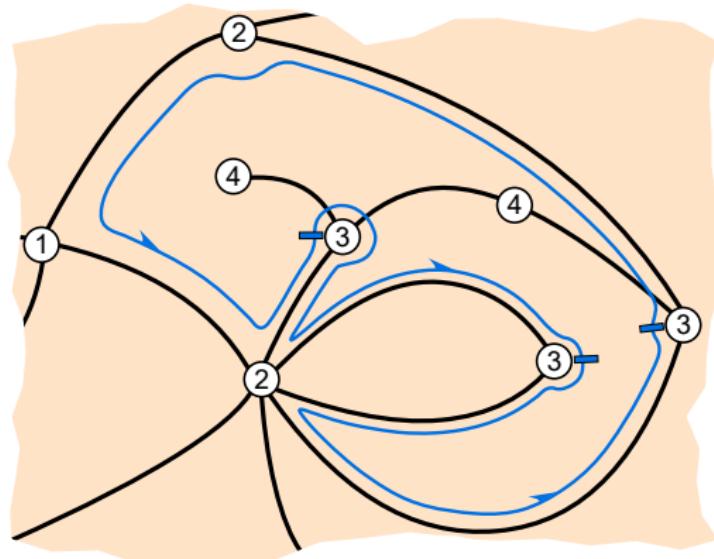
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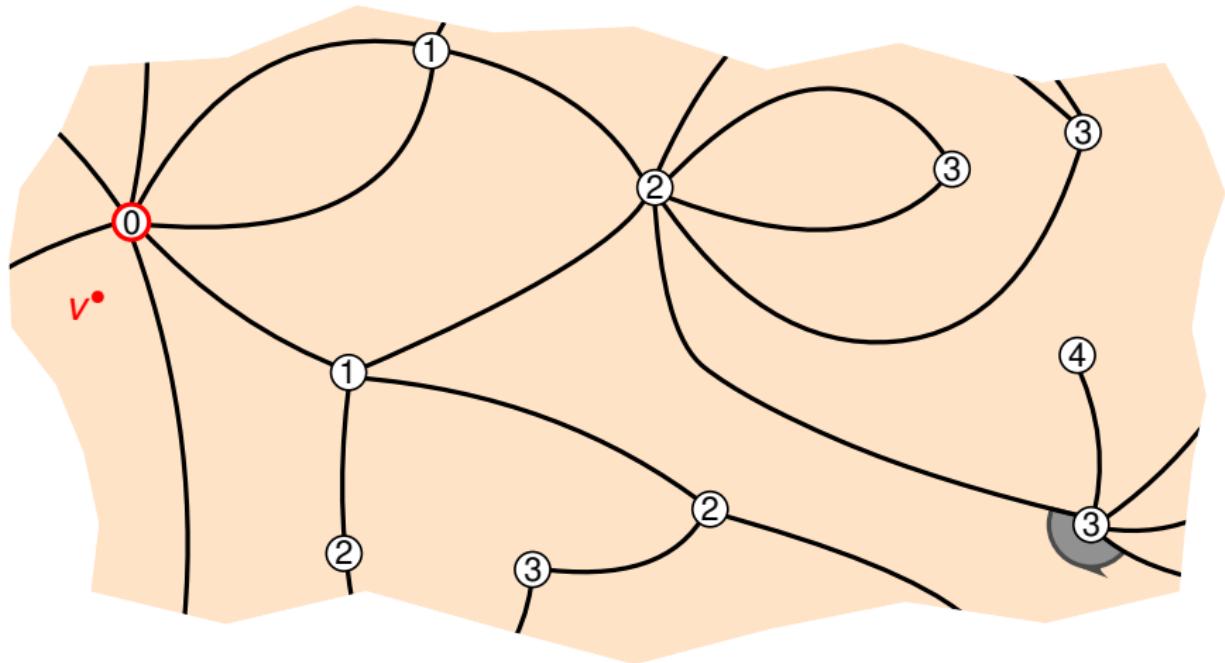
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Orientation of the level loops: initialization



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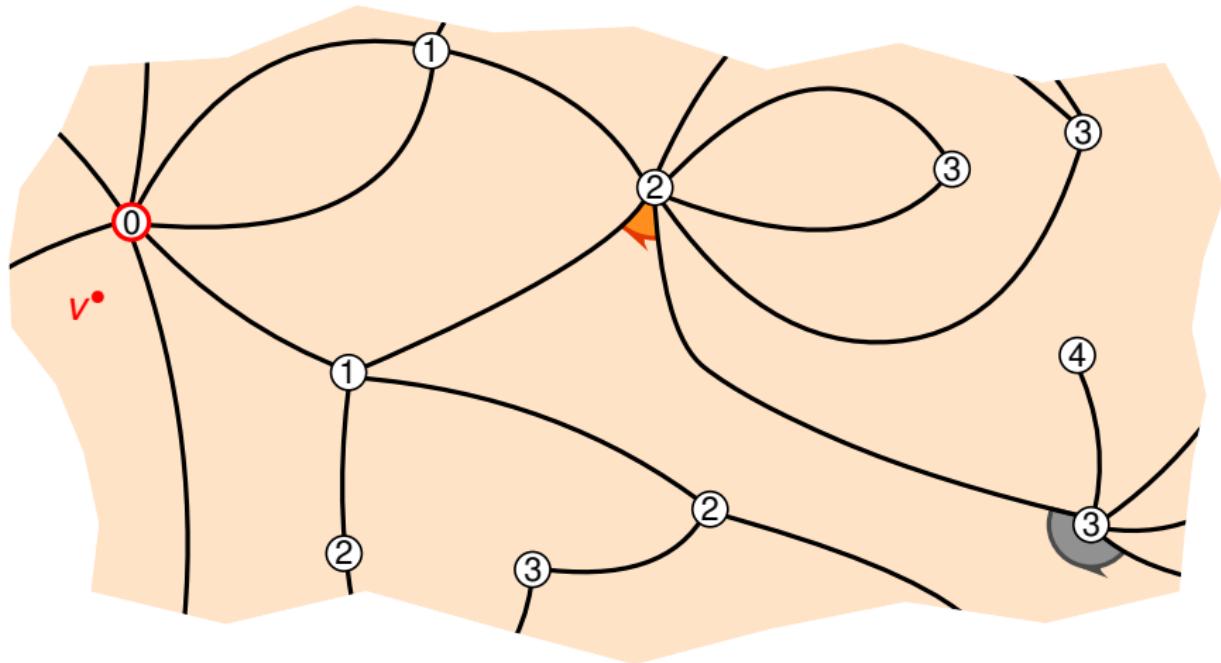
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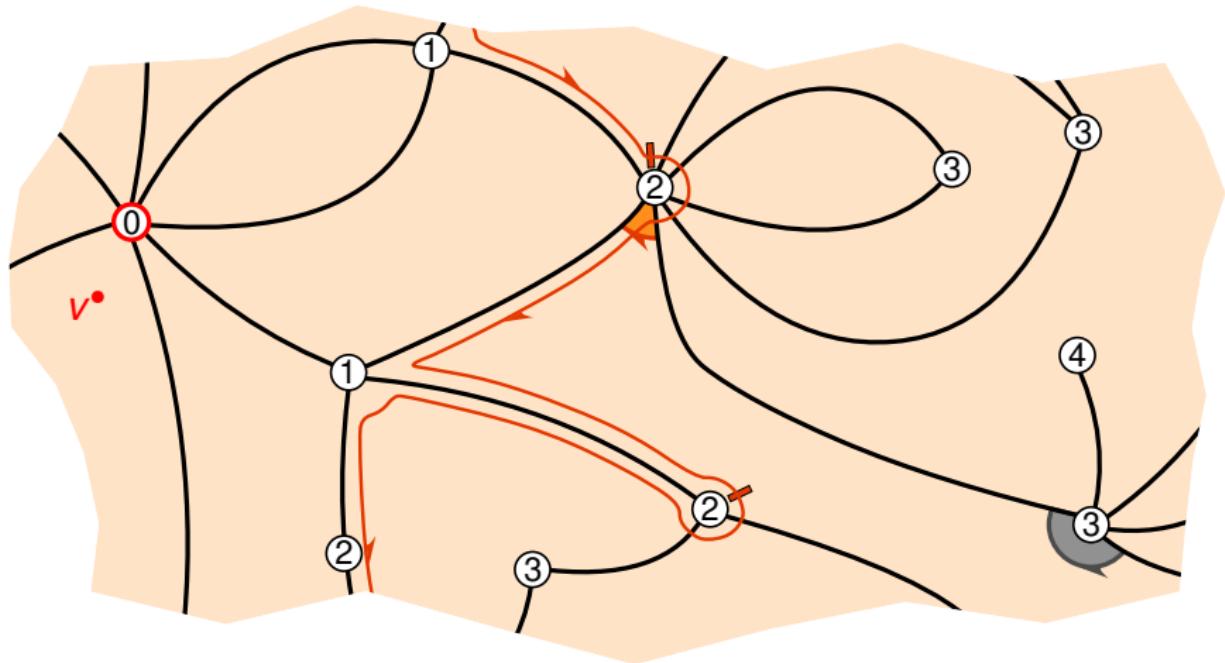
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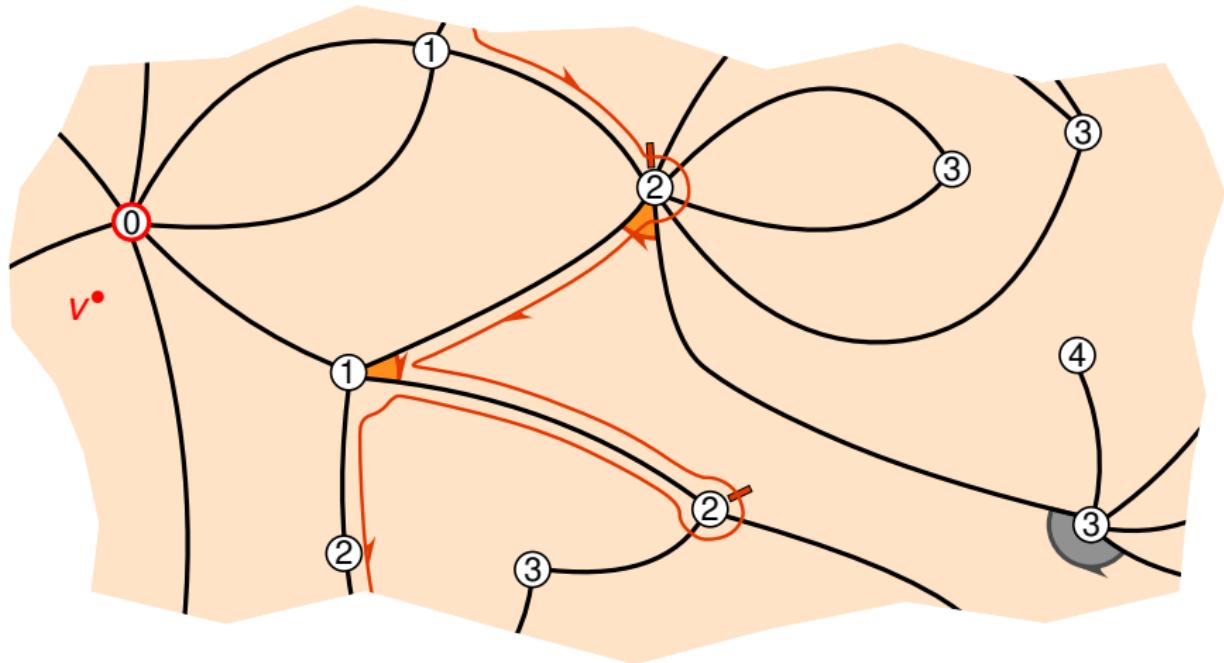
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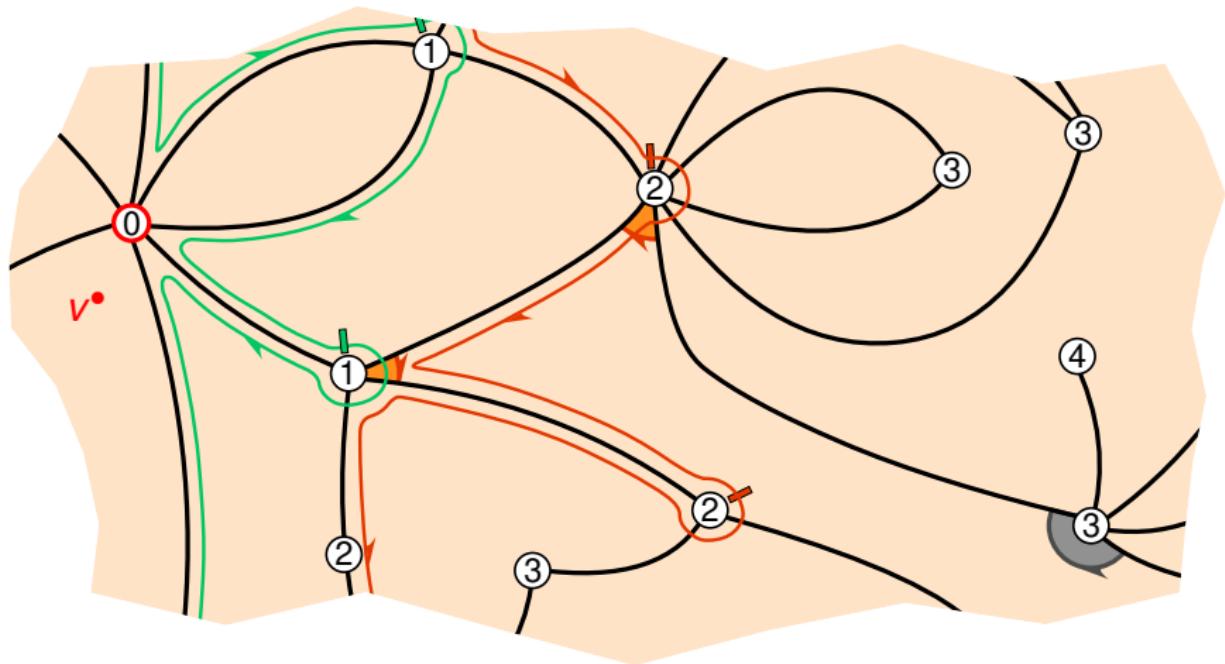
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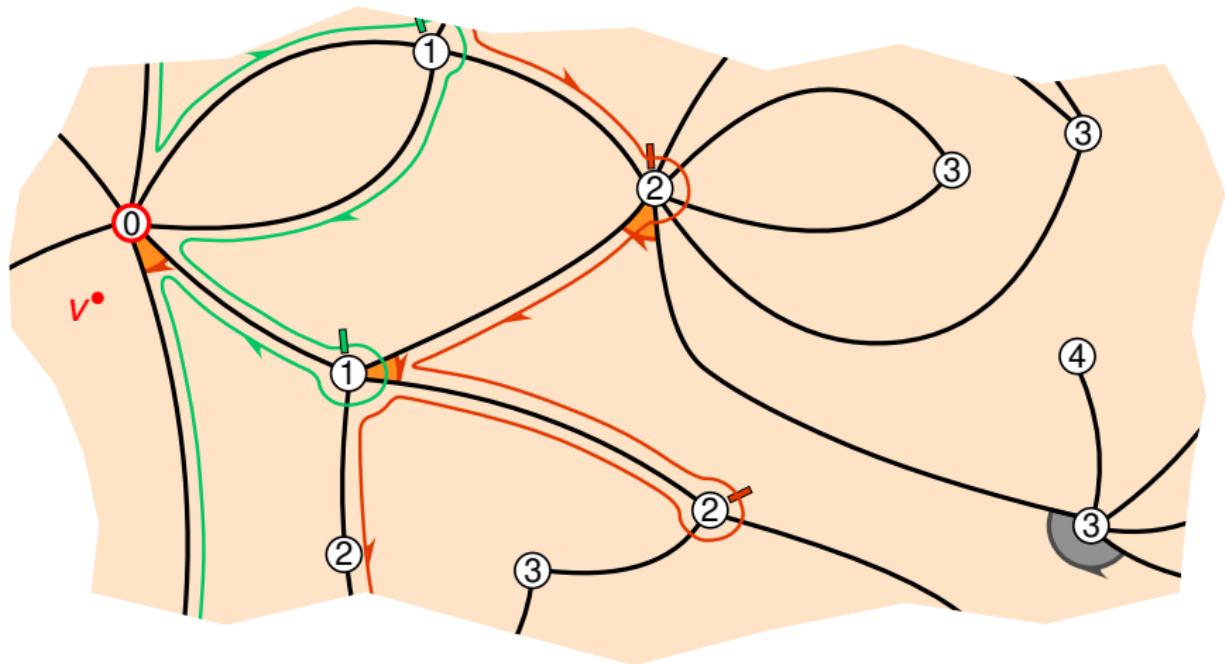
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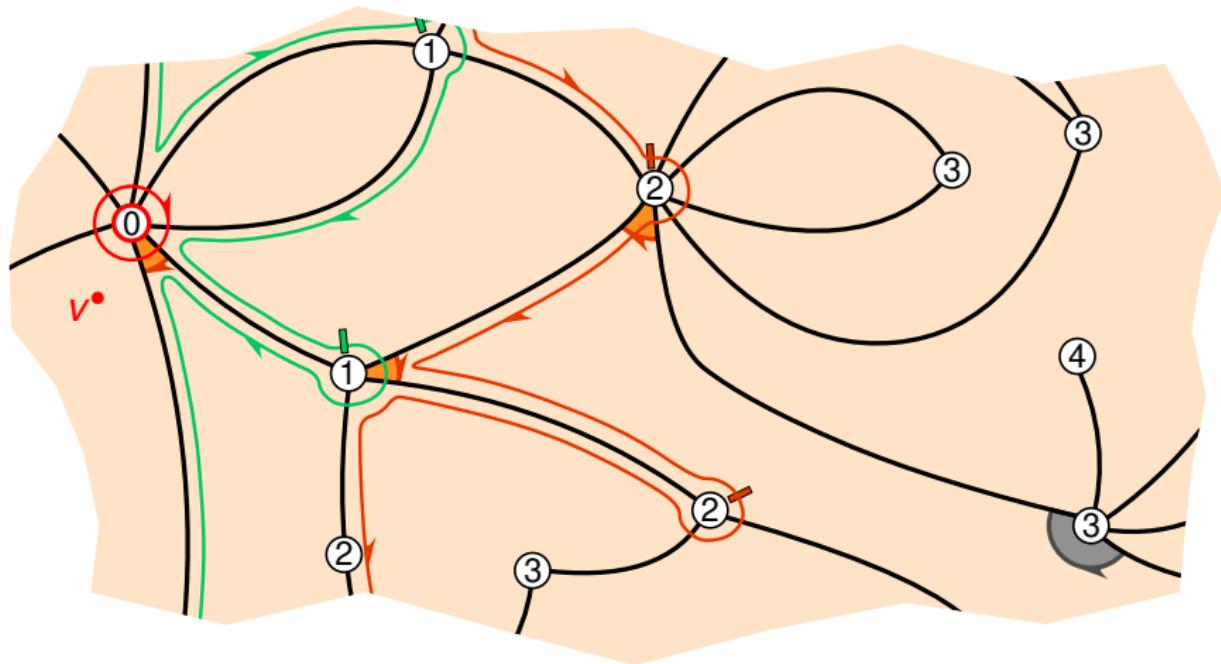
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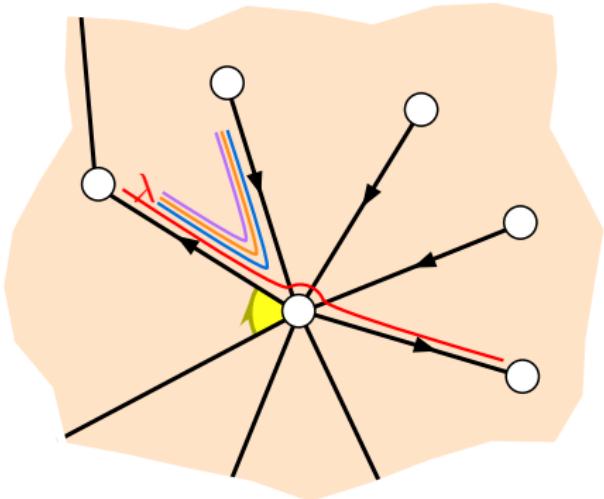
Bipartite maps
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Orientation of the level loops: corner exploration

- o *Turning around the initial vertex*



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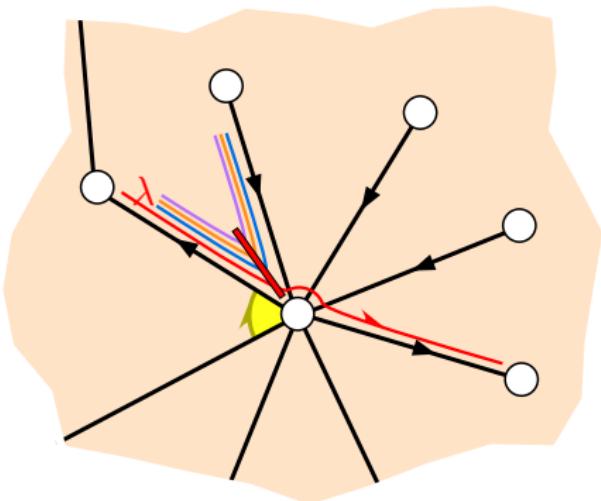
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Bipartite maps
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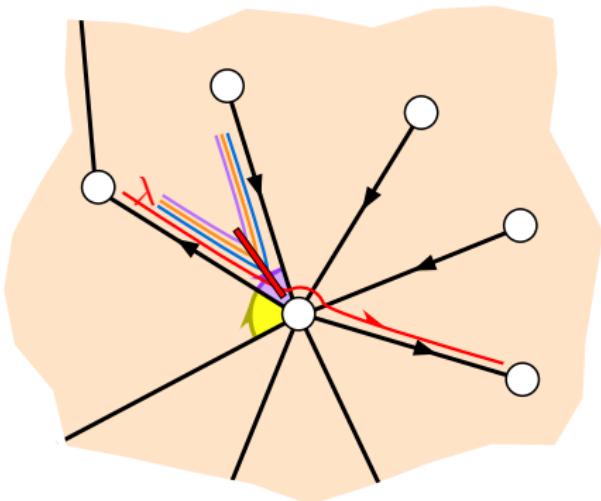
Bipartite quadrangulations
ooo

Orientation of the level loops: corner exploration



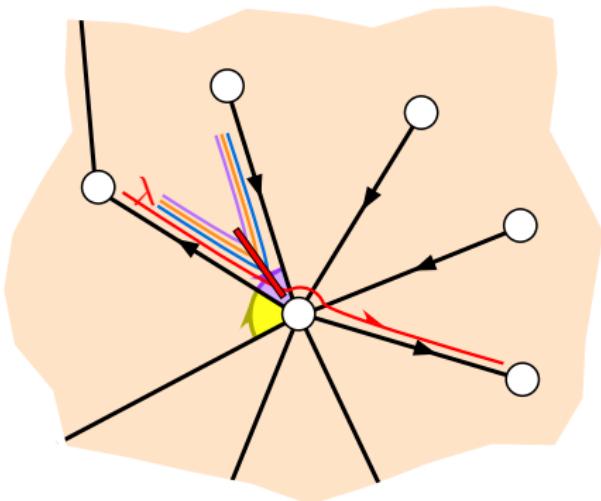
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.

Orientation of the level loops: corner exploration



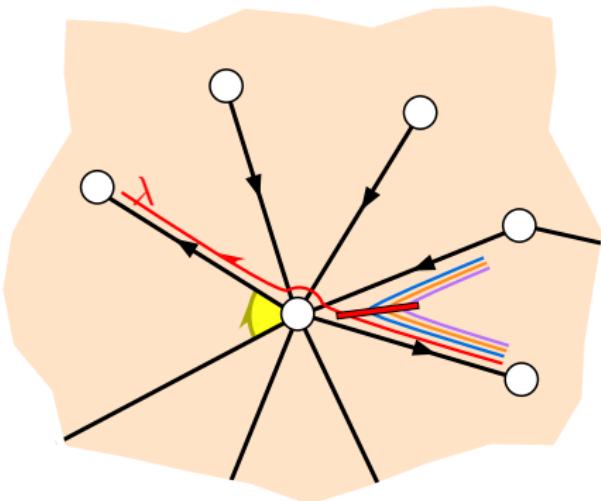
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.

Orientation of the level loops: corner exploration



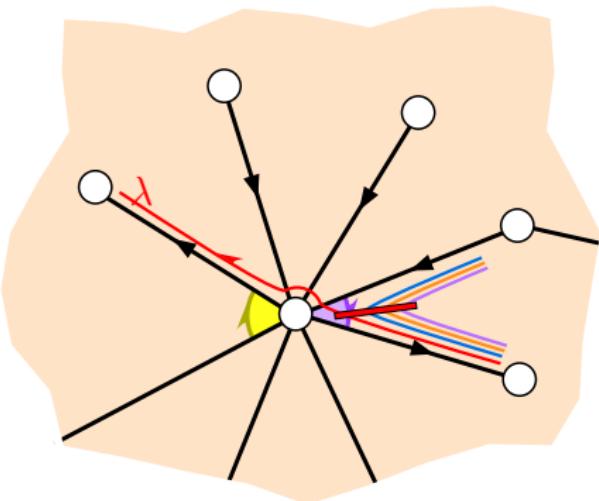
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.

Orientation of the level loops: corner exploration



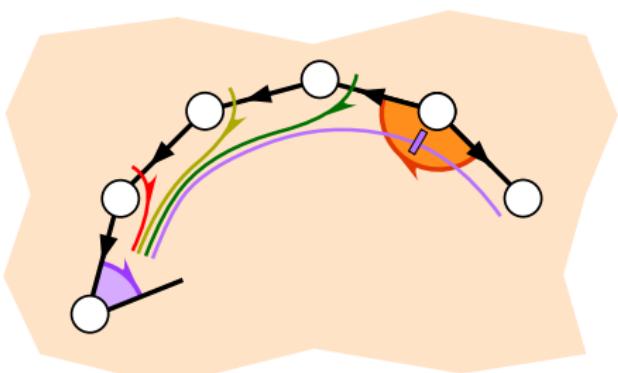
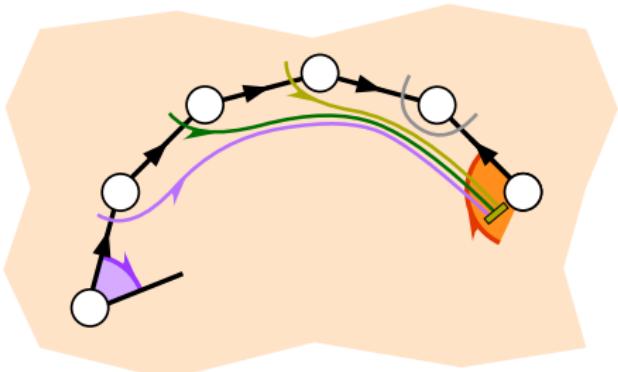
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.

Orientation of the level loops: corner exploration



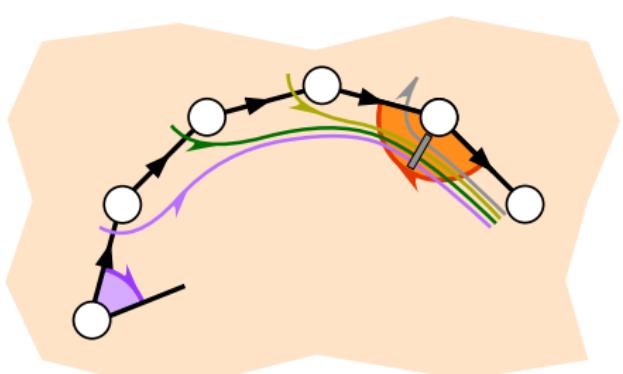
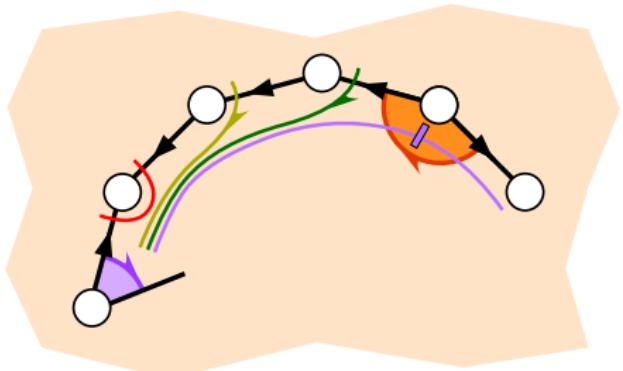
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.

Orientation of the level loops: corner exploration



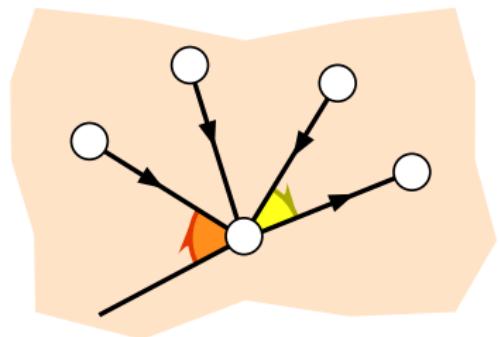
- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.
- *Moving around the face*
 - until there is a stop
 - or orienting the loop creates a stop.

Orientation of the level loops: corner exploration



- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.
- *Moving around the face*
 - until there is a stop
 - or orienting the loop creates a stop.

Orientation of the level loops: corner exploration



- *Turning around the initial vertex*
 - Orient λ if not oriented yet.
 - Turn to next stop.
 - Orient all the nonoriented loops.
- *Moving around the face*
 - until there is a stop
 - or orienting the loop creates a stop.
- *Turning around the final vertex*
 - Turn to next outgoing edge.

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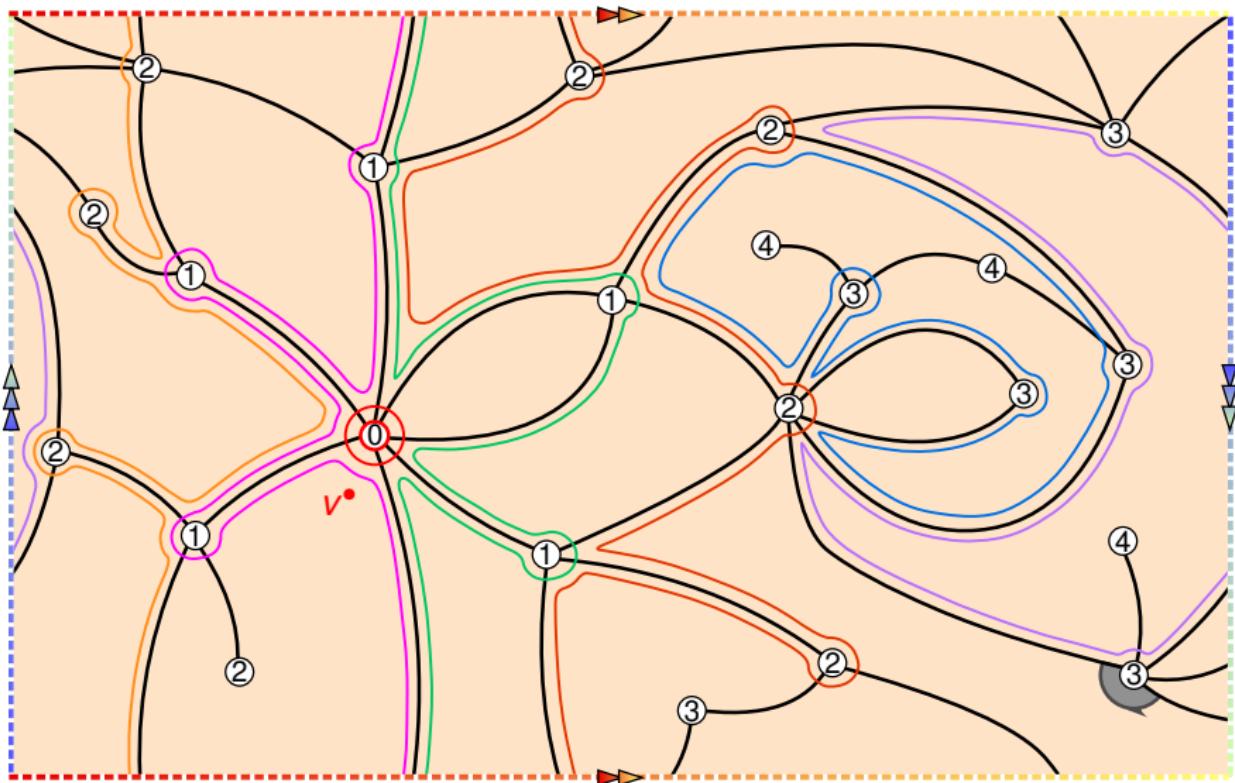
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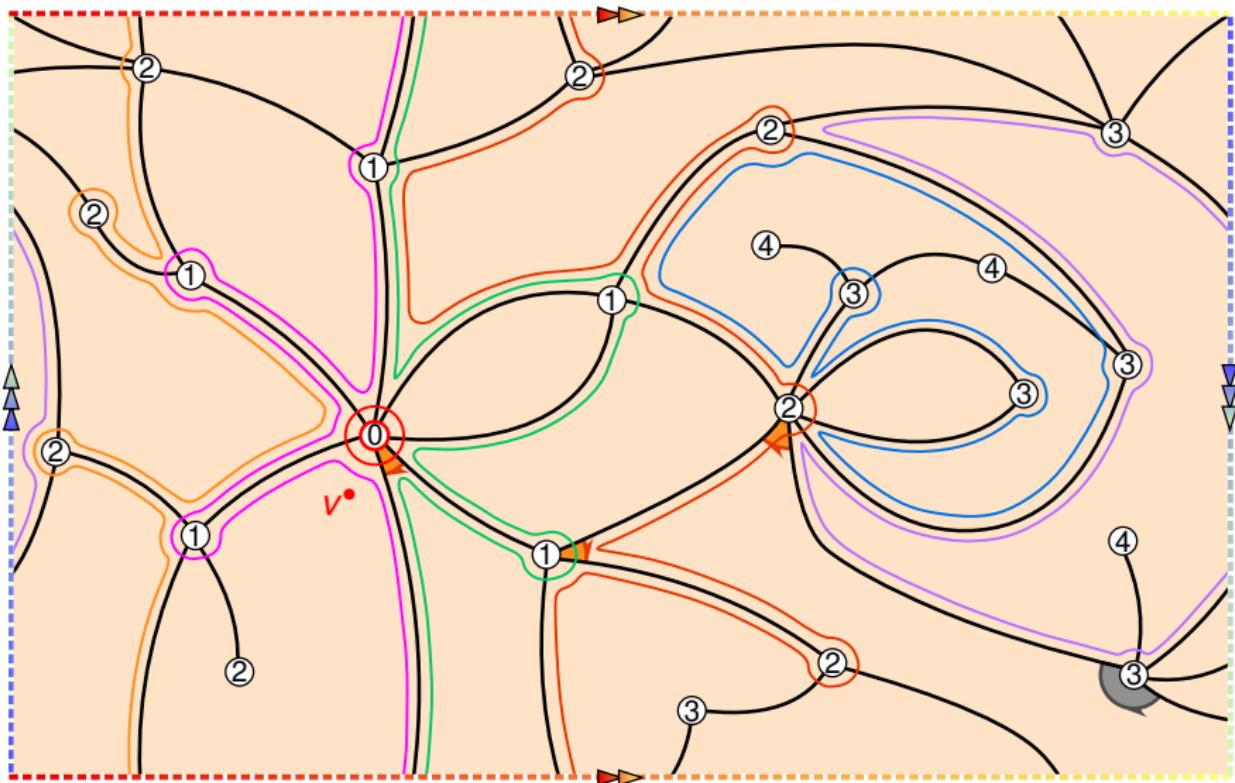
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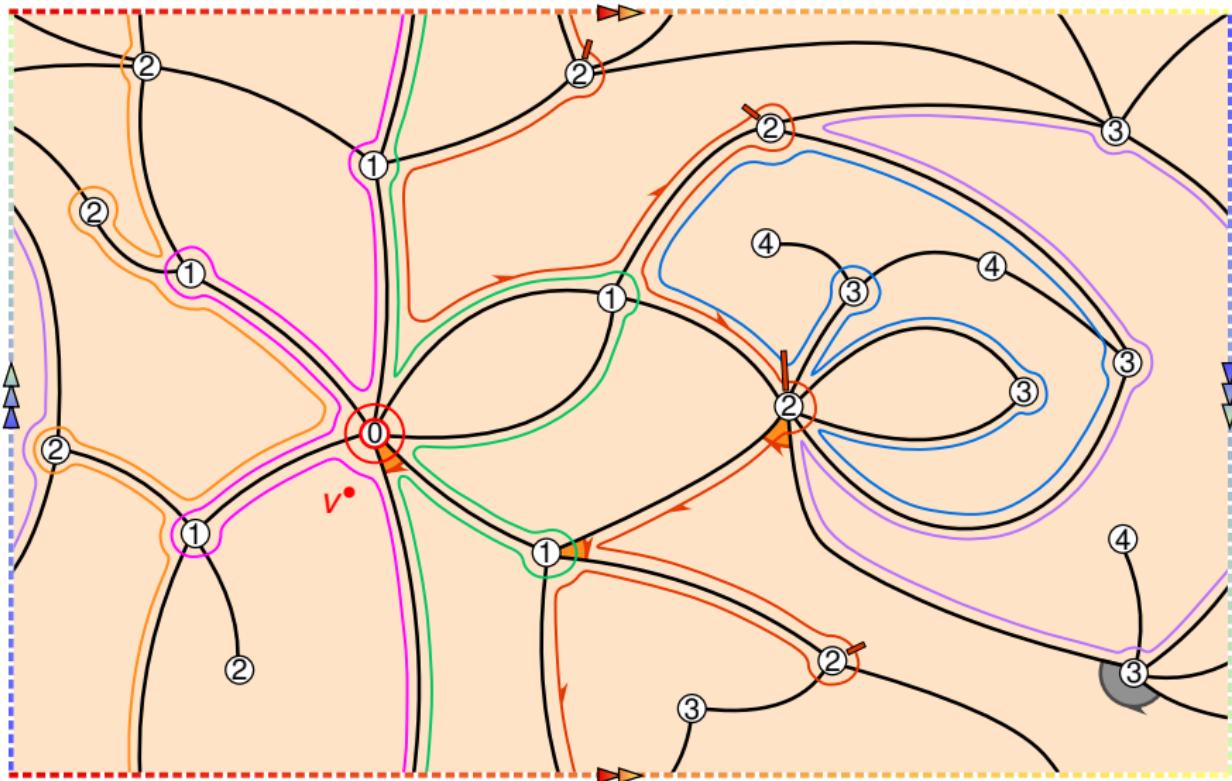
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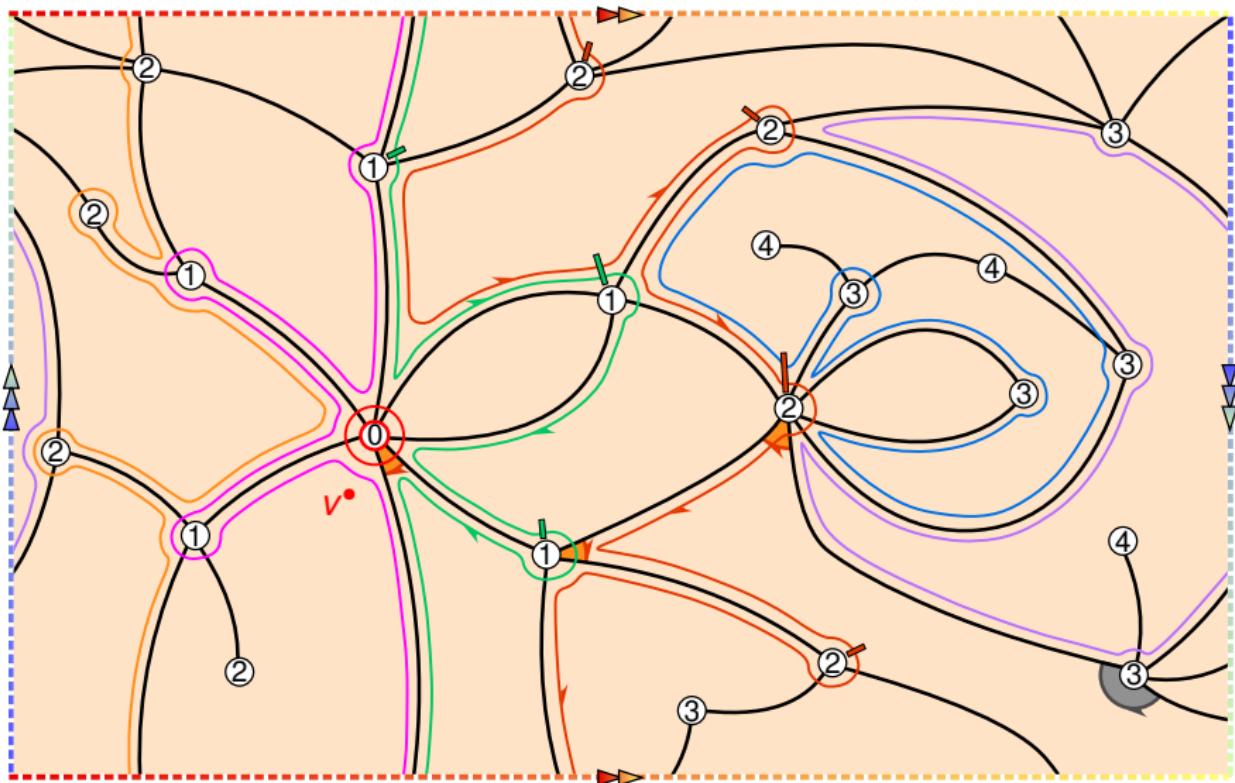
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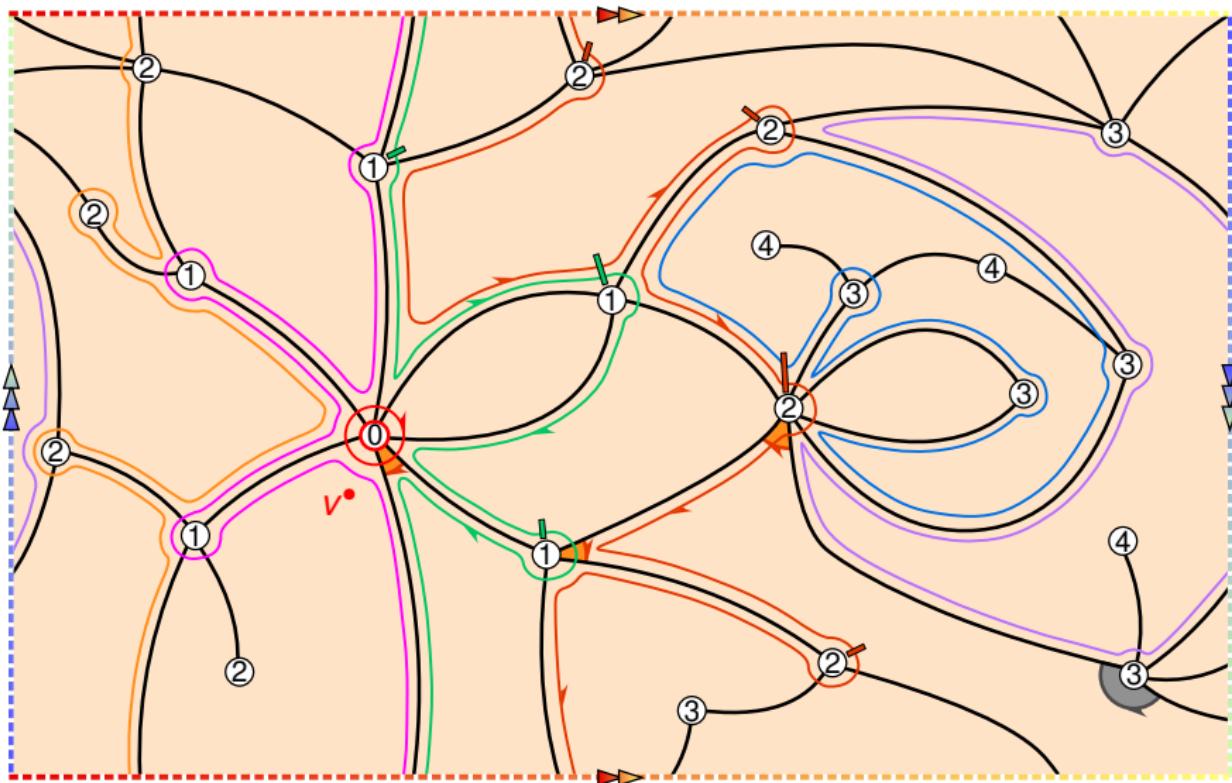
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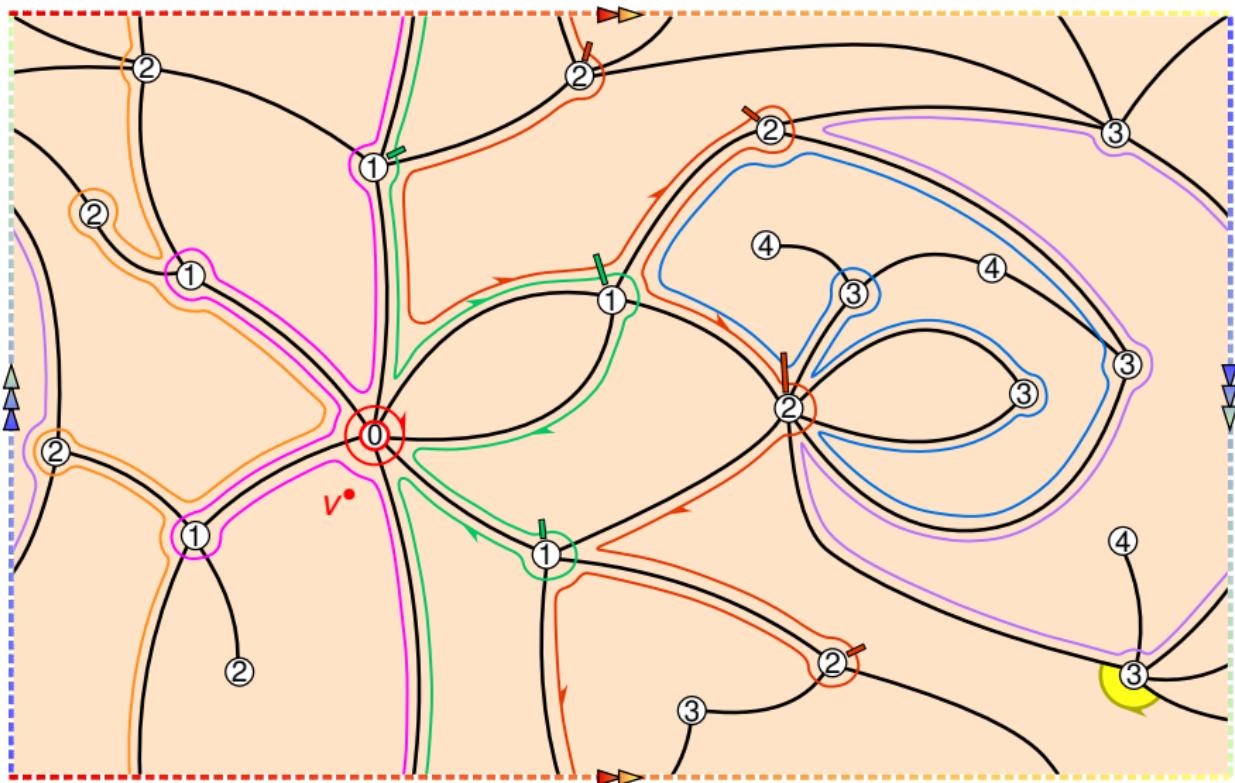
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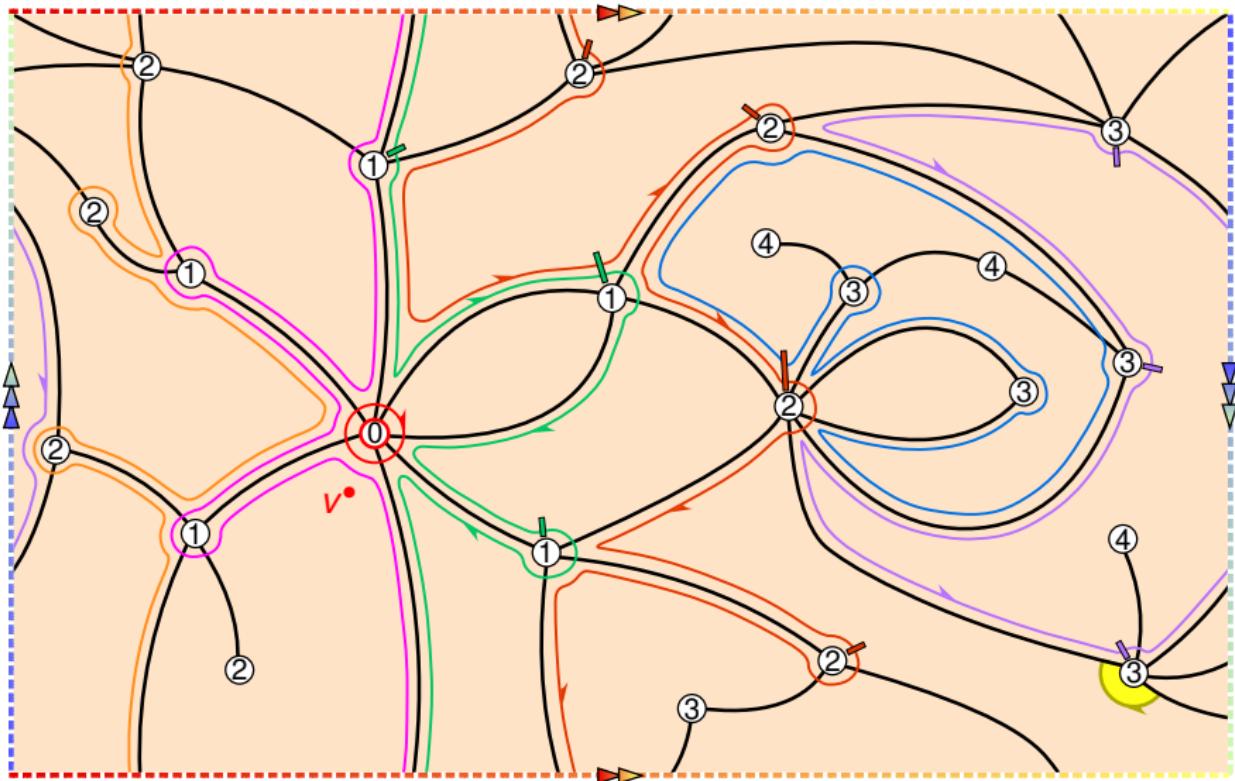
From pointed bipartite maps to unicellular mobiles



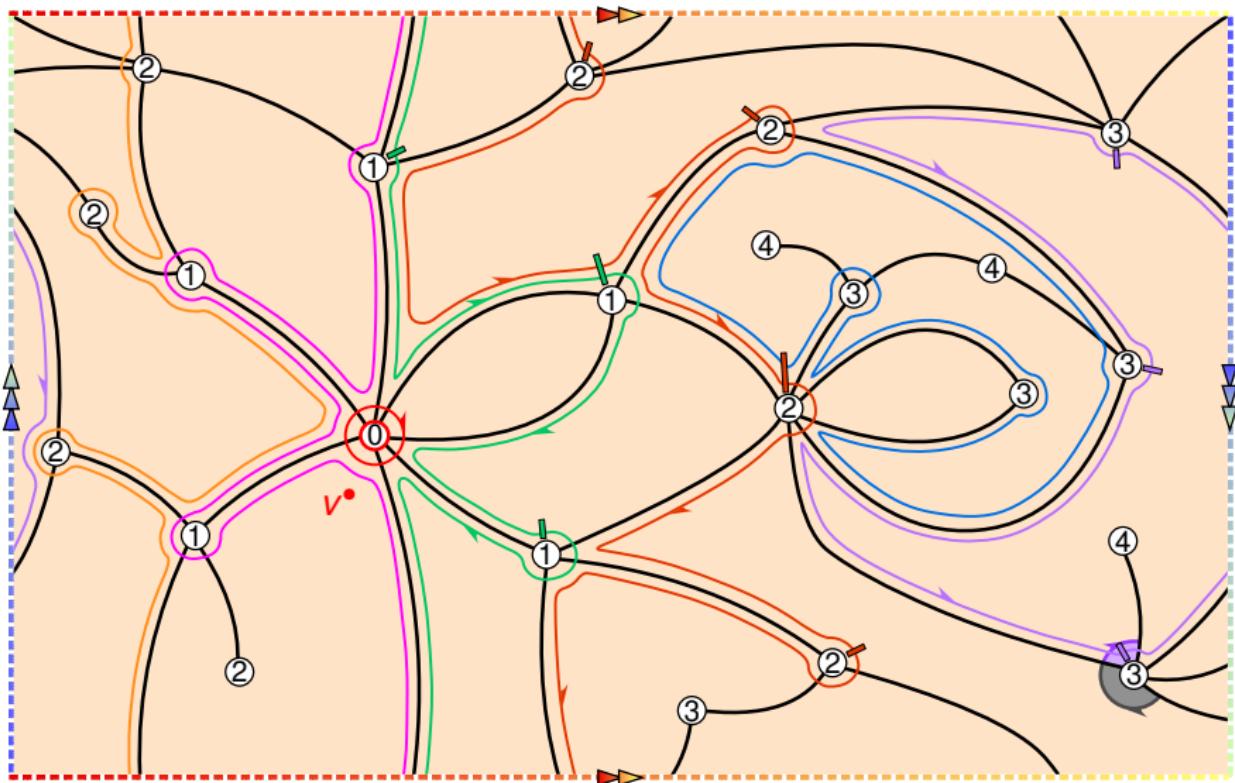
From pointed bipartite maps to unicellular mobiles



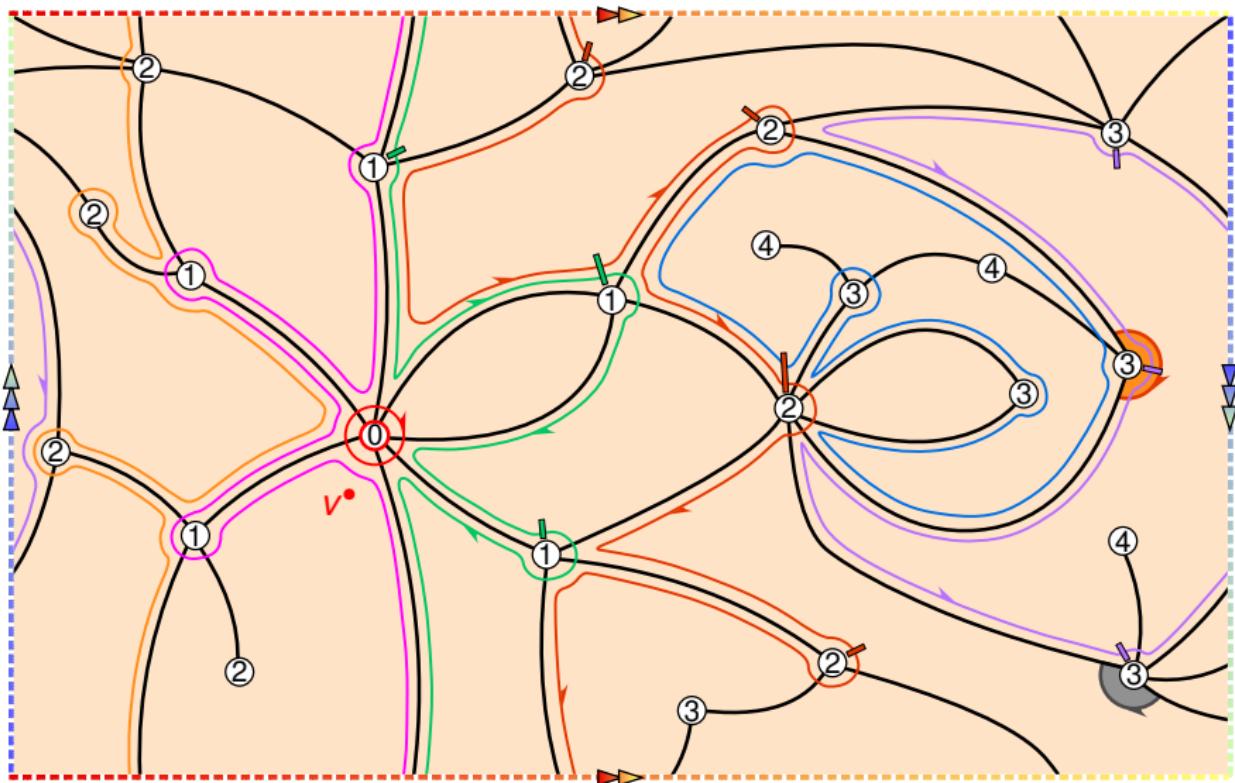
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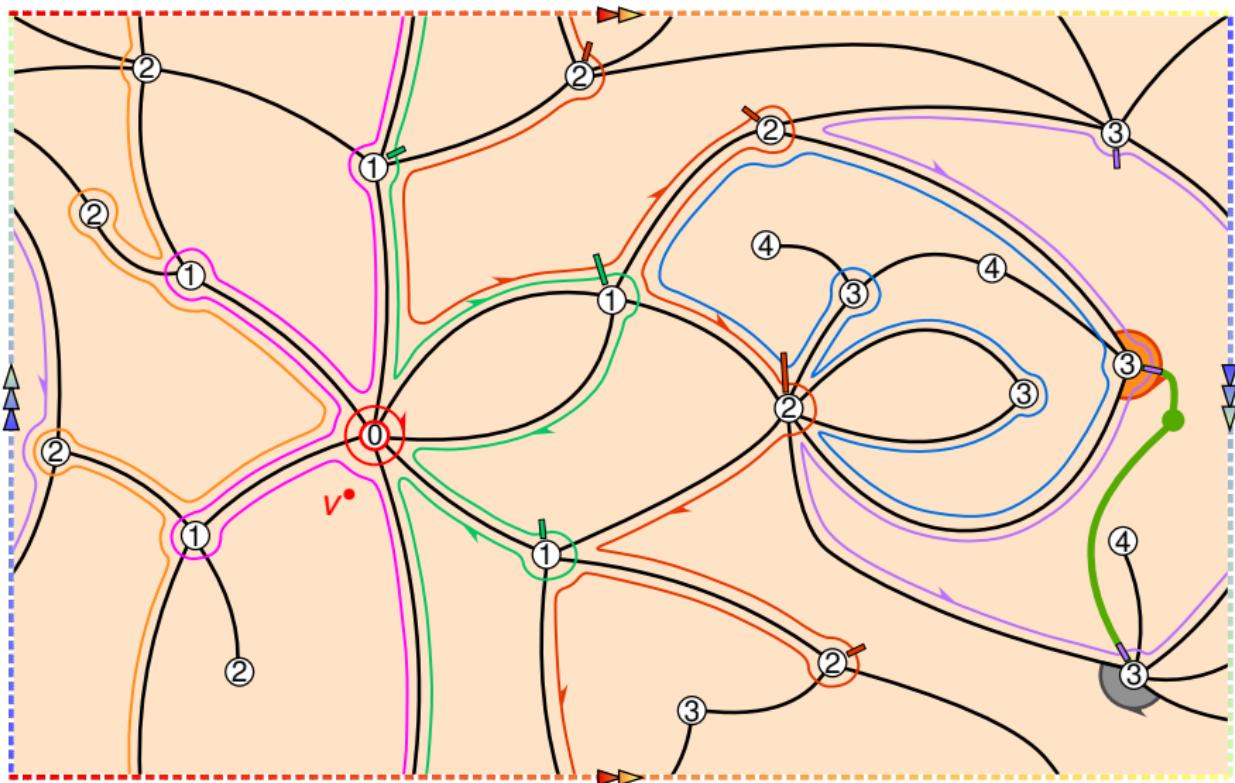
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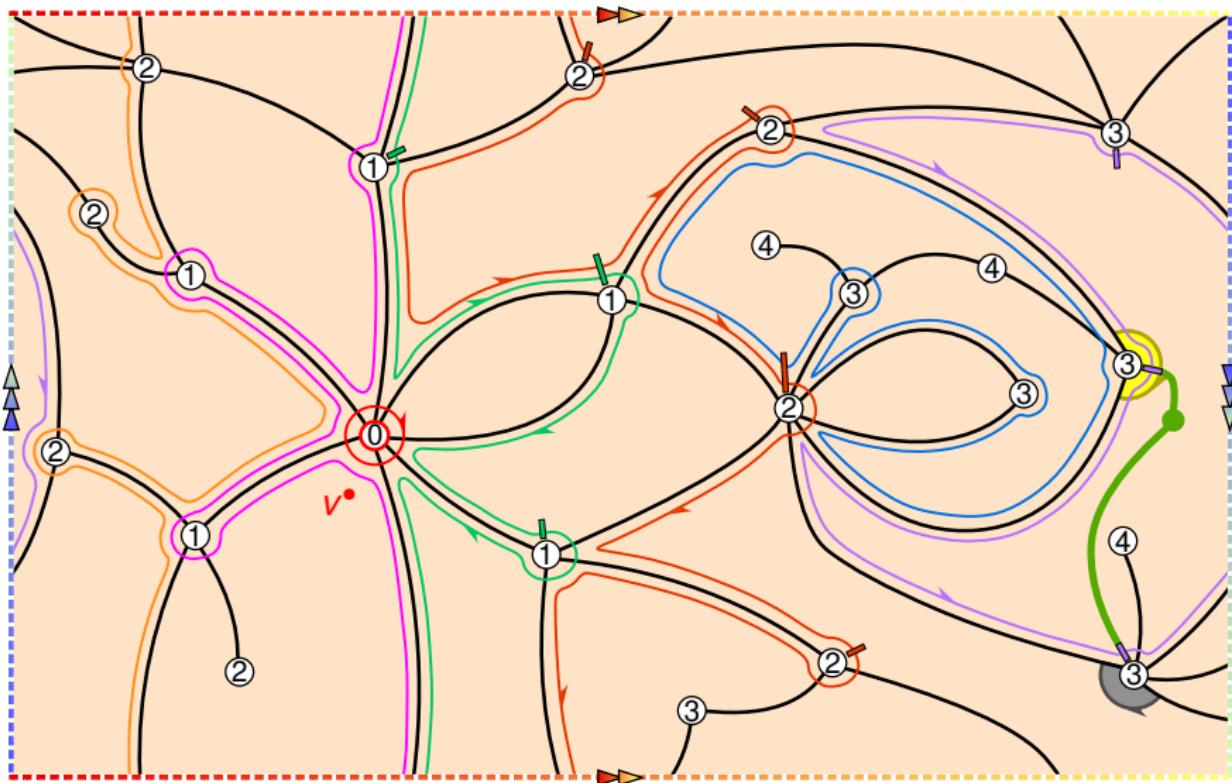
From pointed bipartite maps to unicellular mobiles



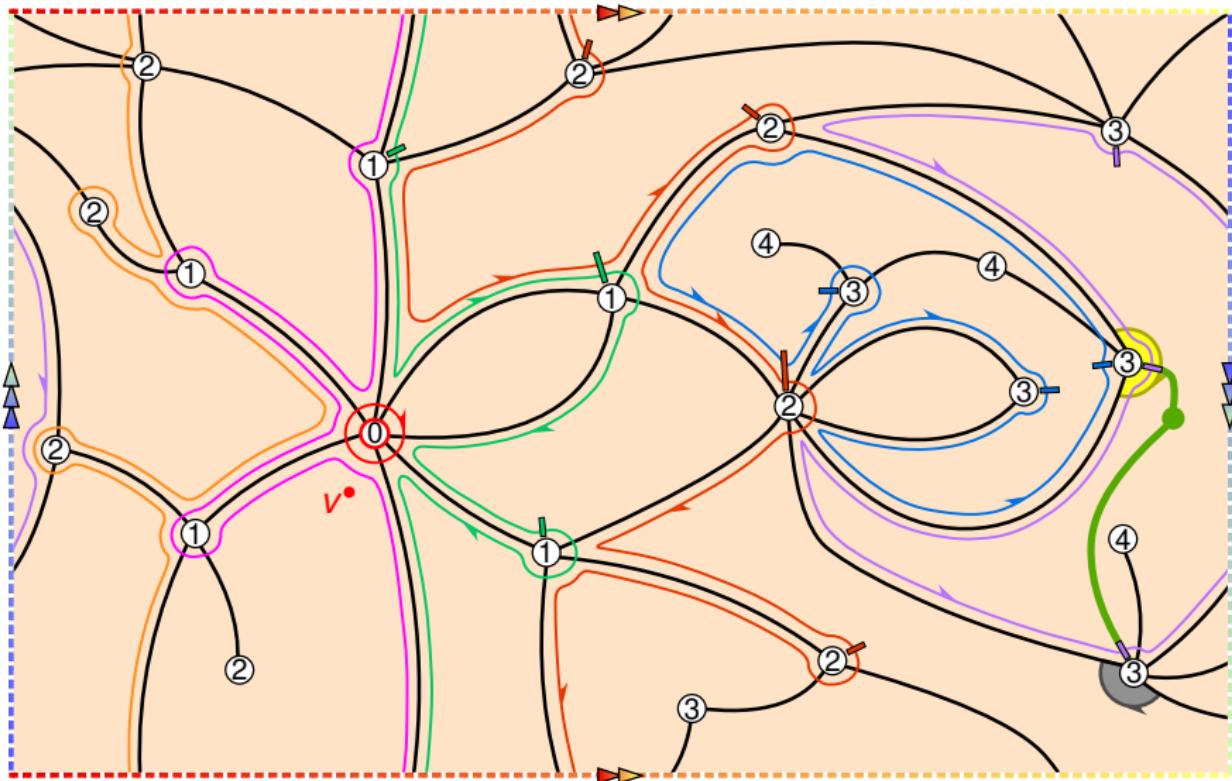
From pointed bipartite maps to unicellular mobiles



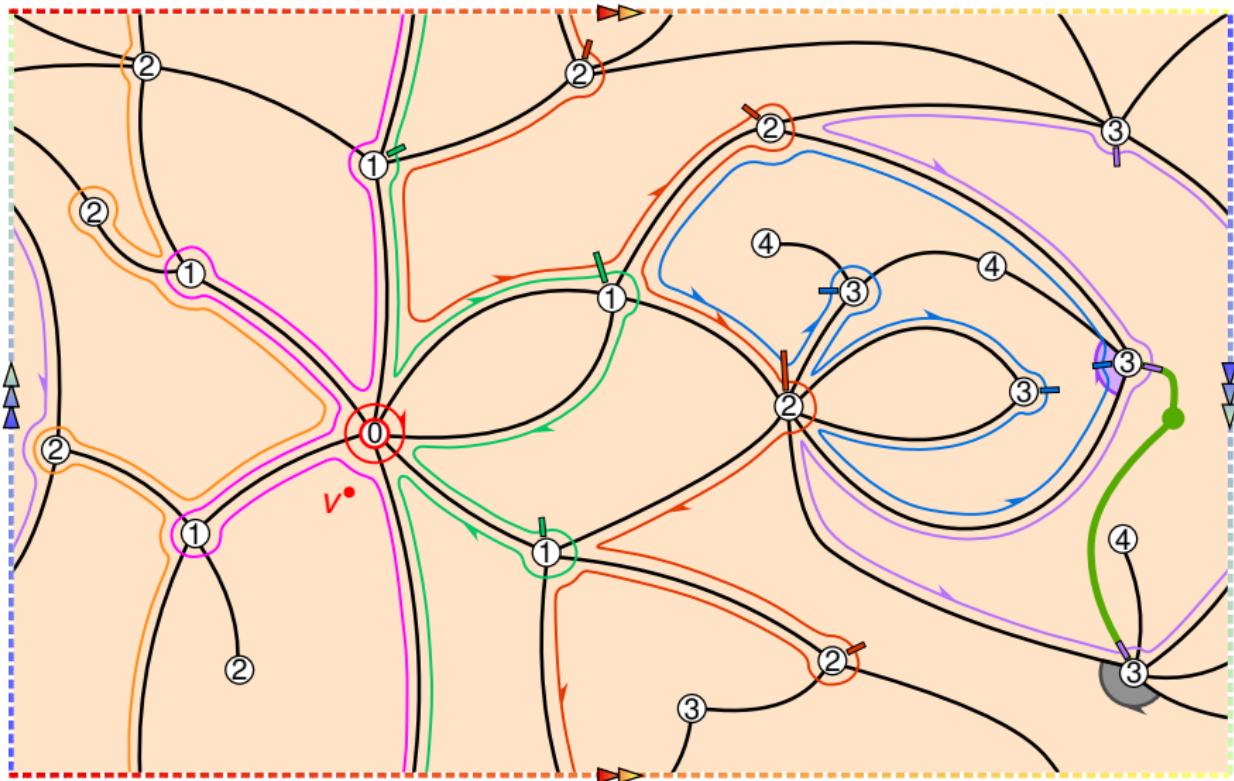
From pointed bipartite maps to unicellular mobiles



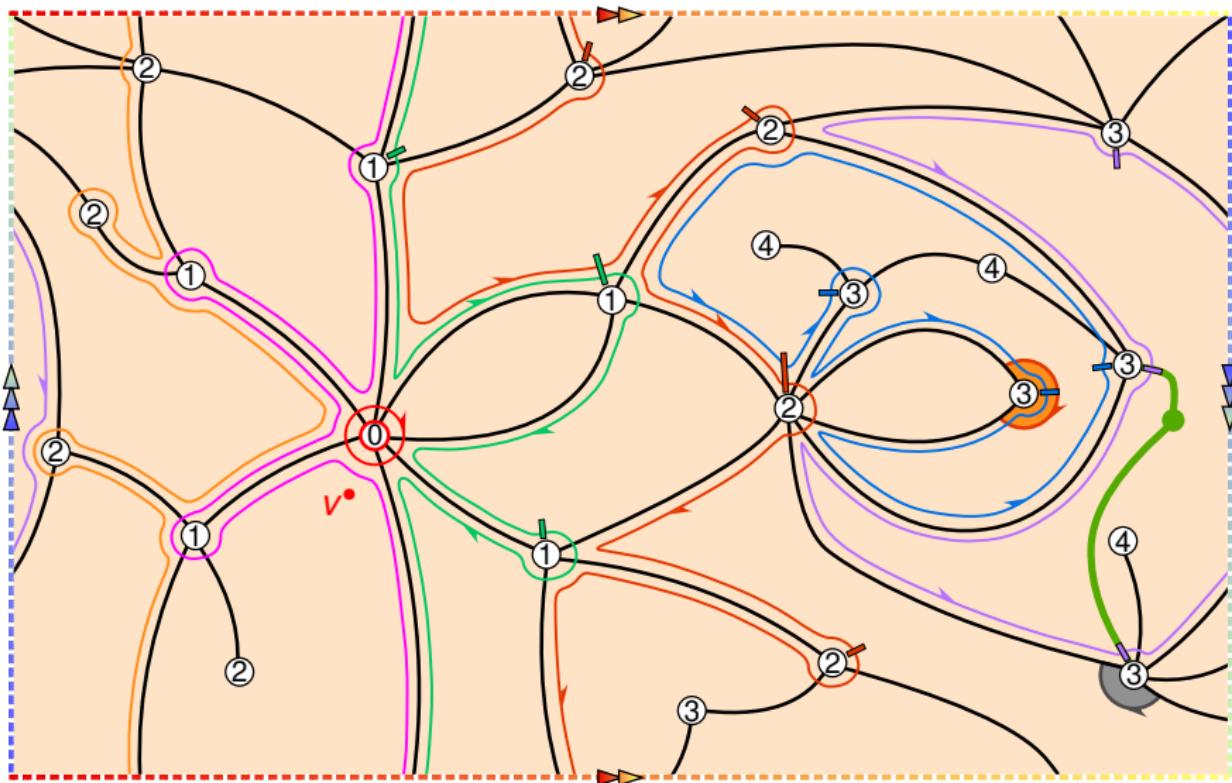
From pointed bipartite maps to unicellular mobiles



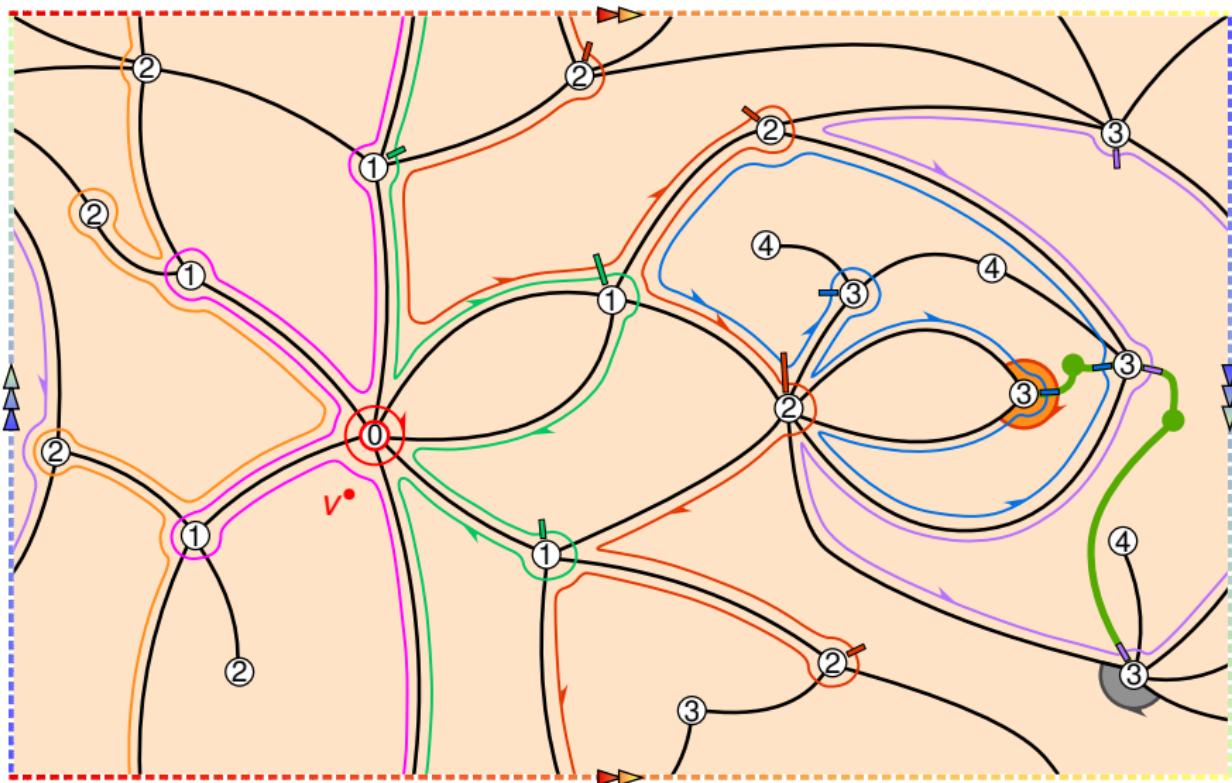
From pointed bipartite maps to unicellular mobiles



From pointed bipartite maps to unicellular mobiles



From pointed bipartite maps to unicellular mobiles



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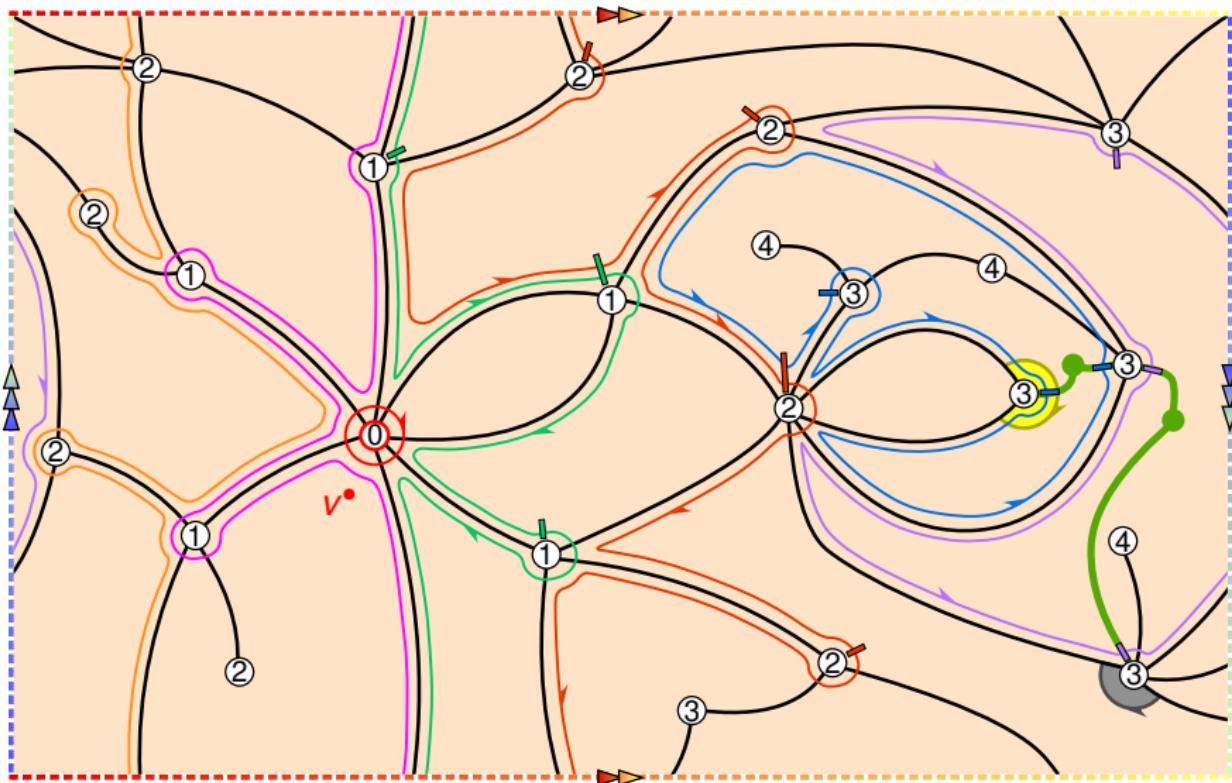
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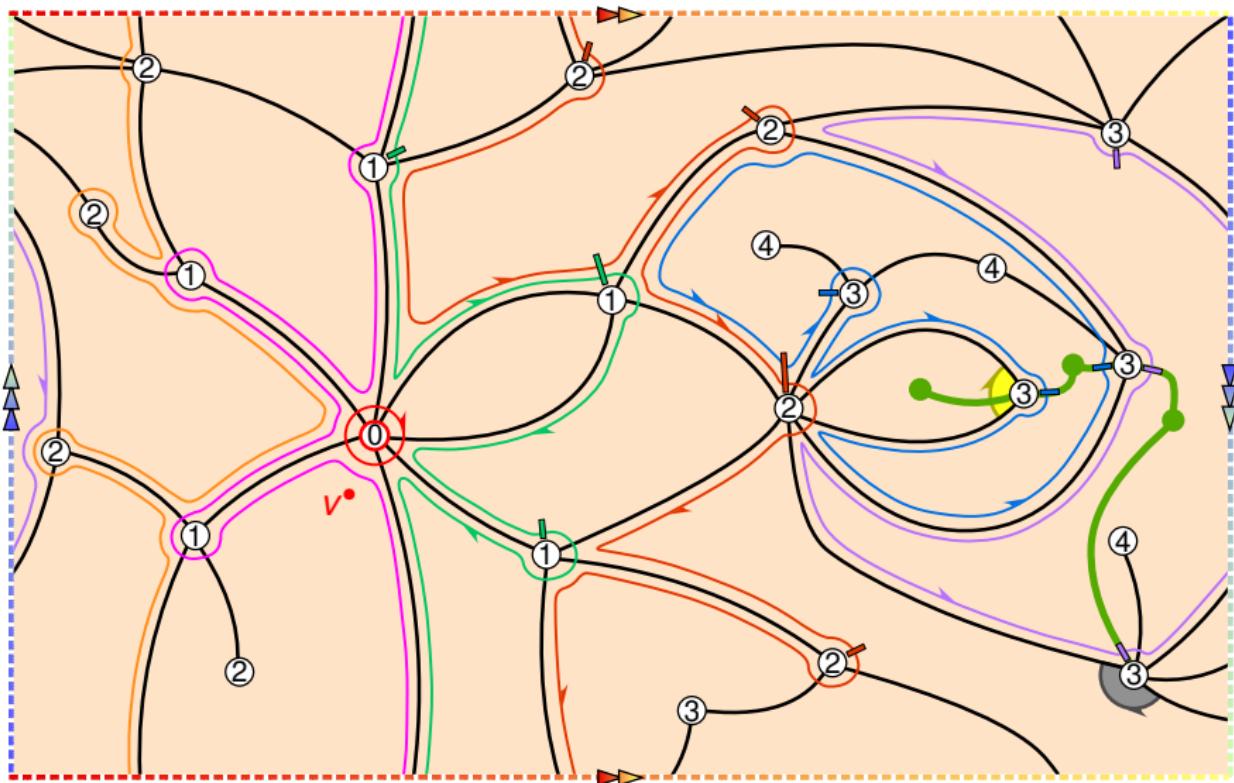
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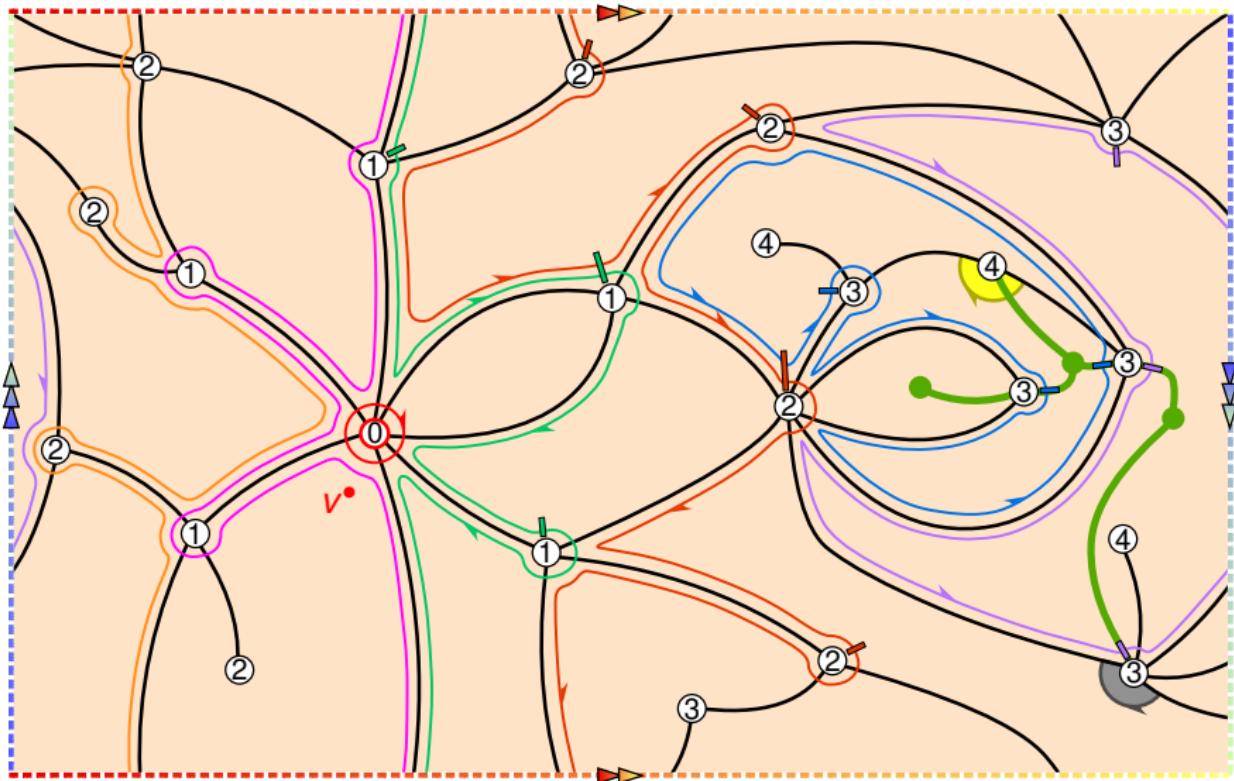
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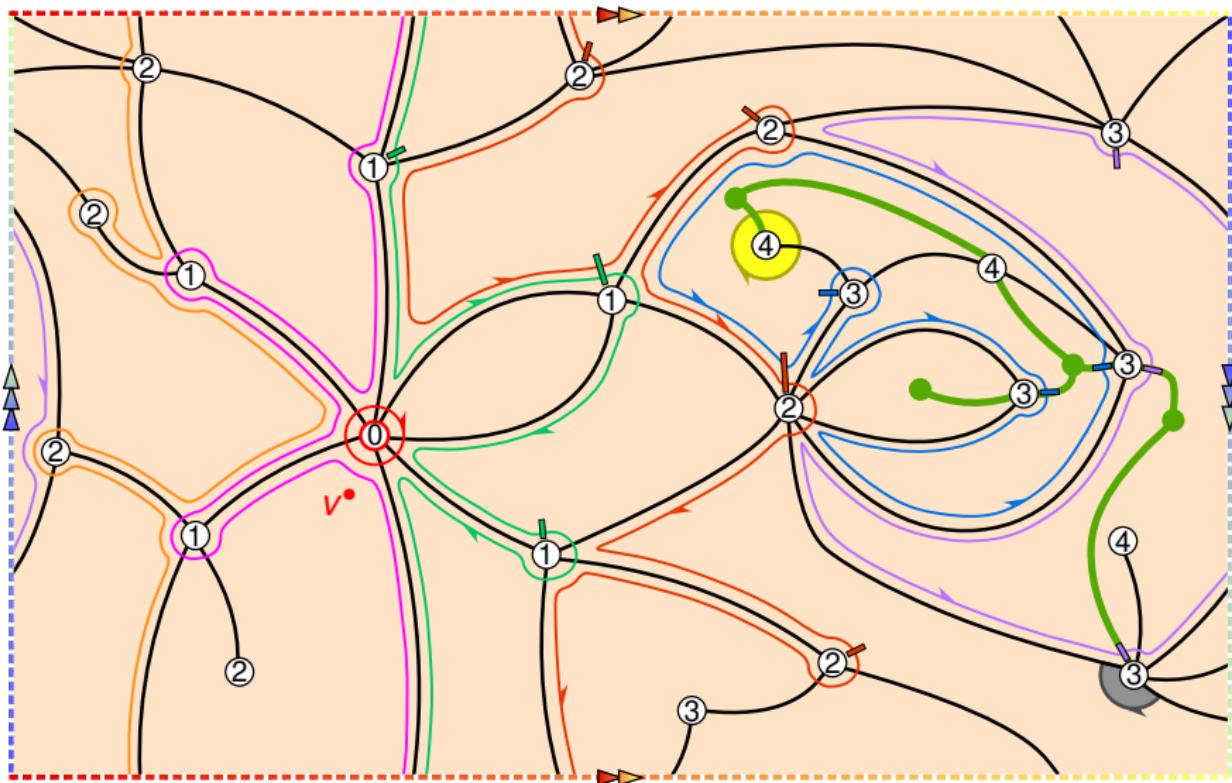
From pointed bipartite maps to unicellular mobiles



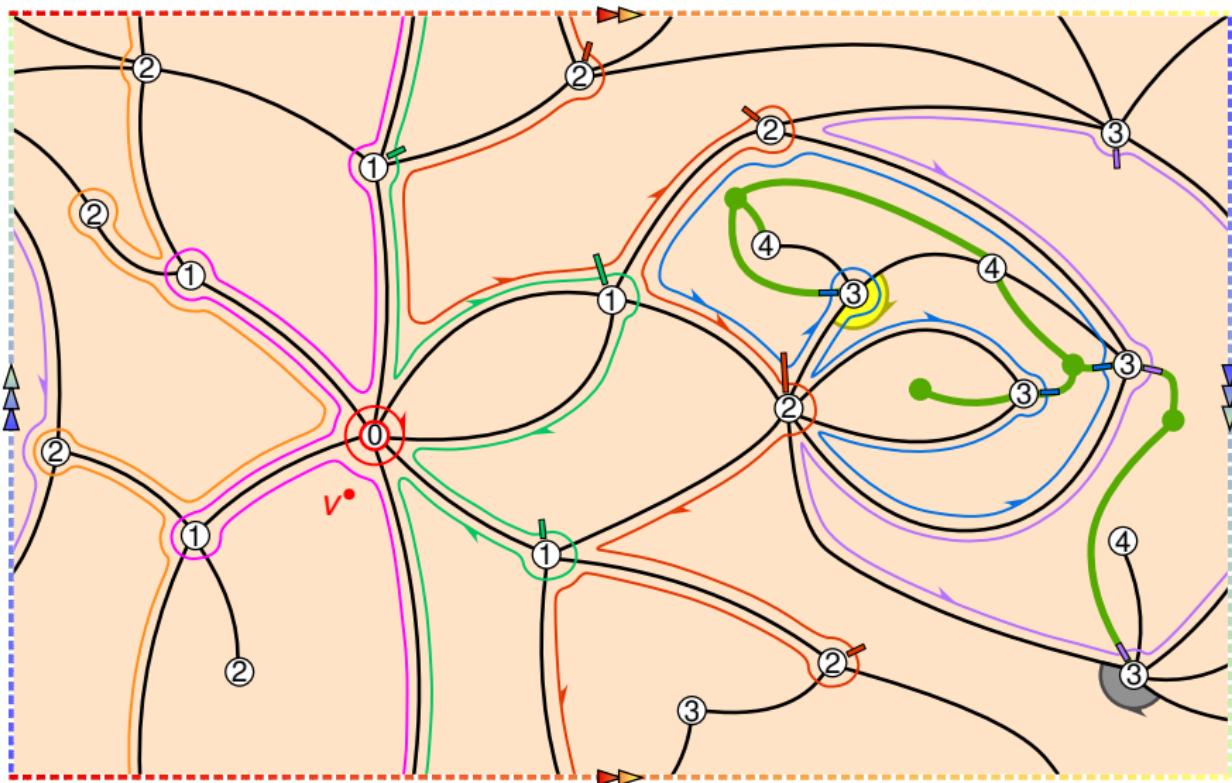
From pointed bipartite maps to unicellular mobiles



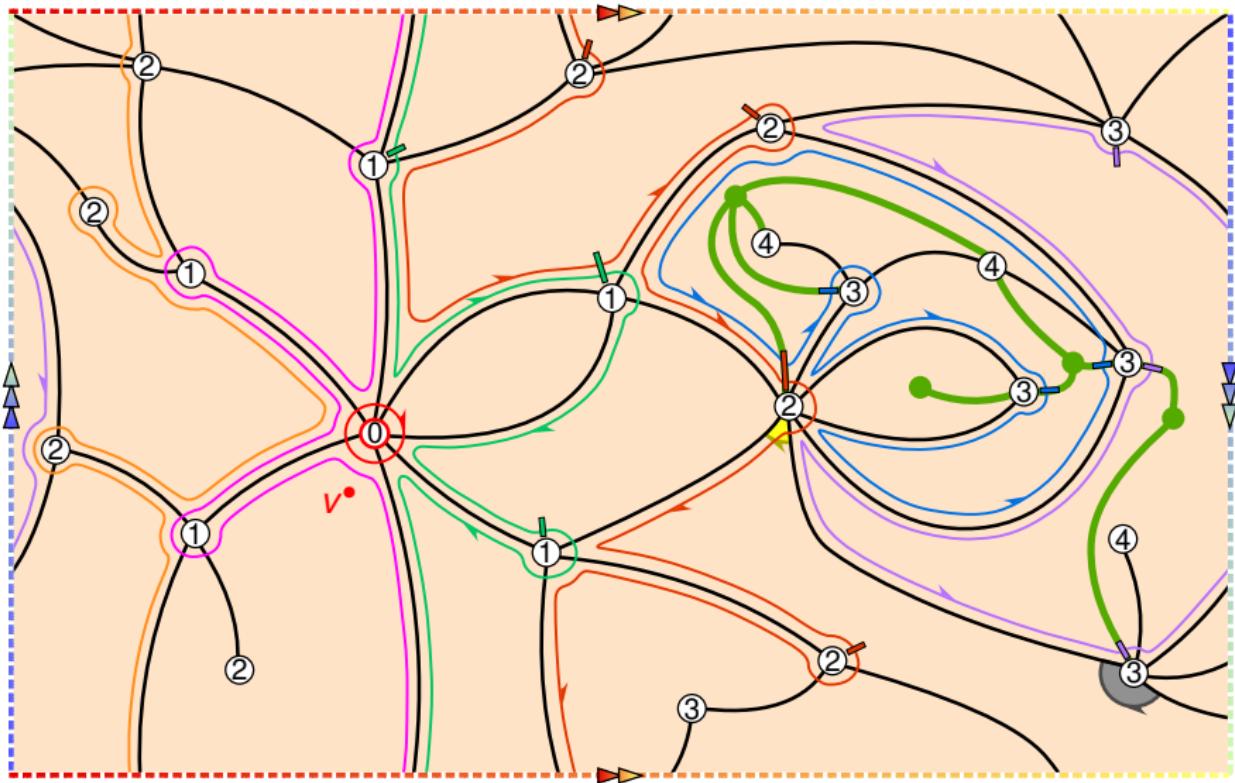
From pointed bipartite maps to unicellular mobiles



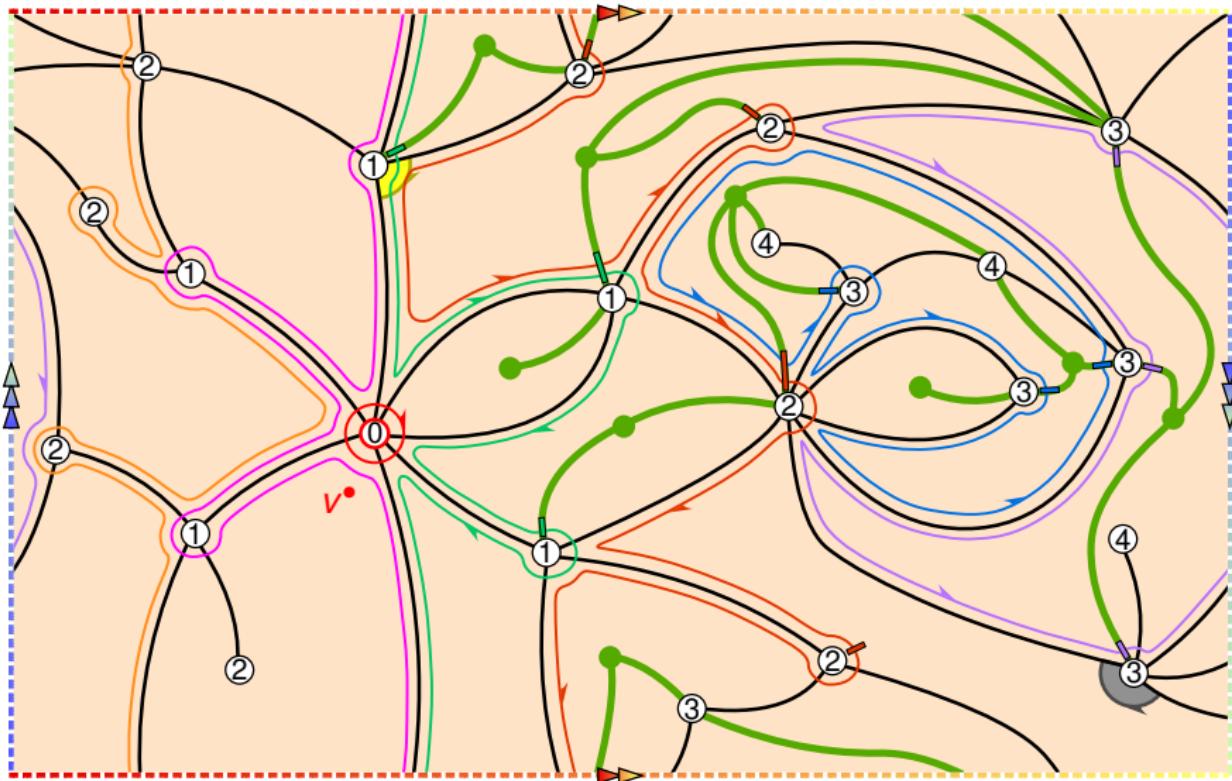
From pointed bipartite maps to unicellular mobiles



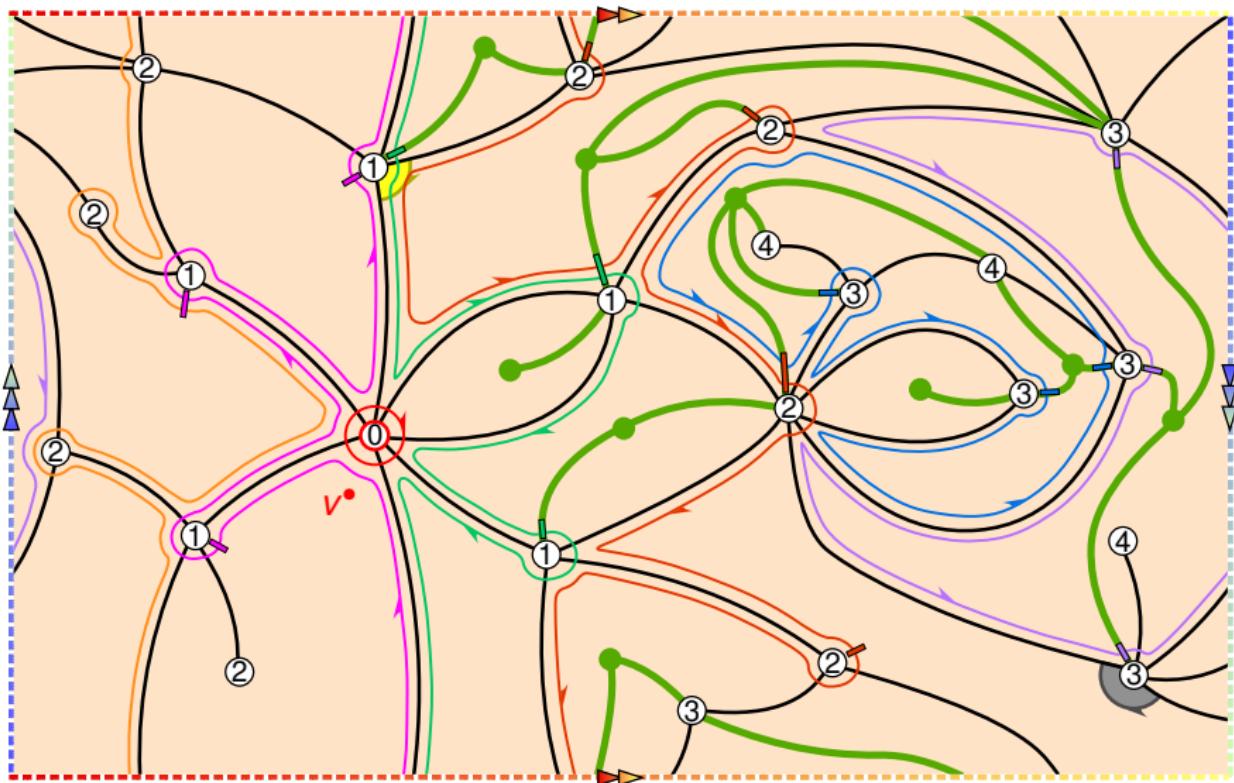
From pointed bipartite maps to unicellular mobiles



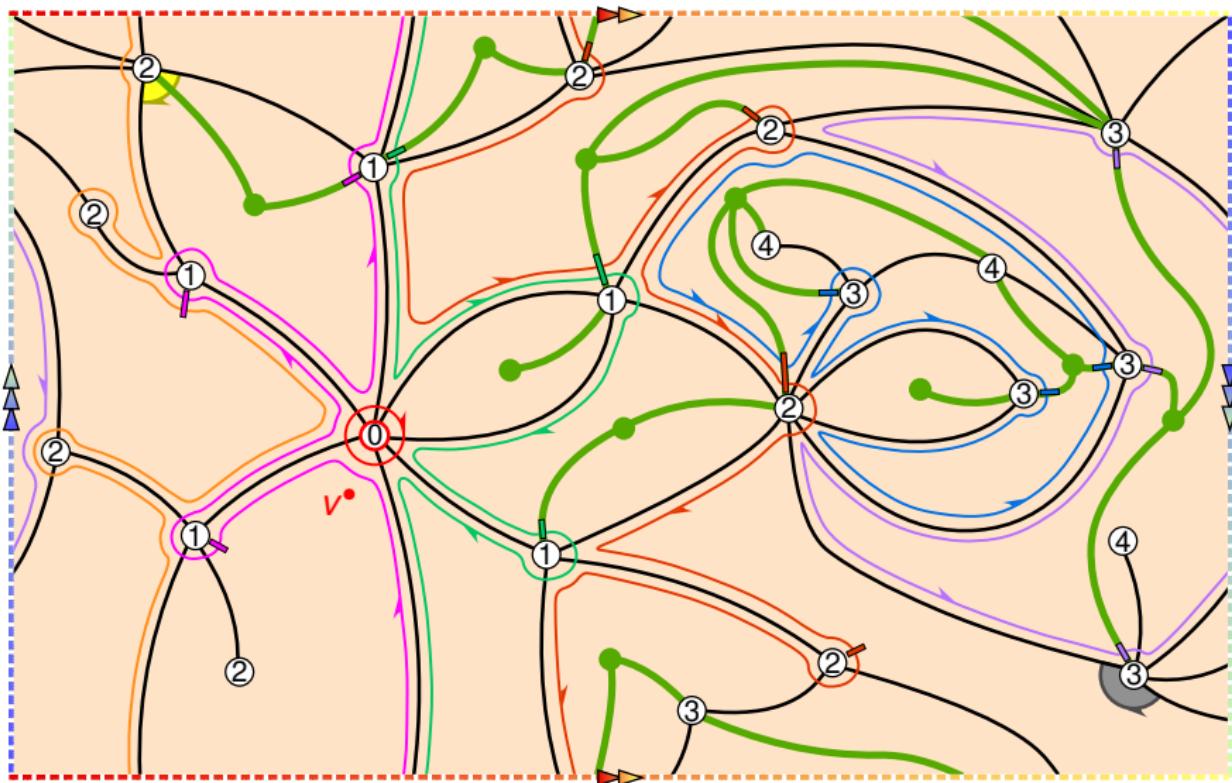
From pointed bipartite maps to unicellular mobiles



From pointed bipartite maps to unicellular mobiles



From pointed bipartite maps to unicellular mobiles



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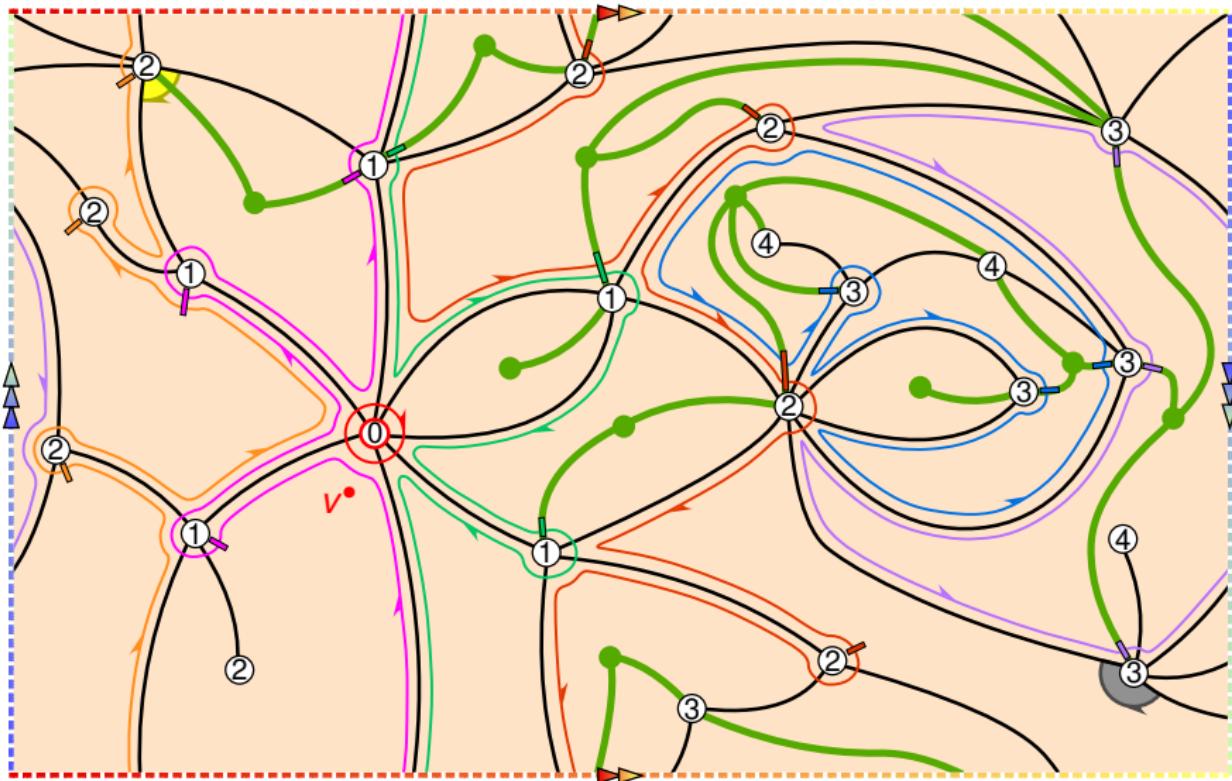
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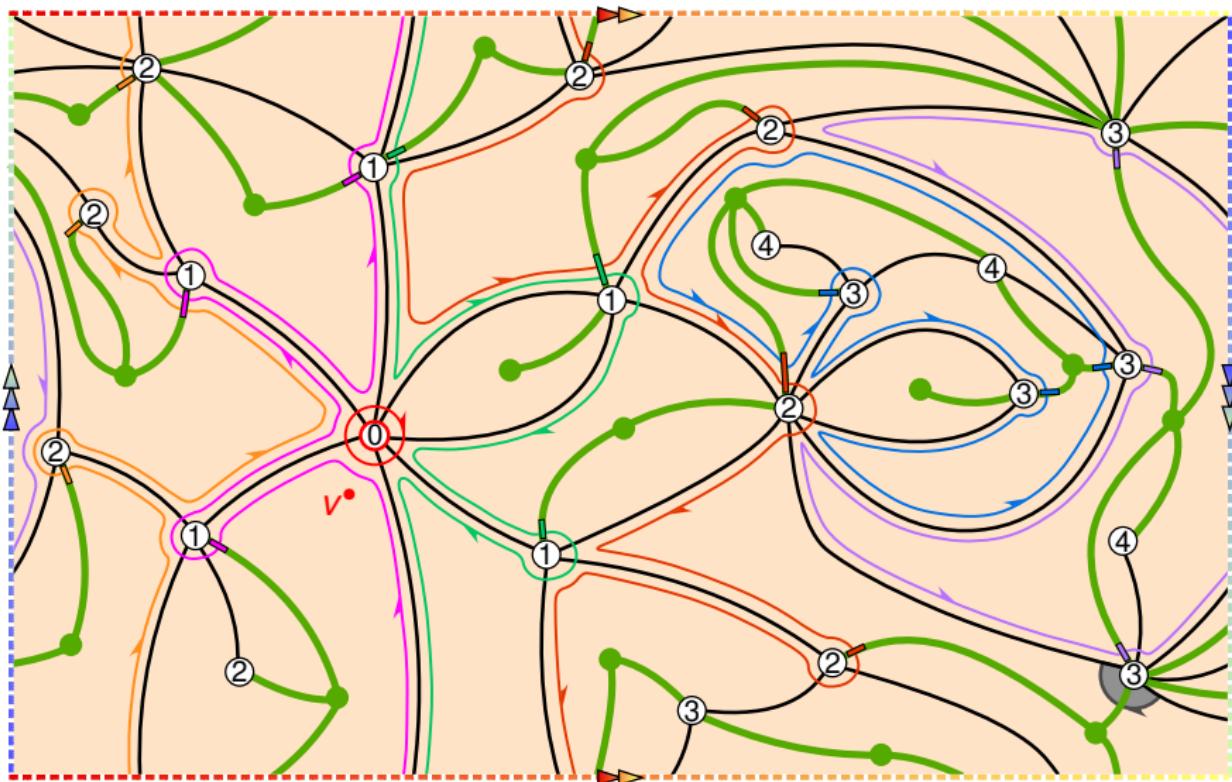
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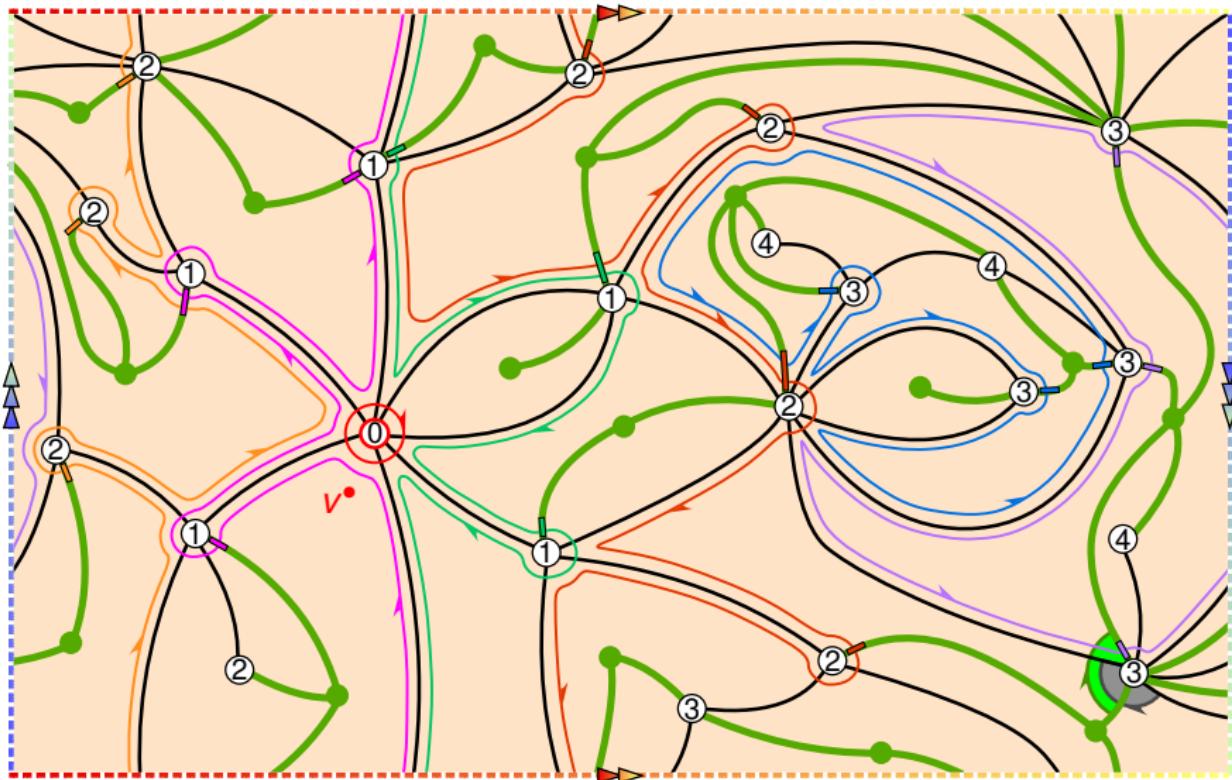
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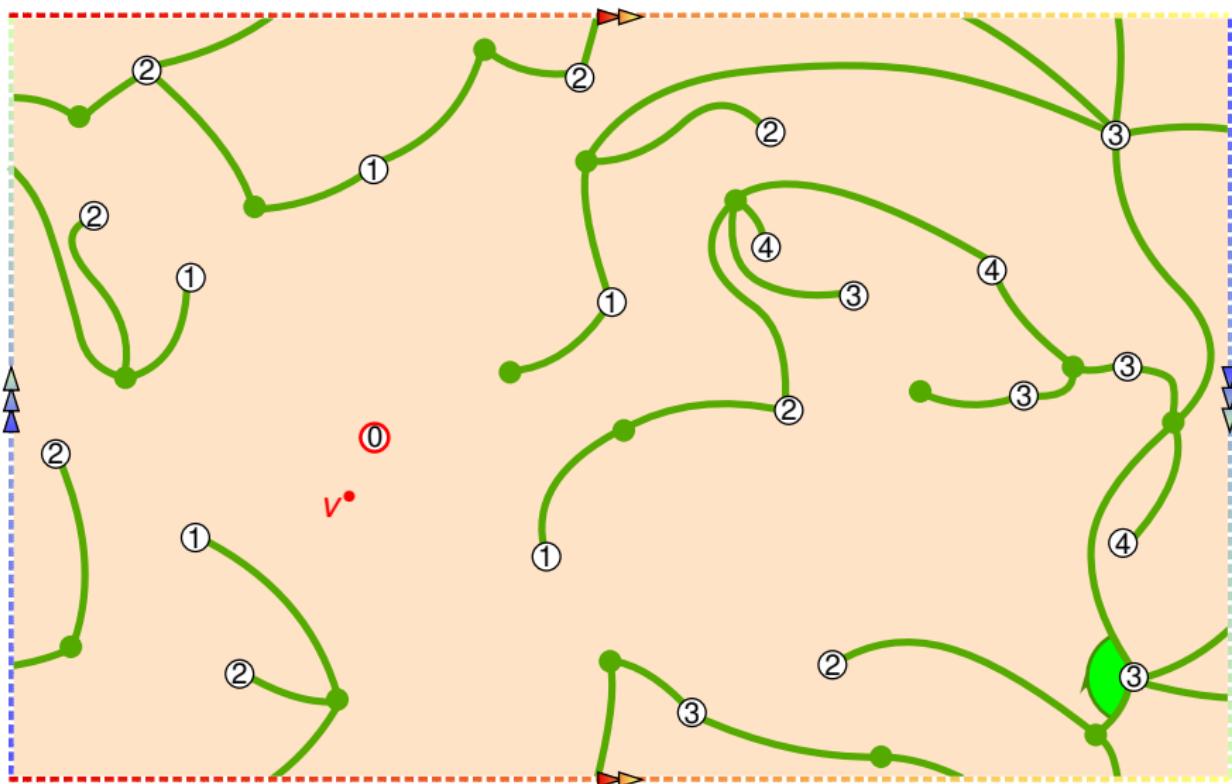
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From pointed bipartite maps to unicellular mobiles



From pointed bipartite maps to unicellular mobiles



Corresponding quantities

Proposition

Let $(\mathfrak{m}, v^\bullet)$ be a pointed bipartite map and (\mathfrak{u}, l) the corresponding well-labeled unicellular mobile. Then

- $V(\mathfrak{m}) = V_o(\mathfrak{u}) \sqcup \{v^\bullet\}$ and, for $v \in V_o(\mathfrak{u})$, $l(v) = d_{\mathfrak{m}}(v, v^\bullet)$;
- the faces of \mathfrak{m} correspond to $V_\bullet(\mathfrak{u})$: moreover, the degree of a face of \mathfrak{m} is twice the degree of the corresponding vertex in $V_\bullet(\mathfrak{u})$;
- the maps \mathfrak{m} and \mathfrak{u} have the same number of edges;
- among the edges of \mathfrak{m} in a white corner of \mathfrak{u} , exactly one is directed toward v^\bullet .

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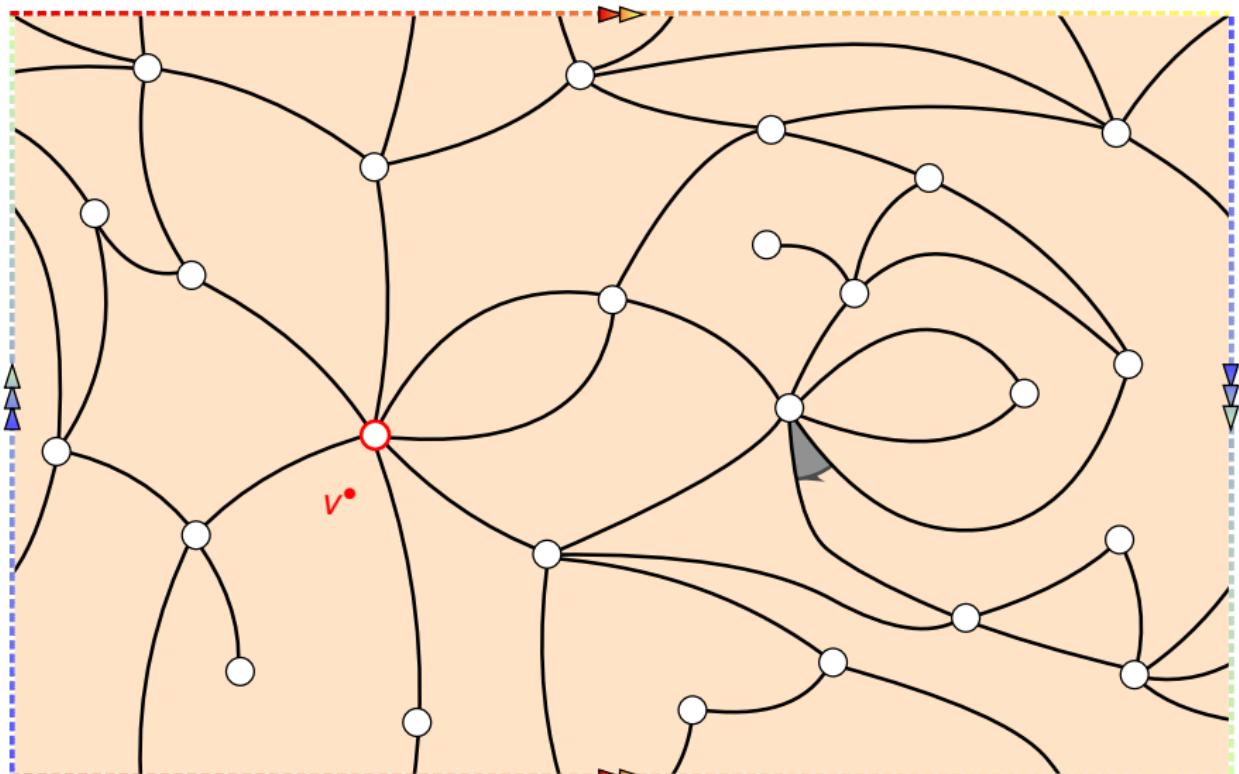
Degree prescriptions

Specializations

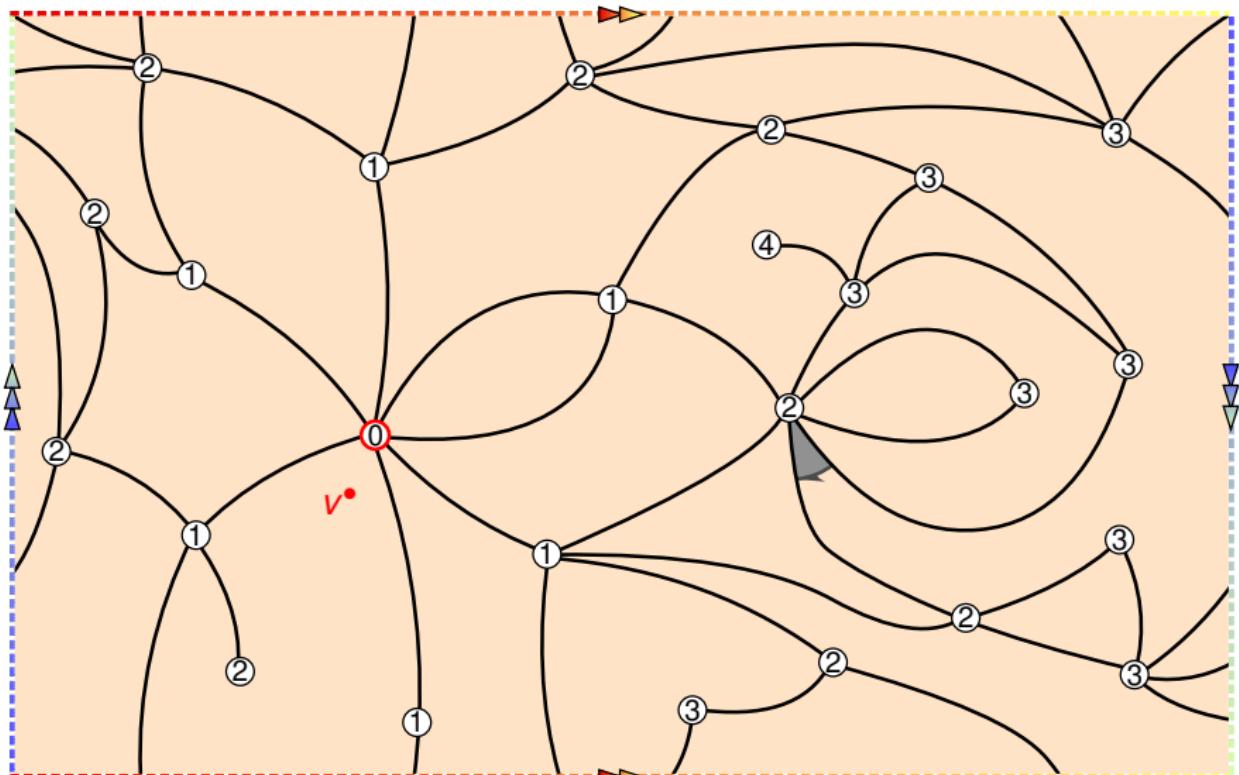
The previous construction specializes into a bijection between

- bipartite maps with n faces marked $1, 2, \dots, n$ and such that, for $1 \leq i \leq n$, the face marked i has degree $2\alpha_i$;
- pairs of a sign $+$ or $-$ and a well-labeled unicellular mobile with n green vertices marked $1, 2, \dots, n$ and such that, for $1 \leq i \leq n$, the green vertex marked i has degree α_i .

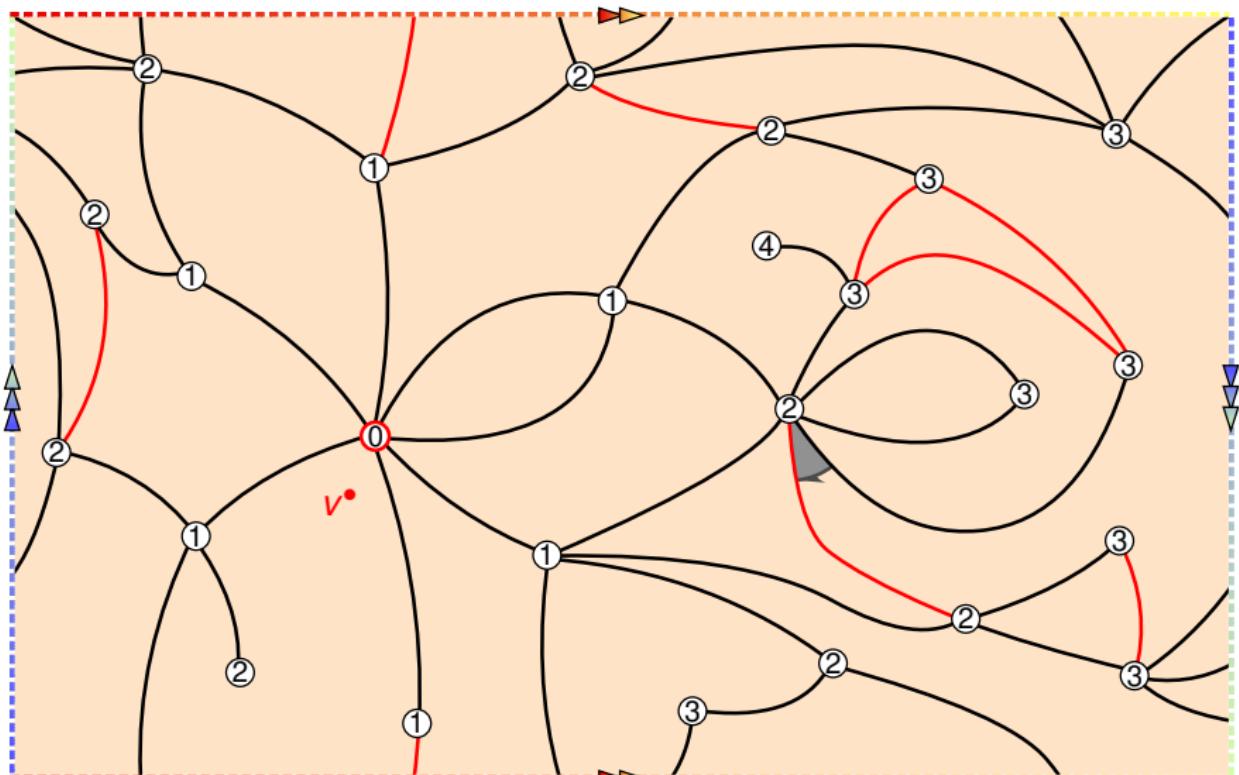
The construction for nonbipartite maps



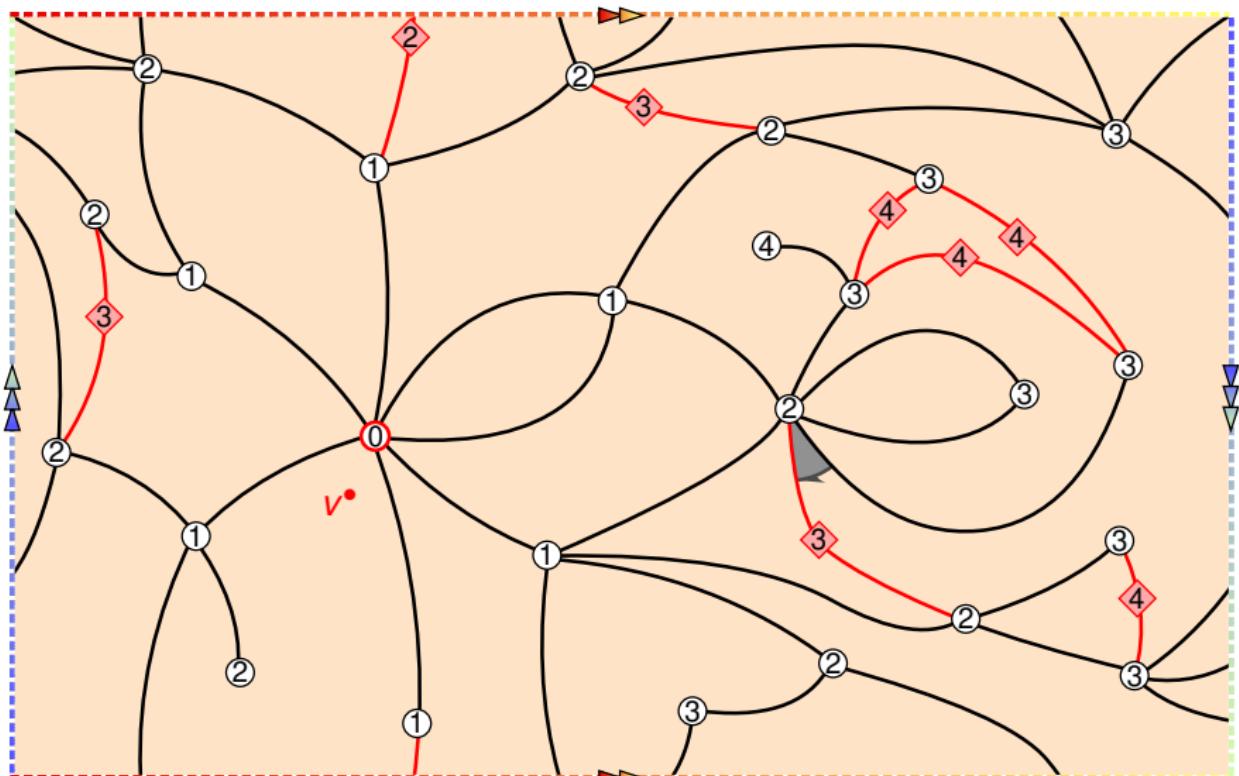
The construction for nonbipartite maps



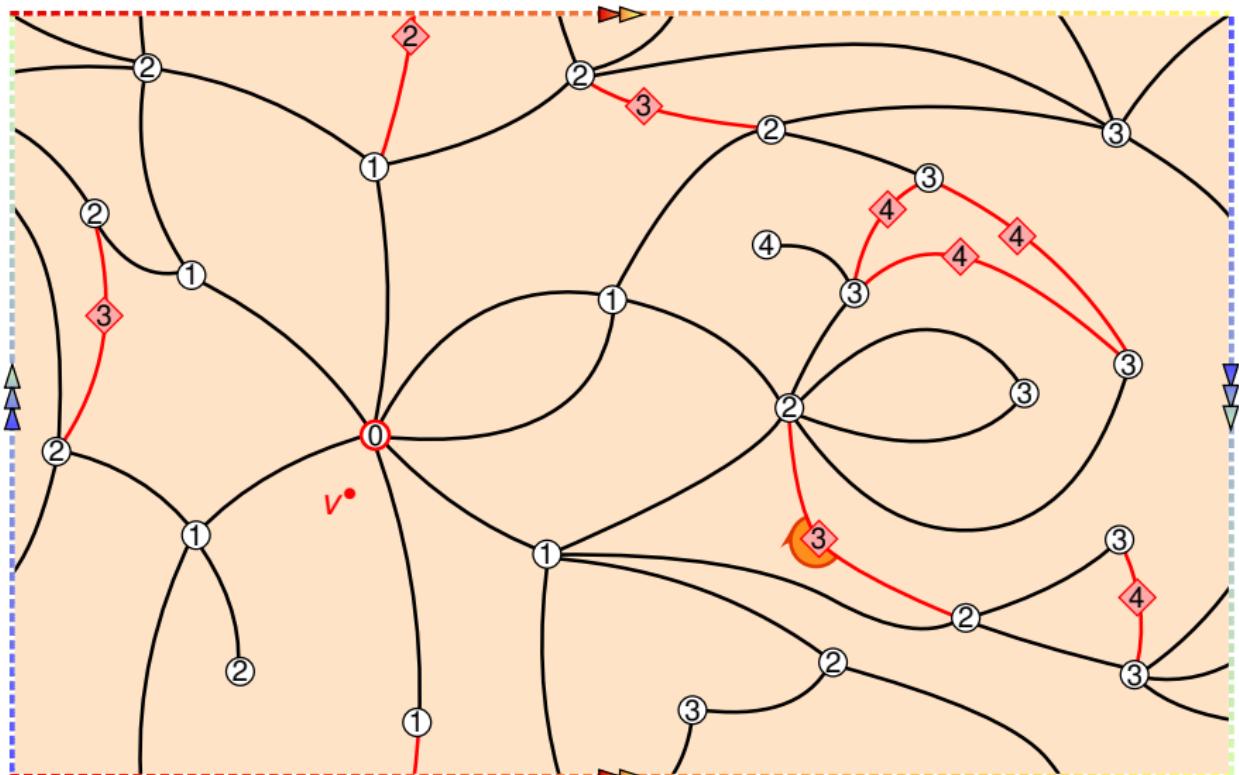
The construction for nonbipartite maps



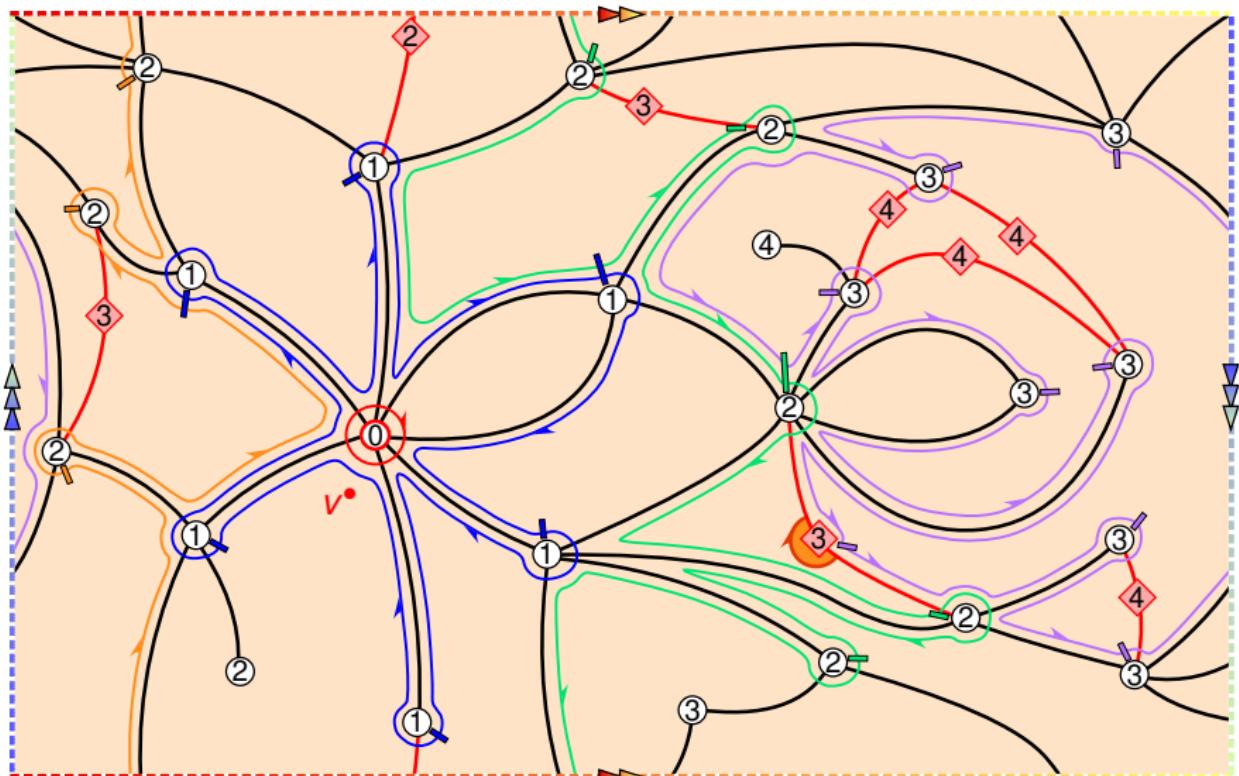
The construction for nonbipartite maps



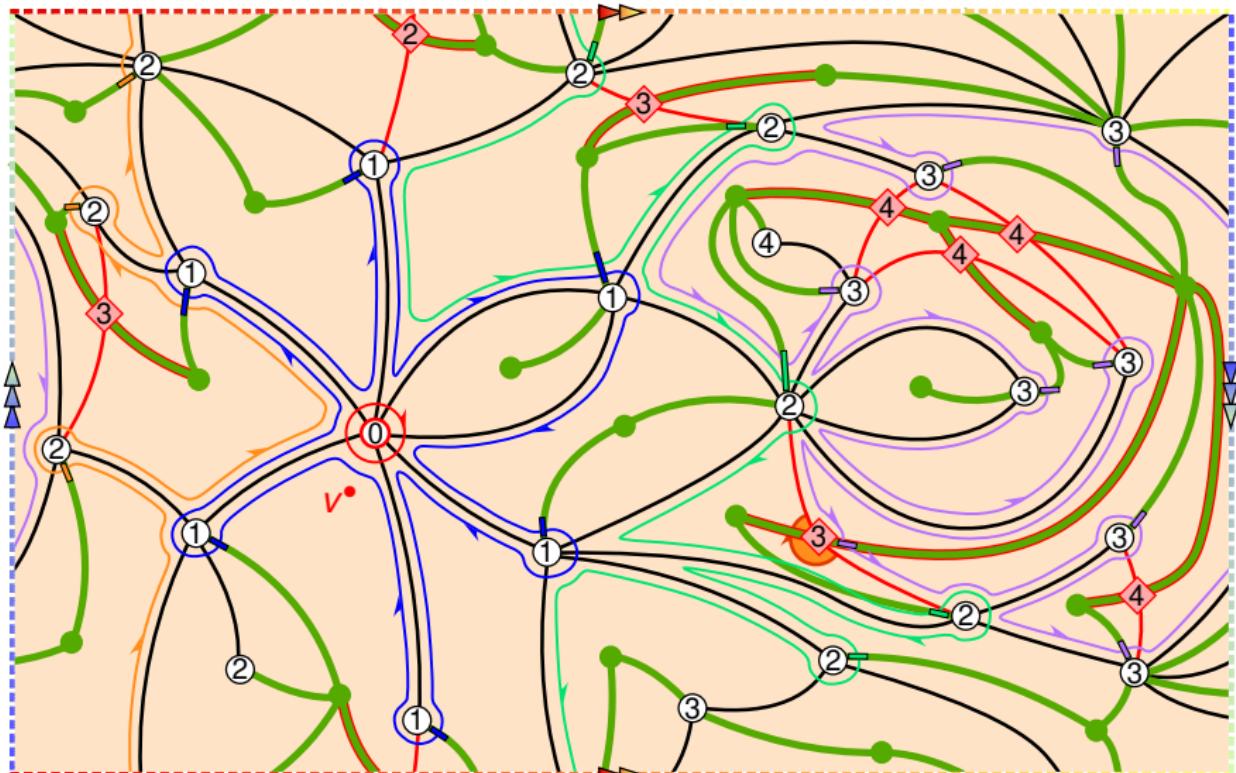
The construction for nonbipartite maps



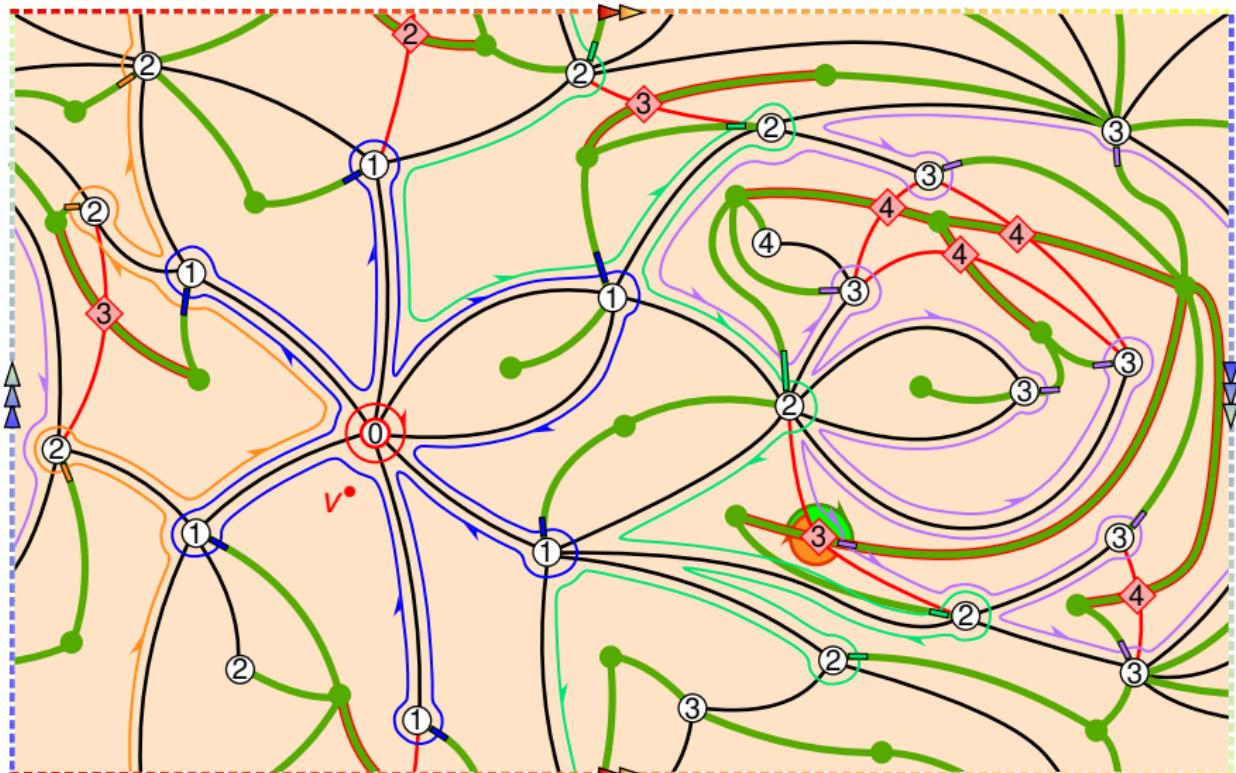
The construction for nonbipartite maps



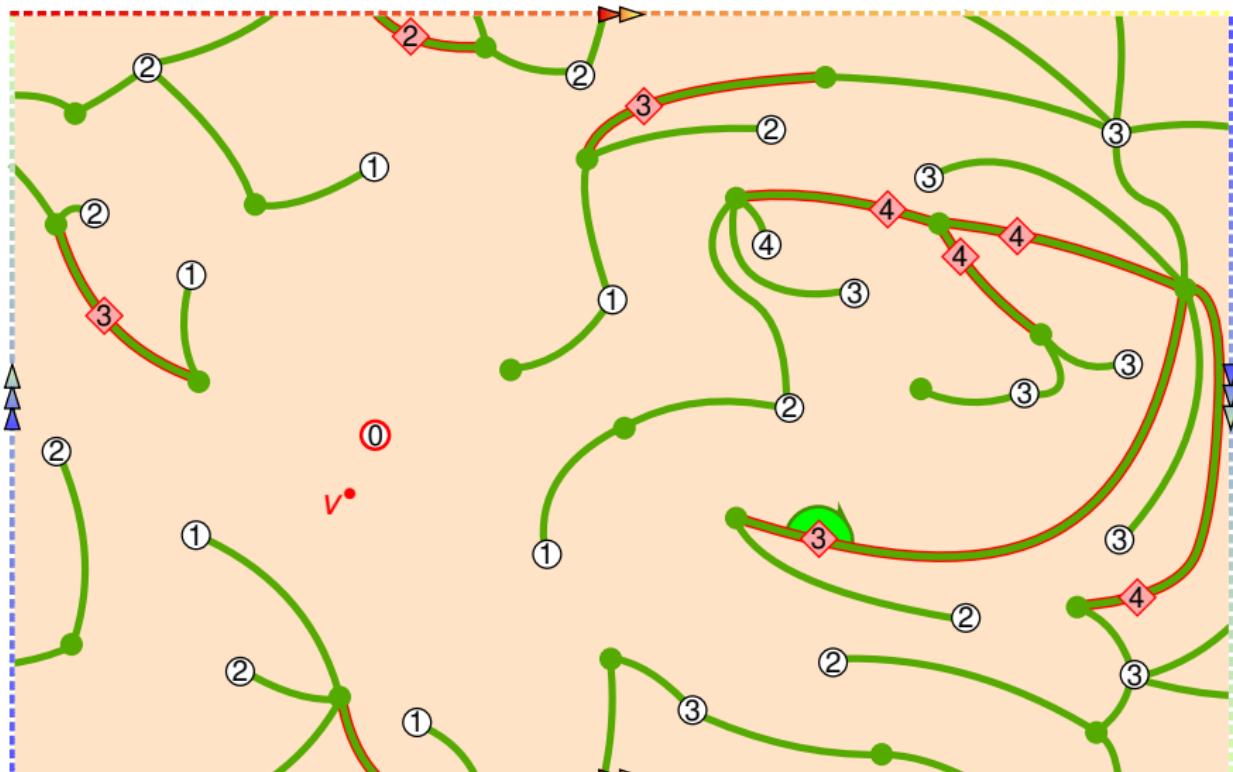
The construction for nonbipartite maps



The construction for nonbipartite maps



The construction for nonbipartite maps



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Well-labeled unicellular maps

Proposition

A labeled unicellular mobile whose green vertices all have degree 2 is well labeled iff the labels of neighboring vertices differ by at most 1.

Well-labeled unicellular maps

Proposition

A labeled unicellular mobile whose green vertices all have degree 2 is well labeled iff the labels of neighboring vertices differ by at most 1.

In fact, no matter how we orient the corners in the definition of successors, a labeled unicellular mobile whose green vertices all have degree 2 is well labeled iff the labels of neighboring vertices differ by at most 1.

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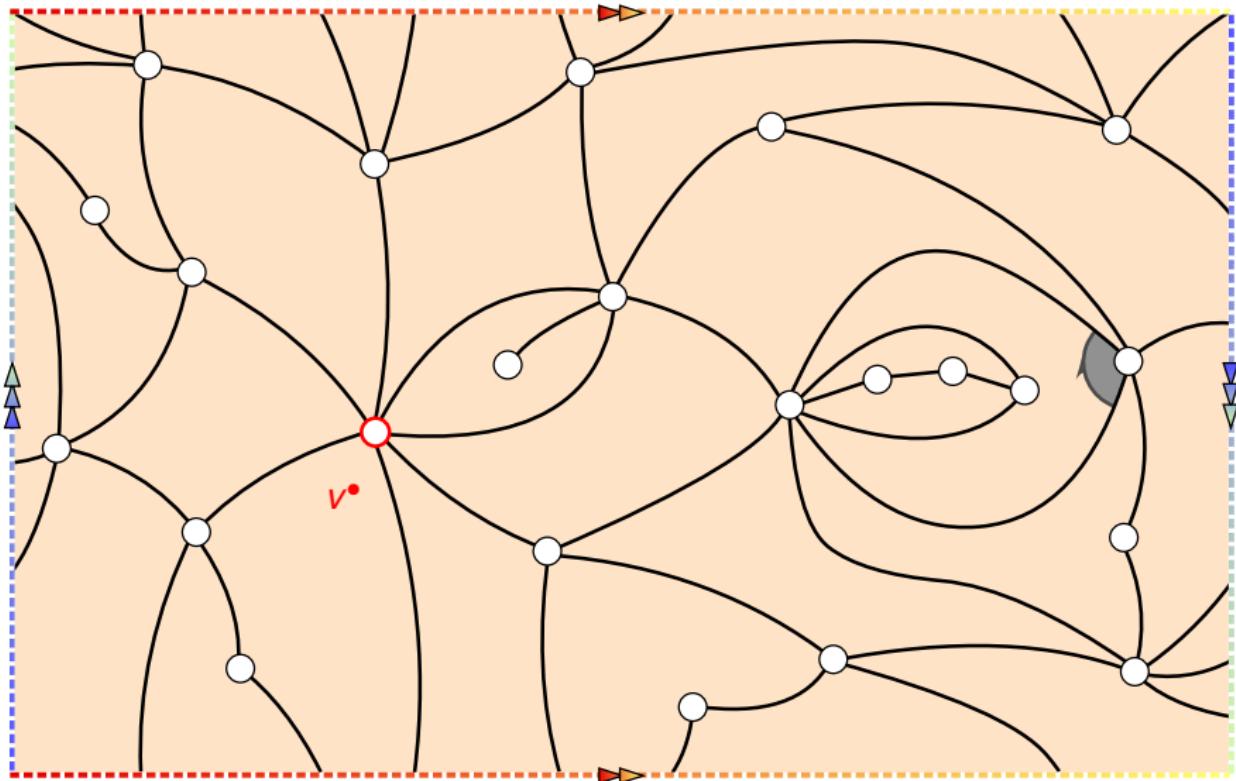
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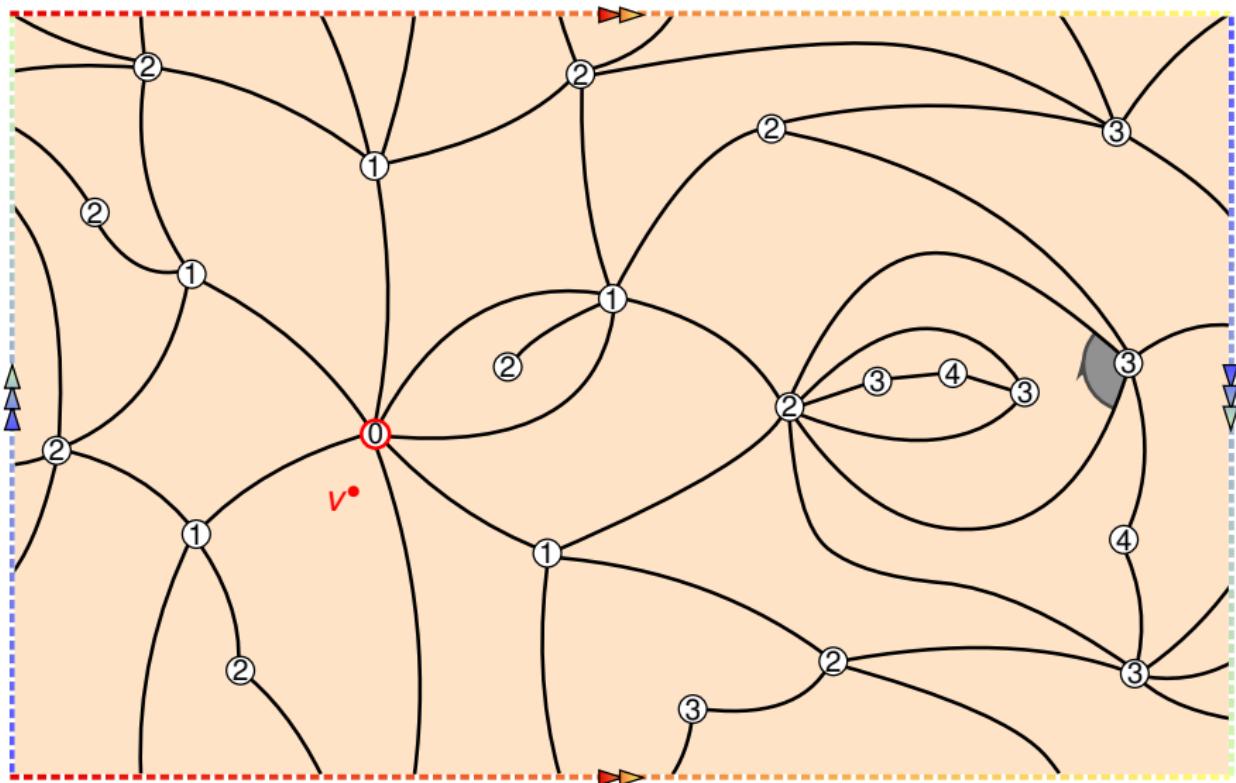
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Chapuy–Dolega bijection



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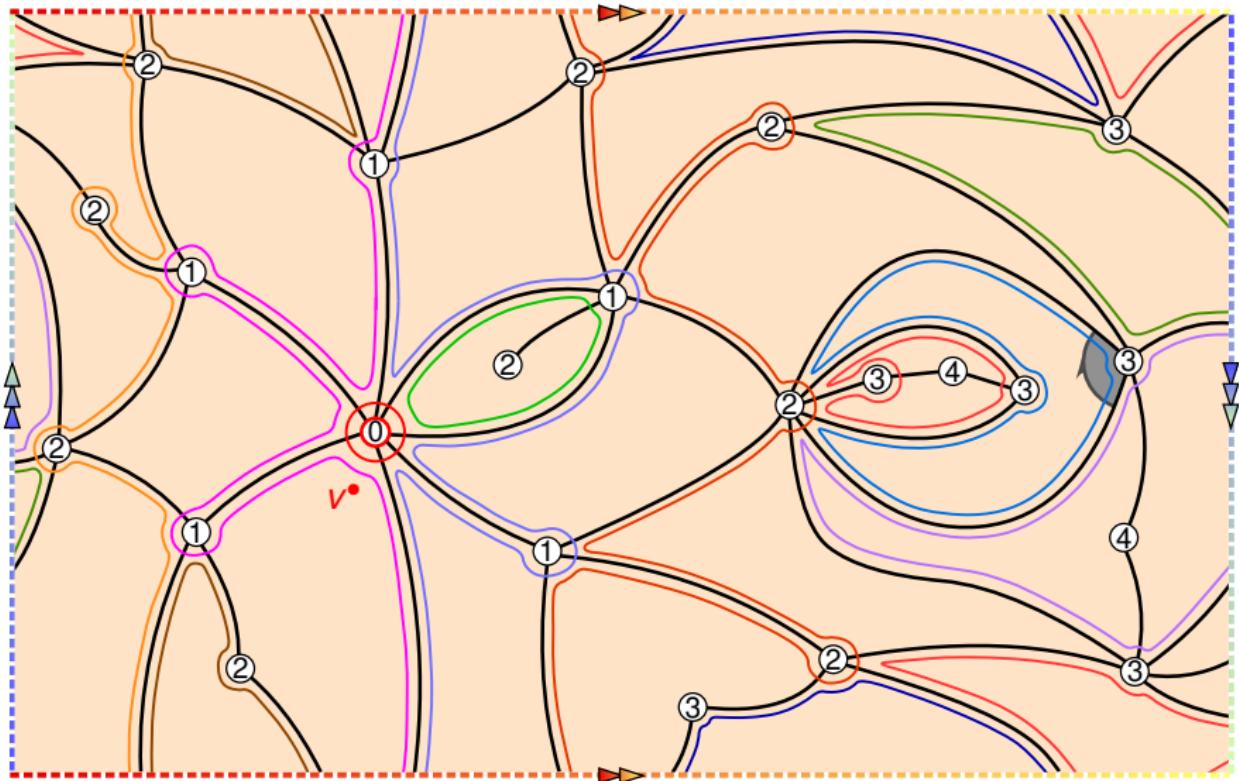
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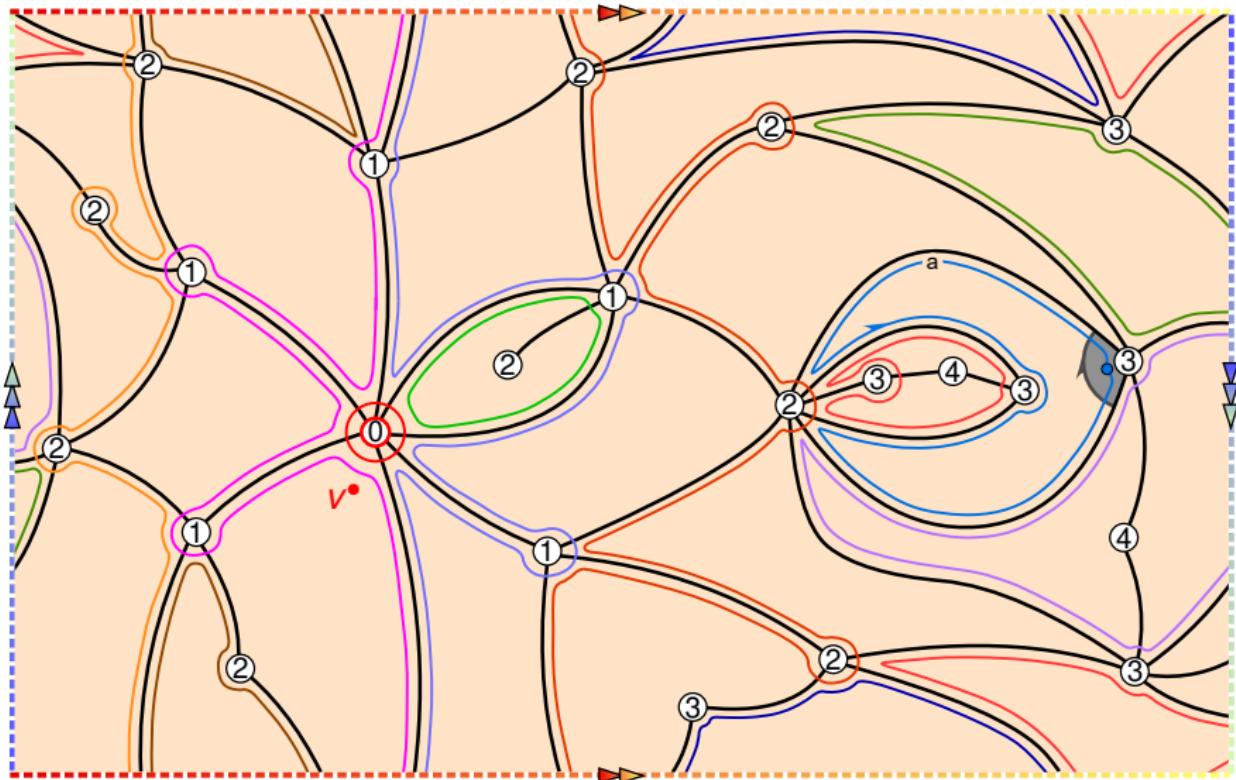
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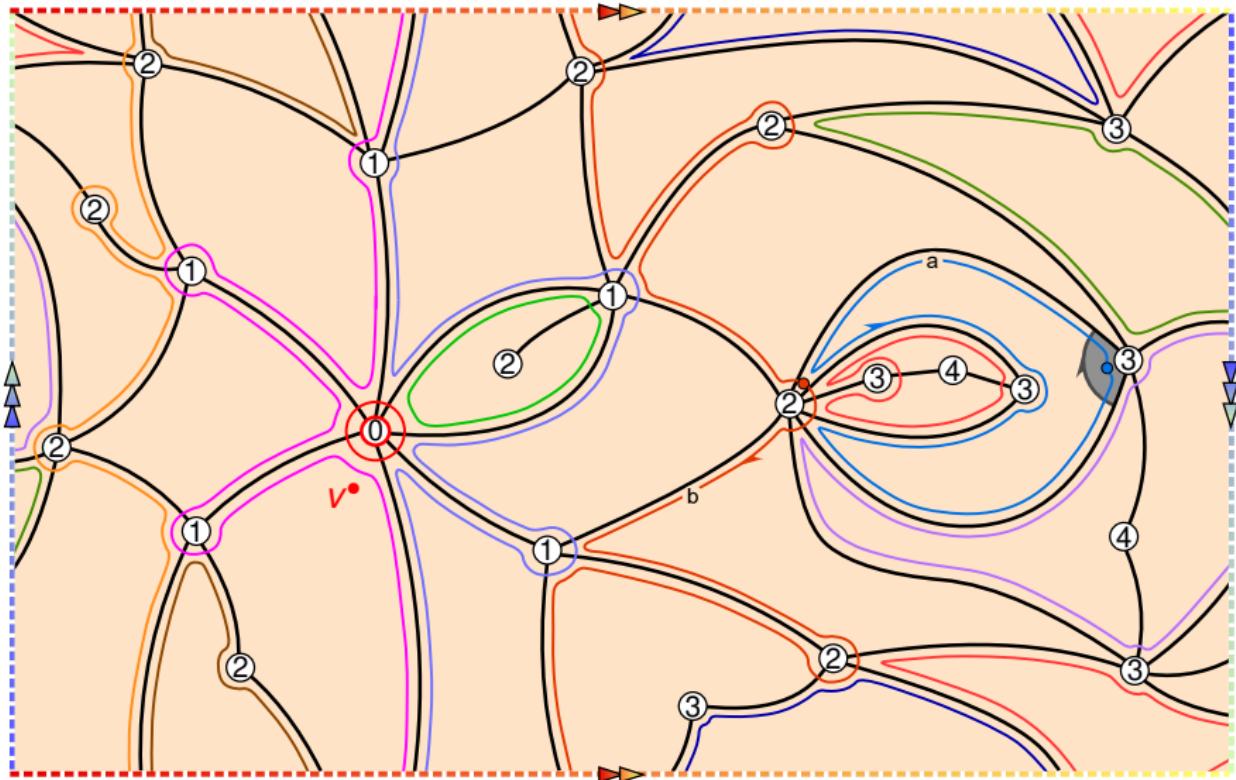
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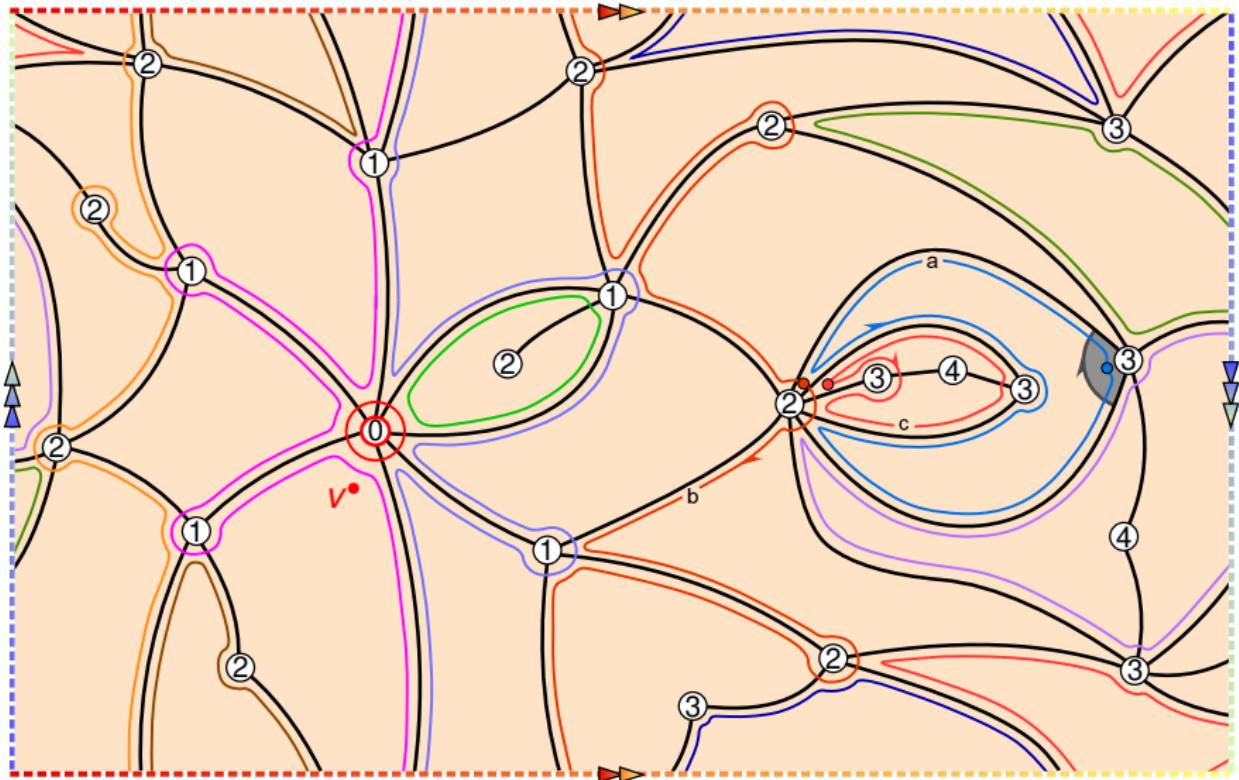
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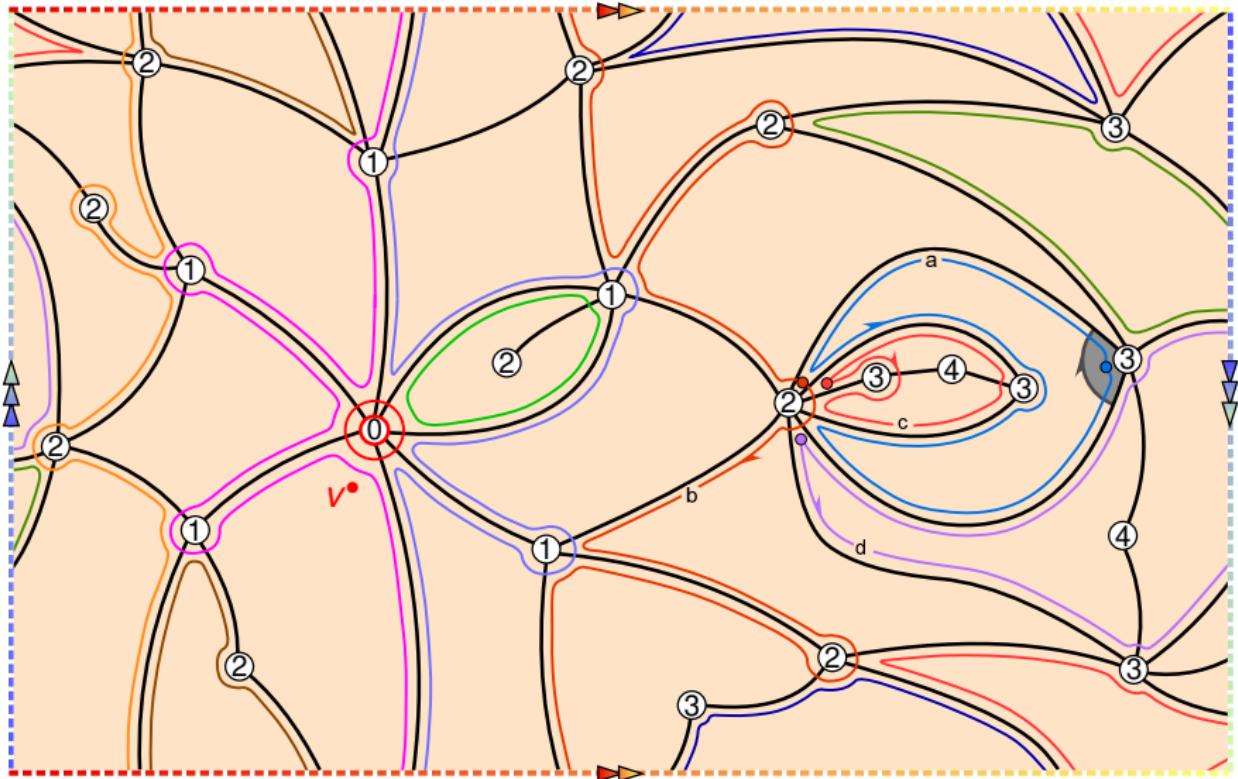
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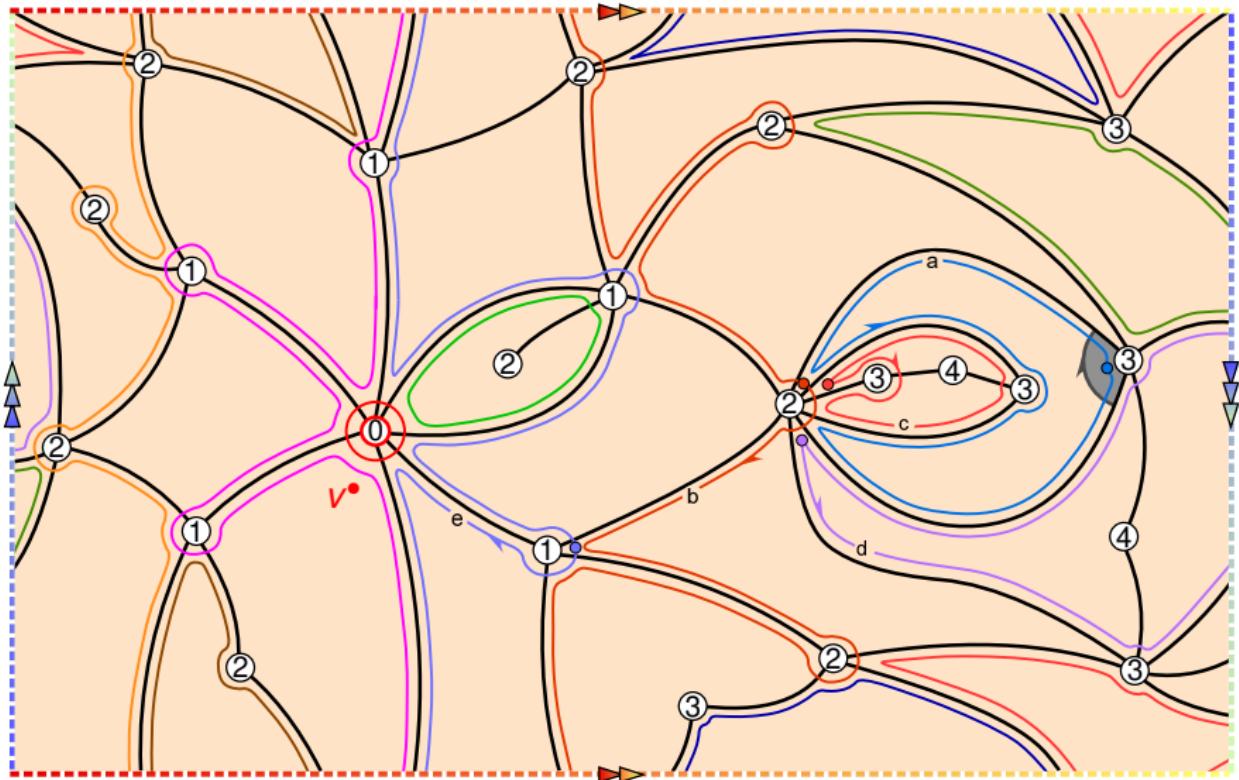
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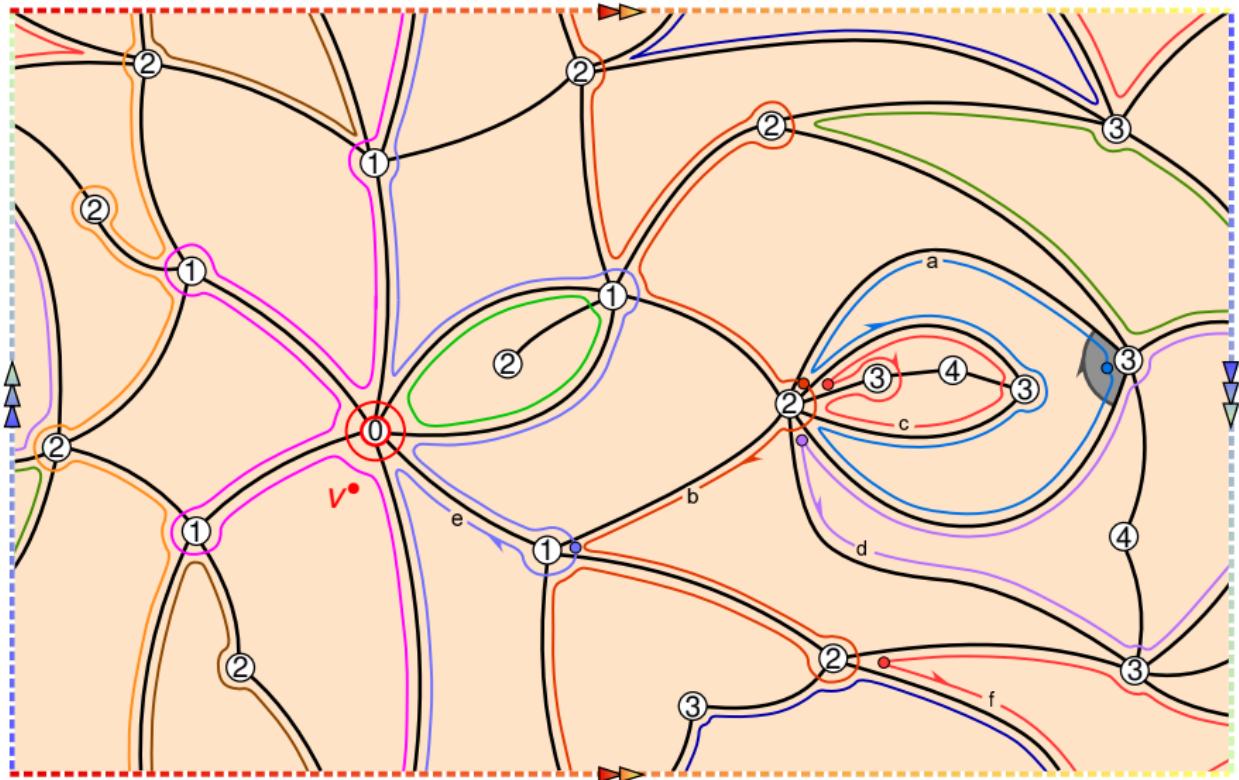
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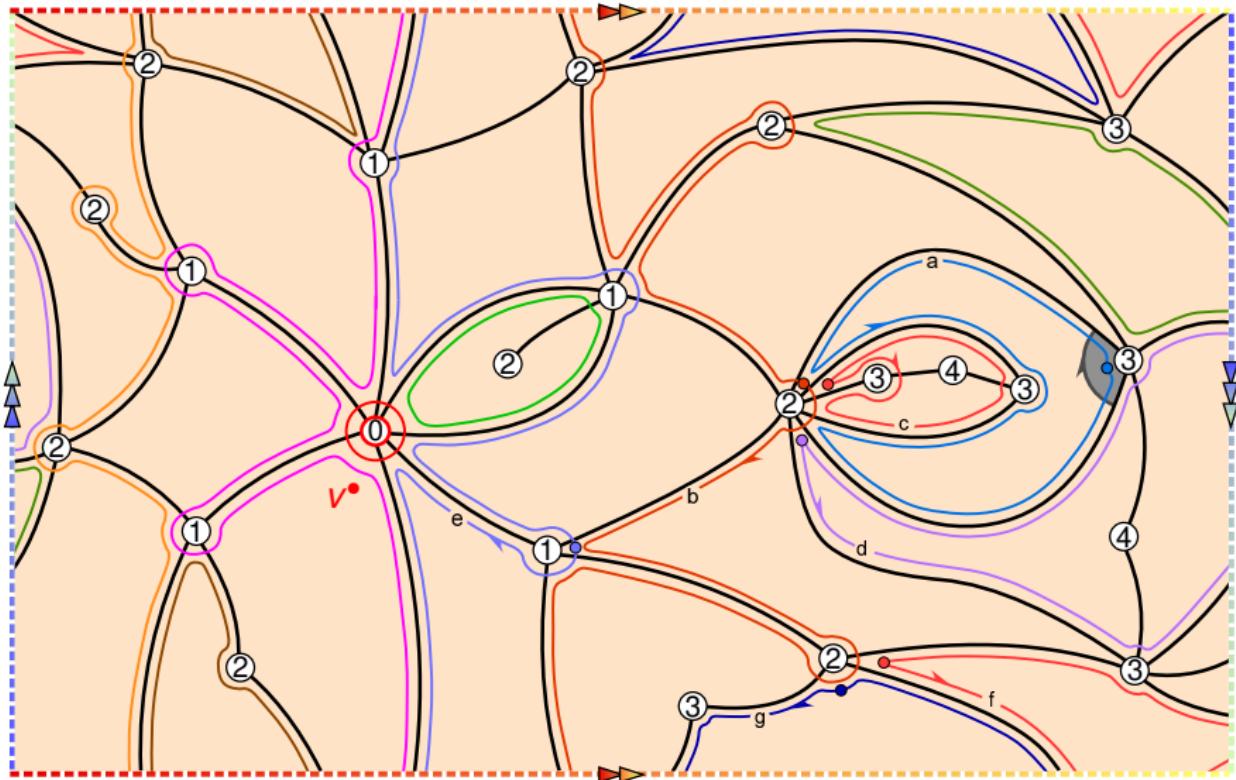
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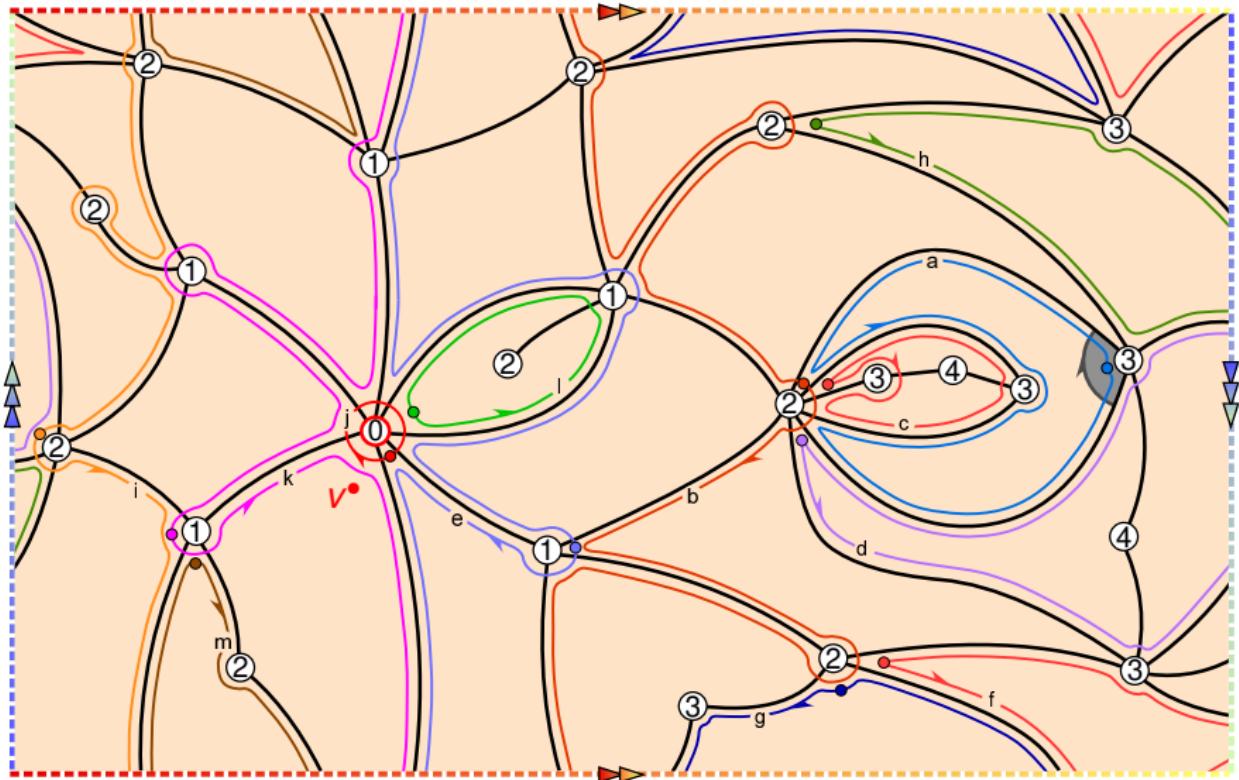
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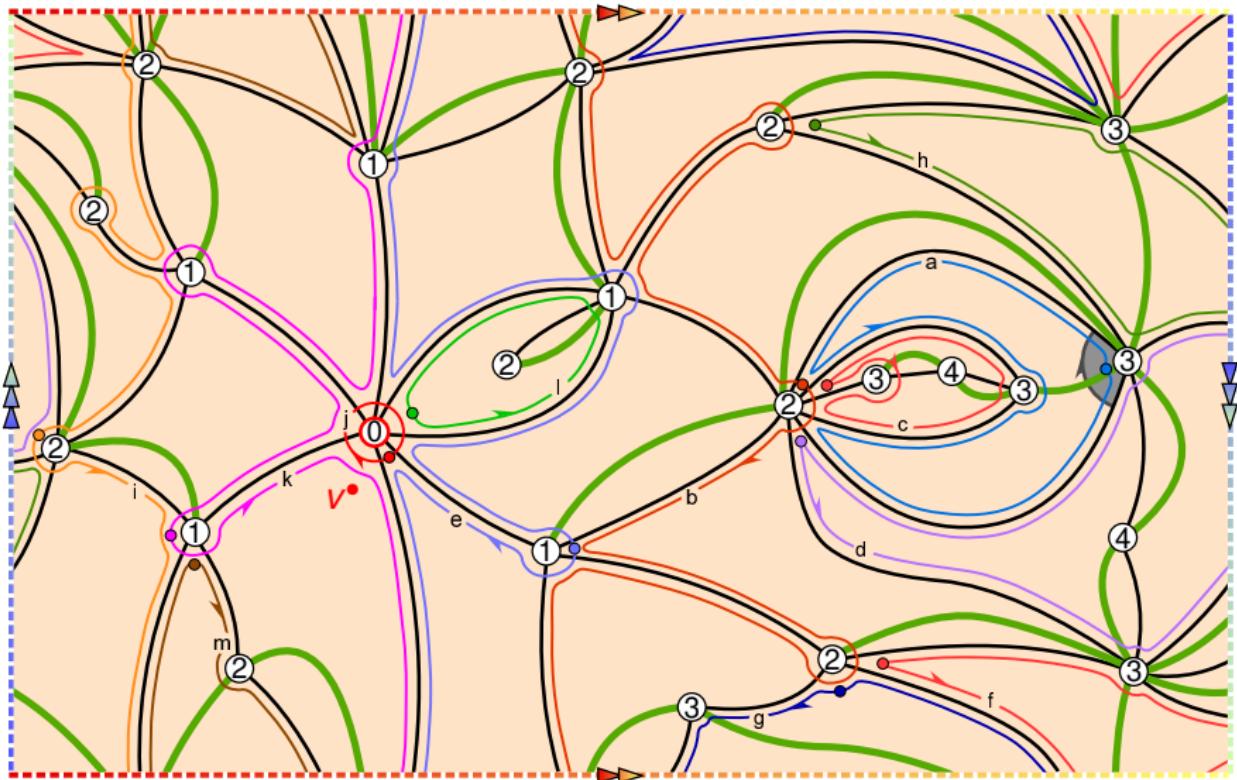
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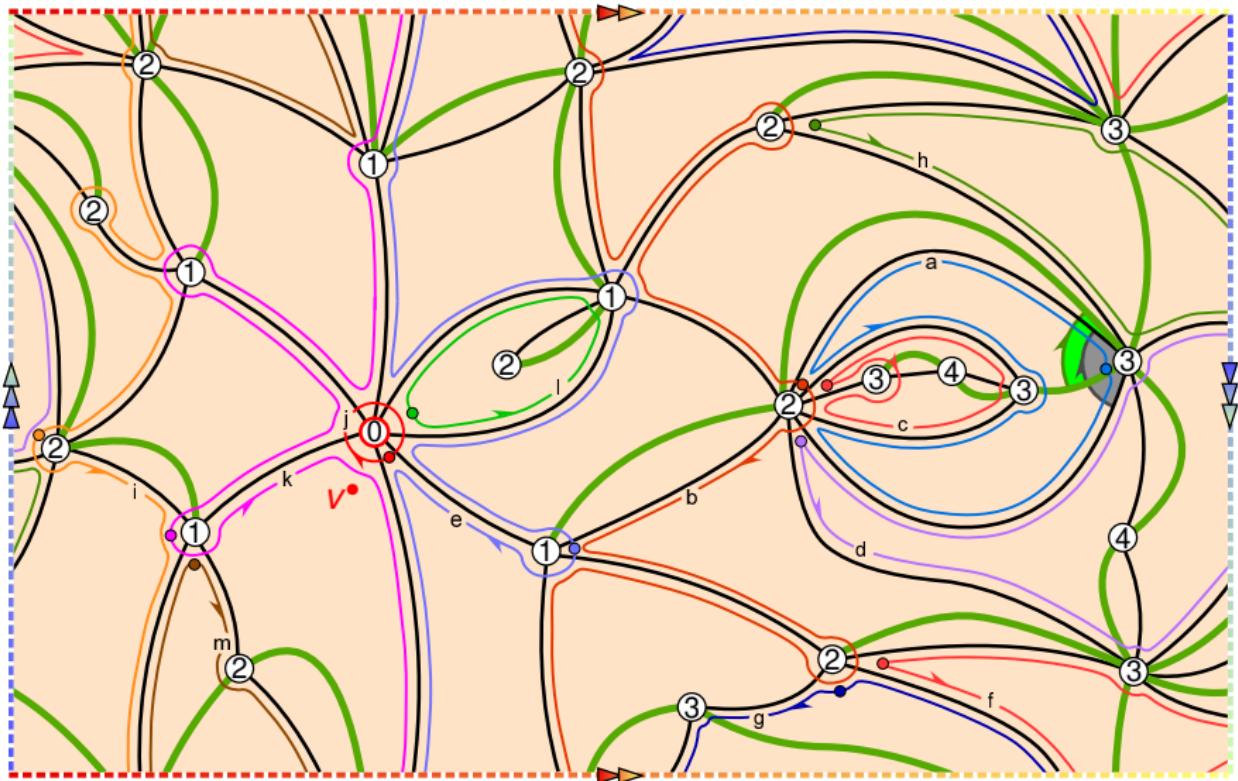
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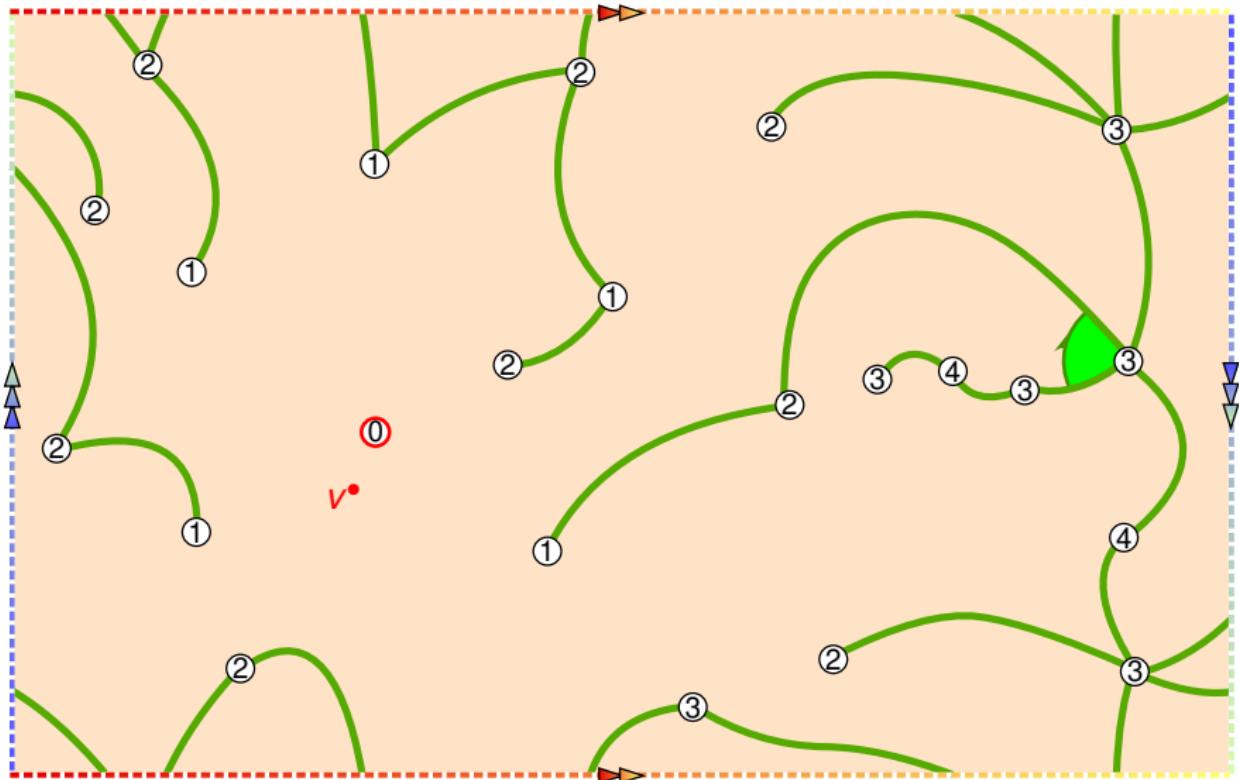
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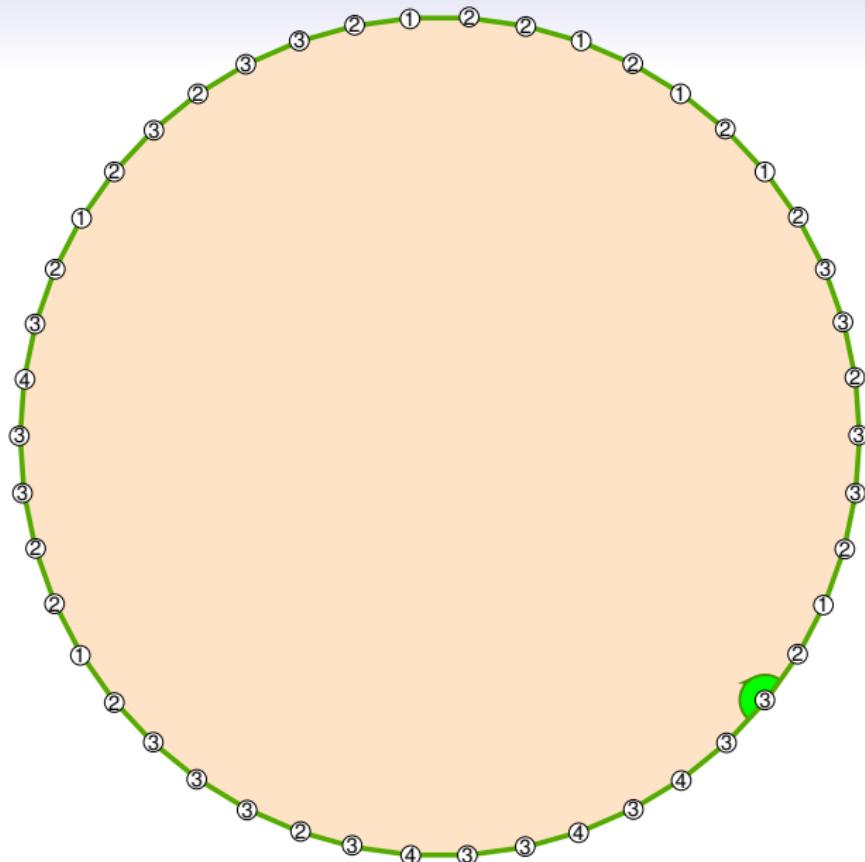
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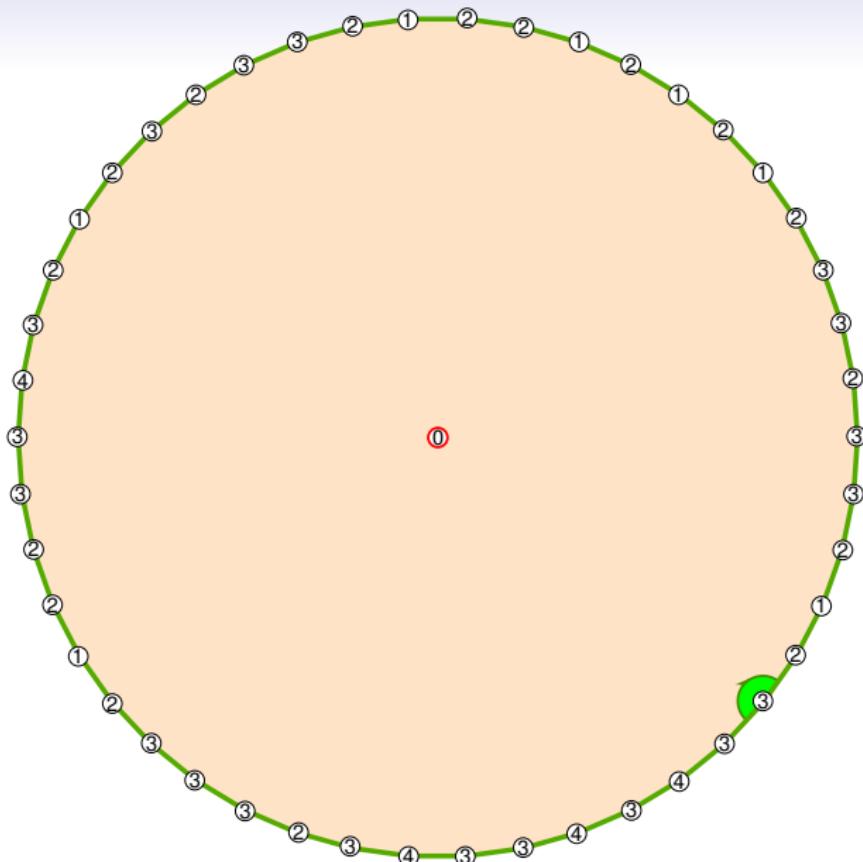
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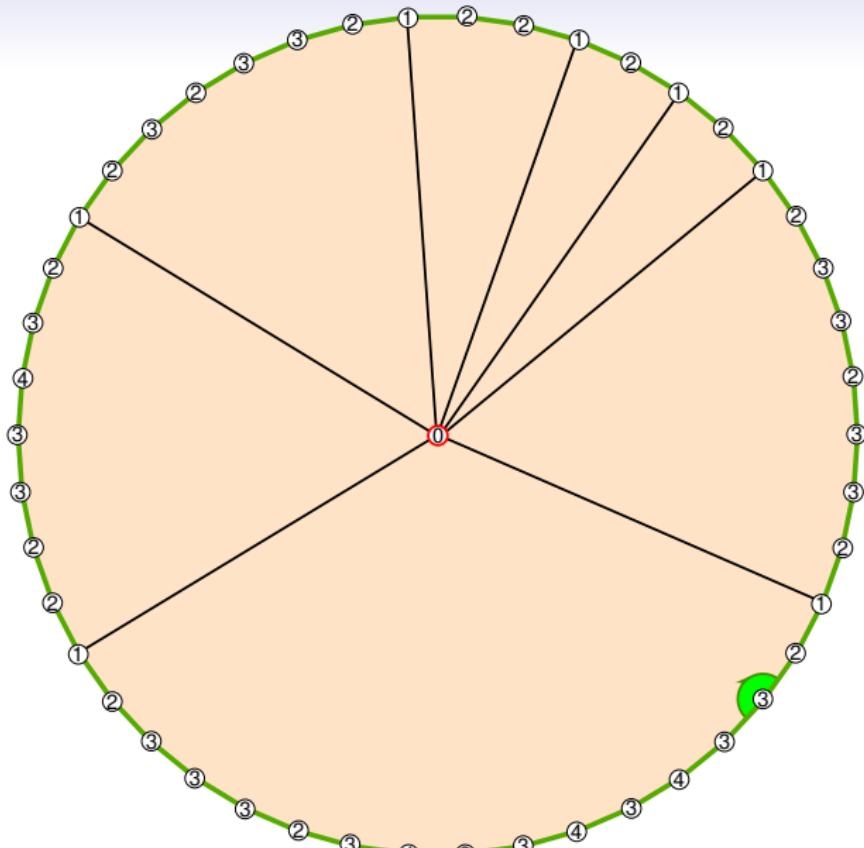
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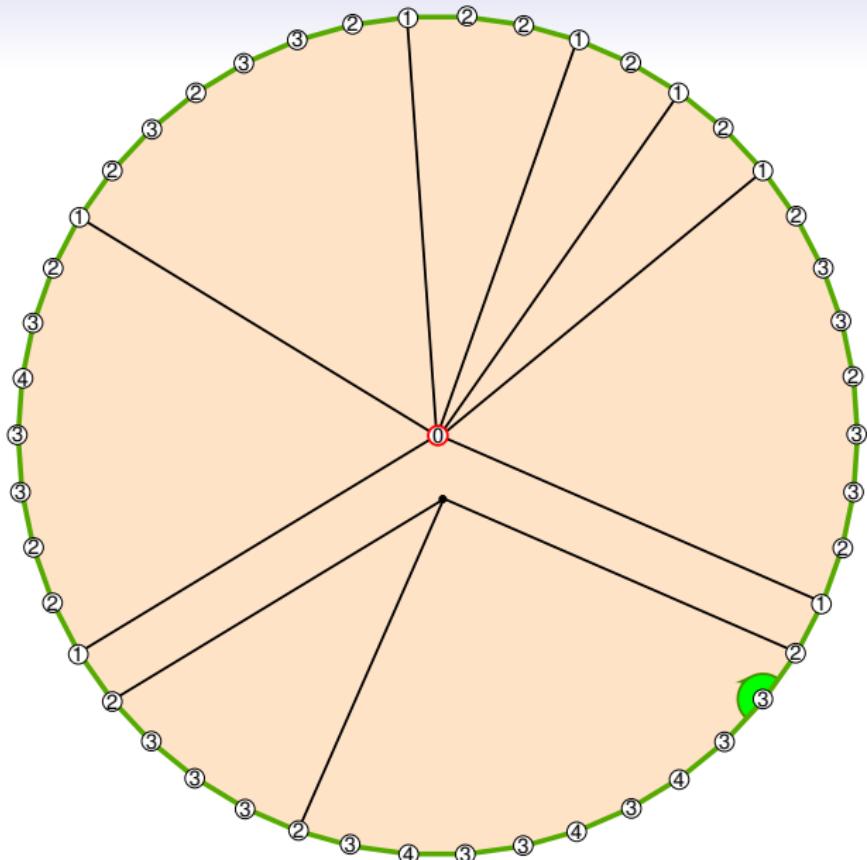
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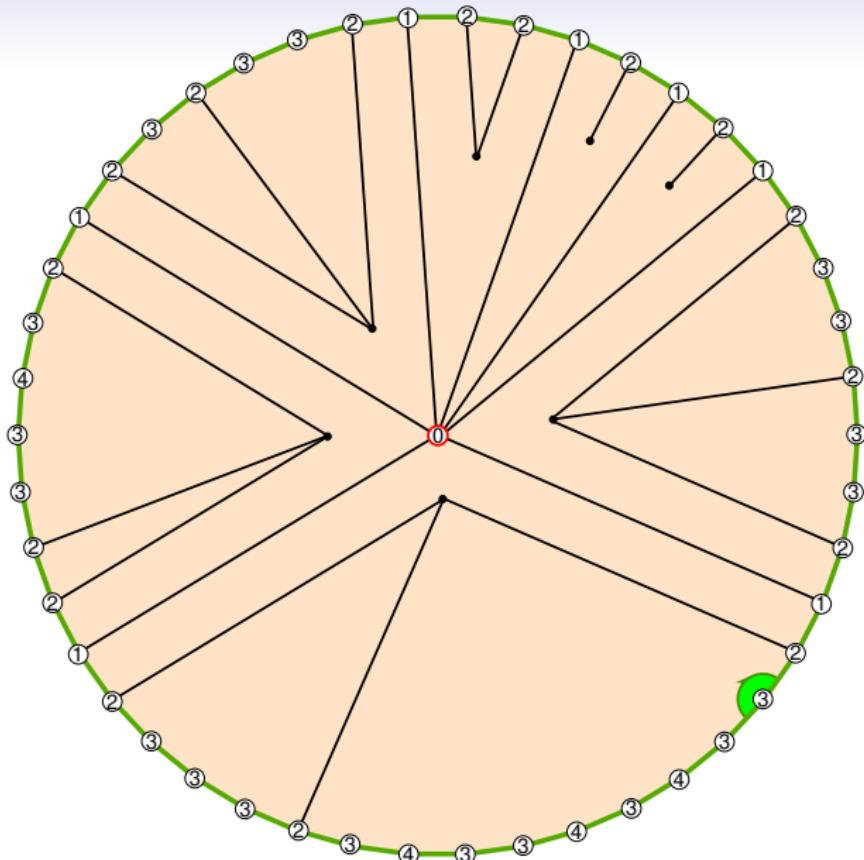
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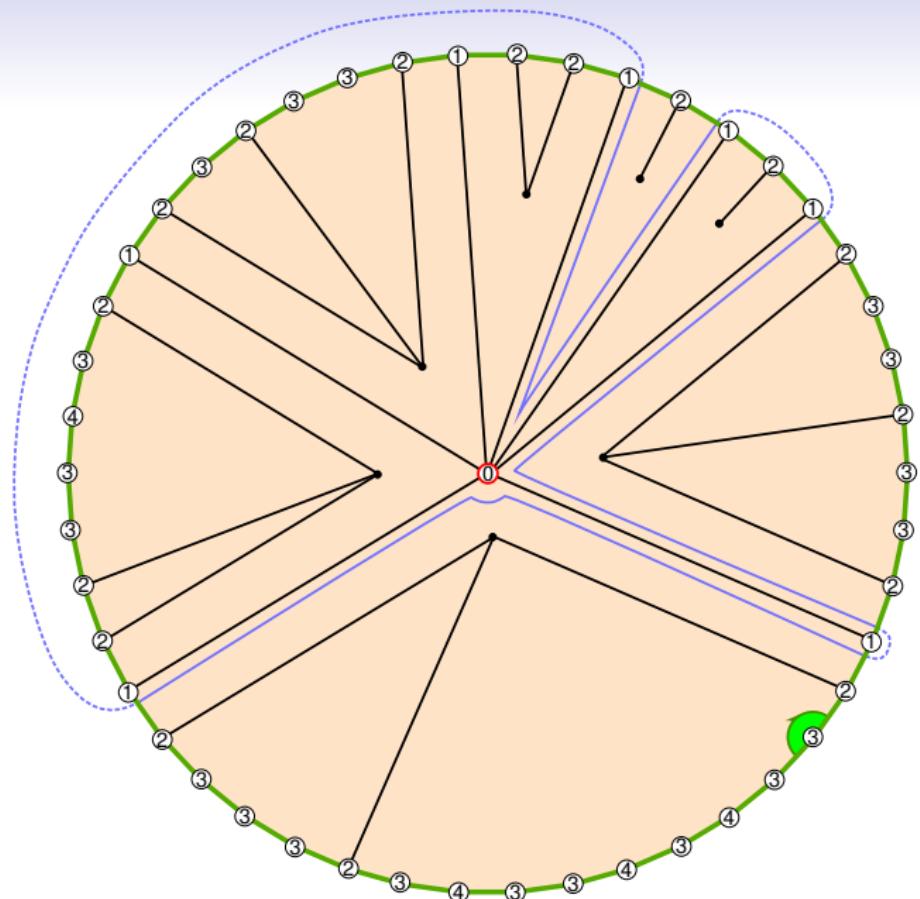
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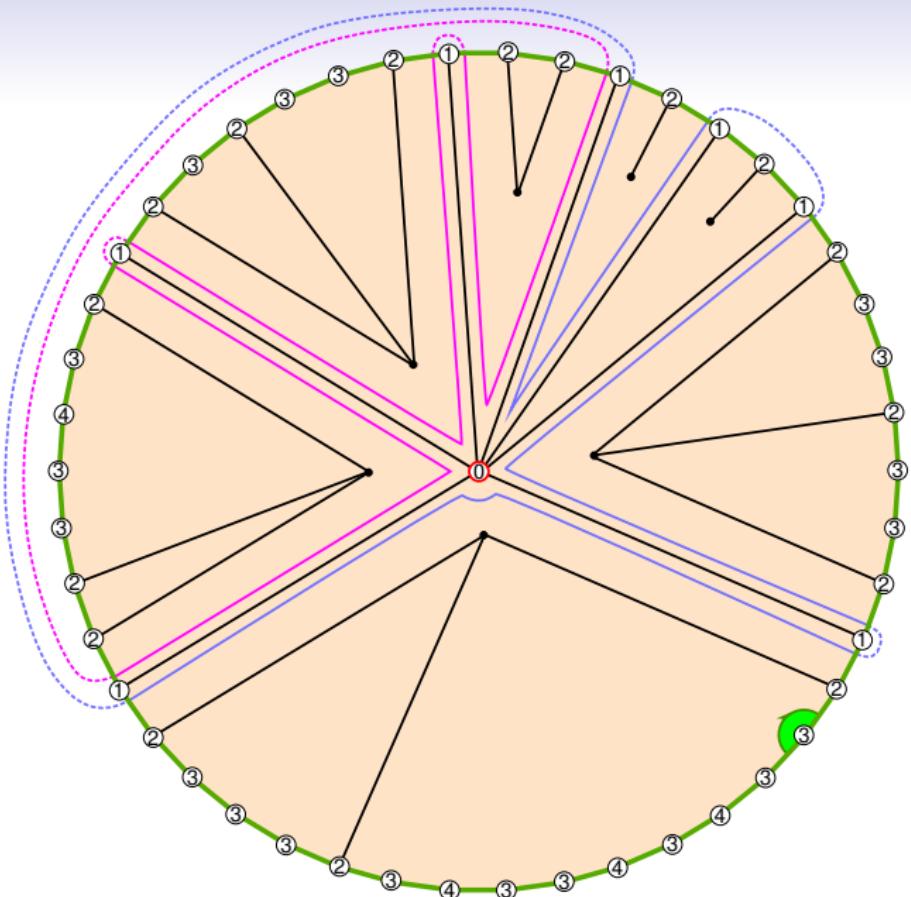
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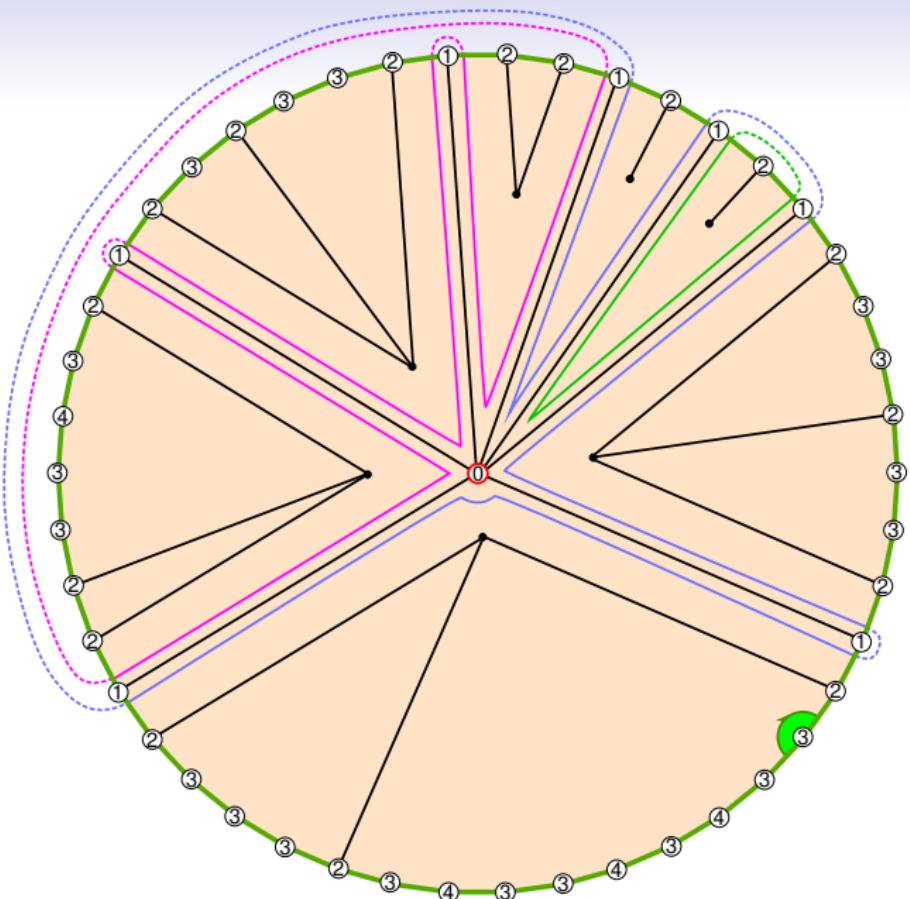
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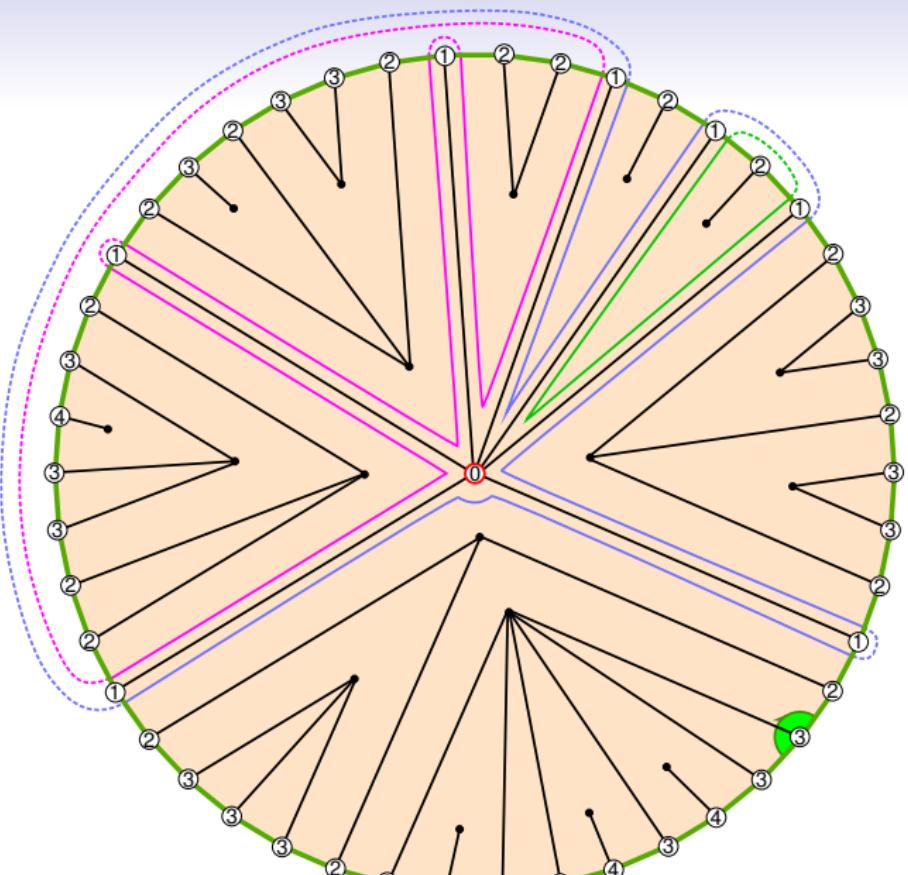
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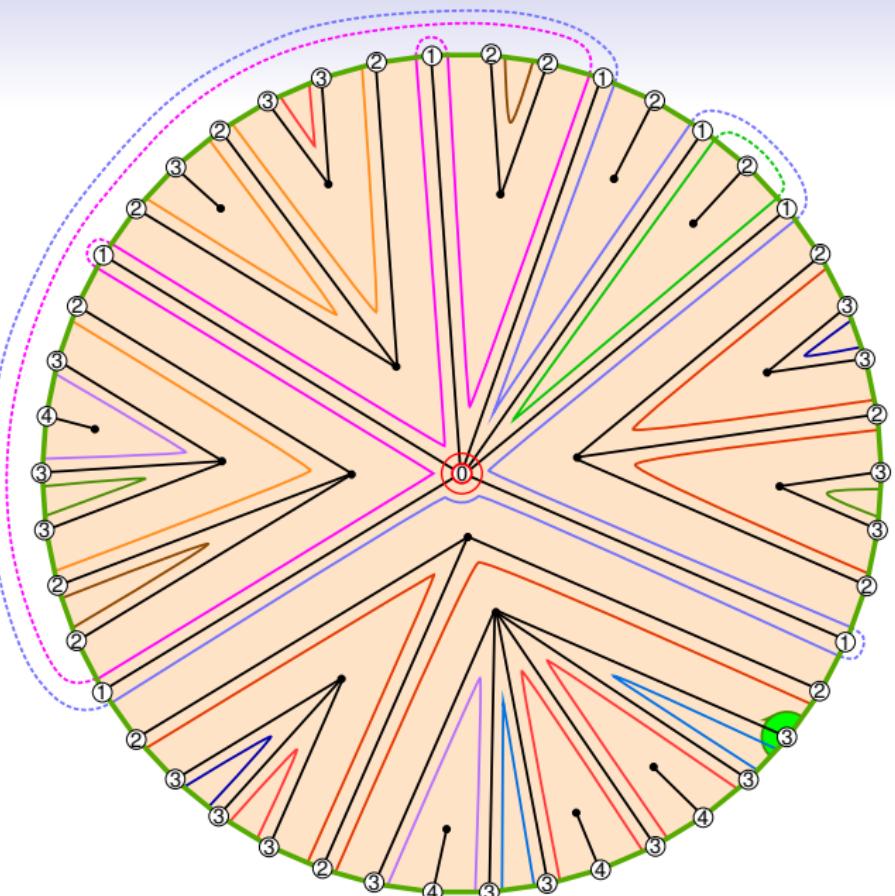
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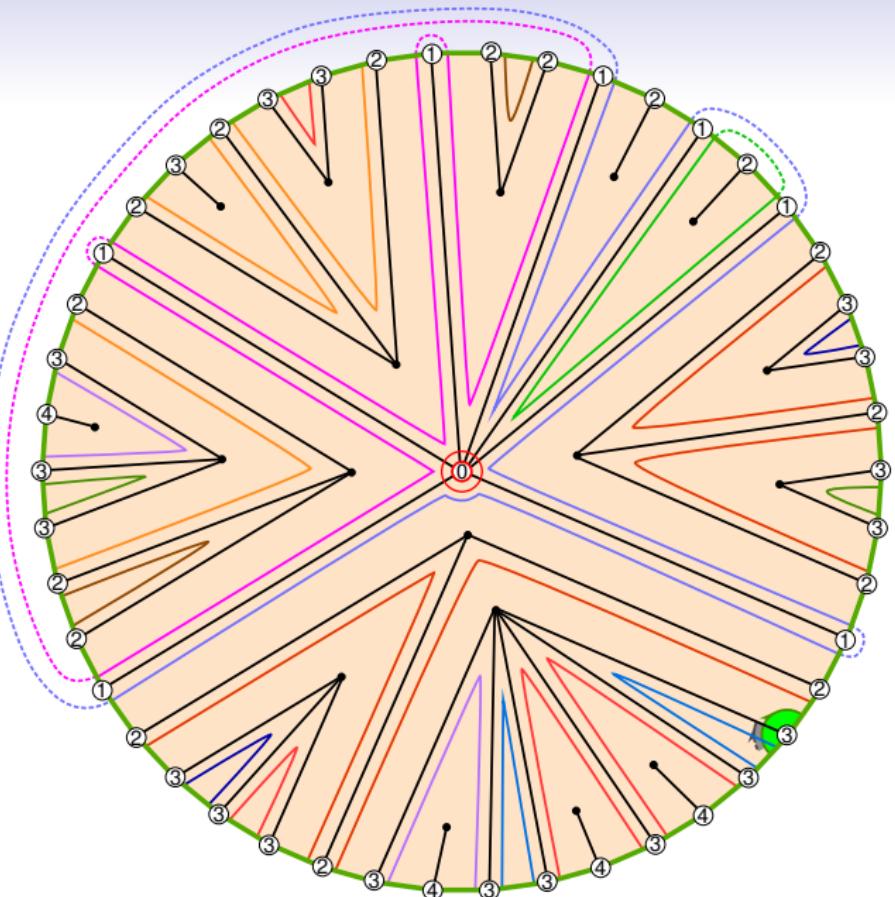
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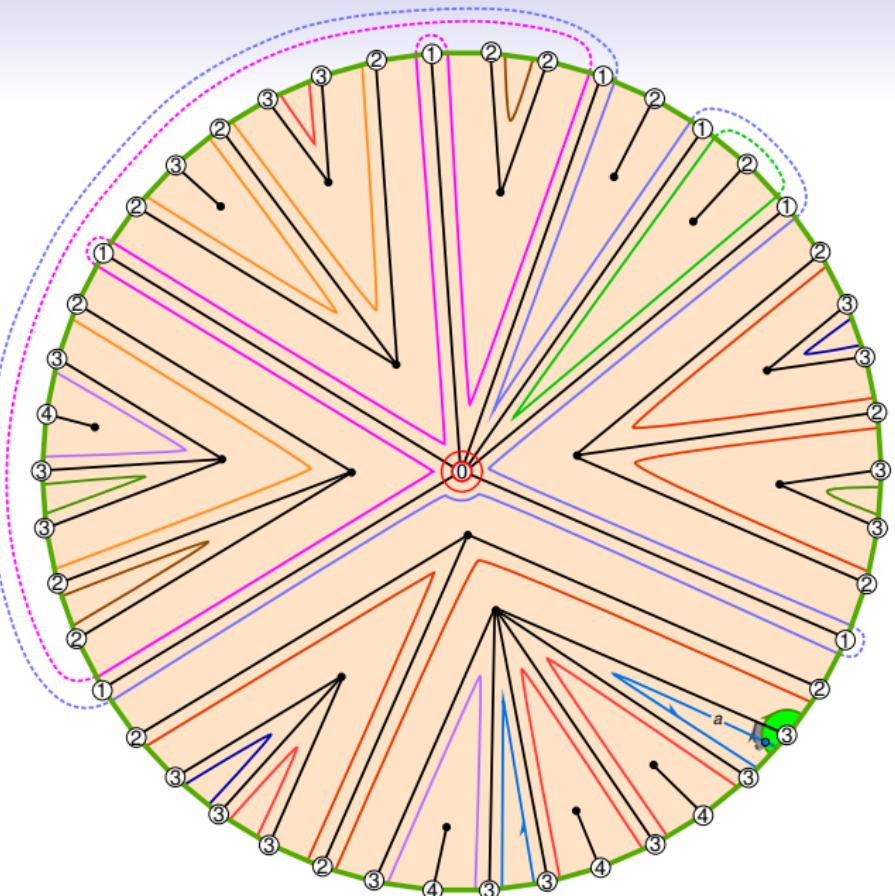
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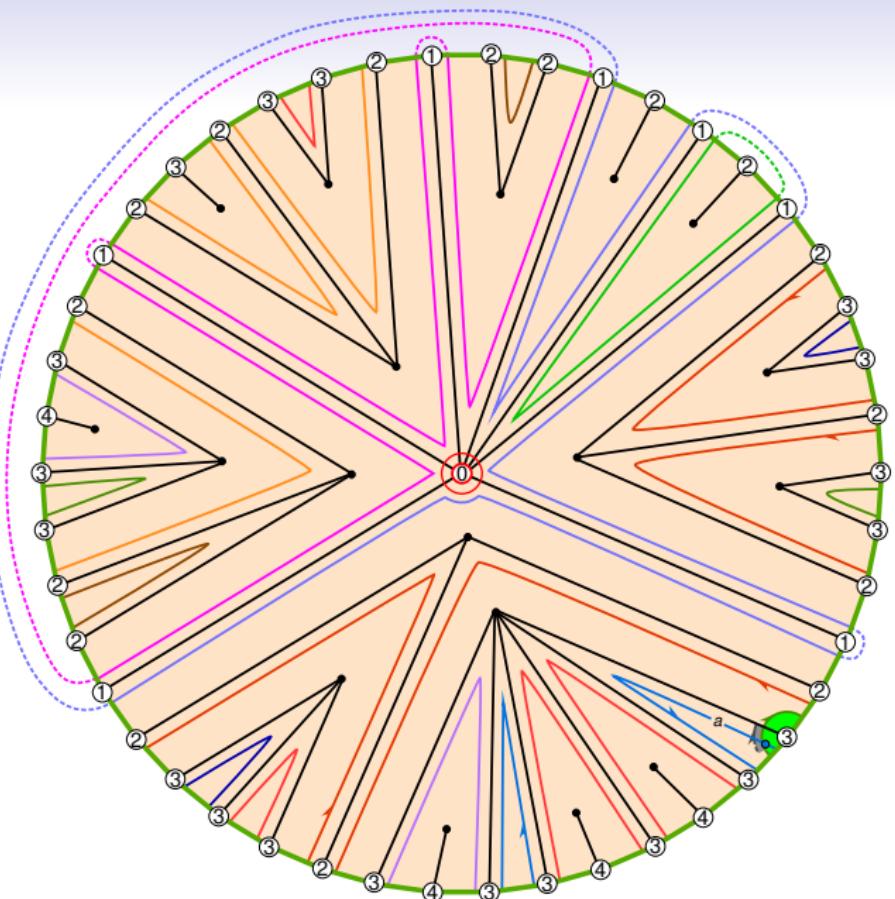
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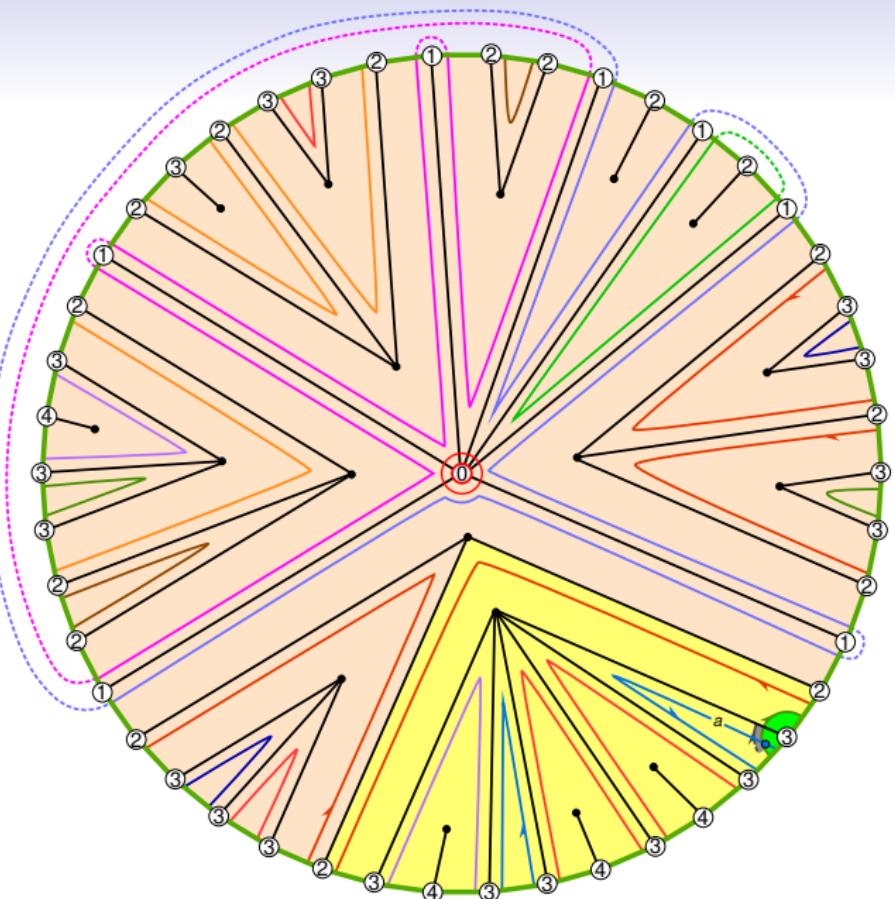
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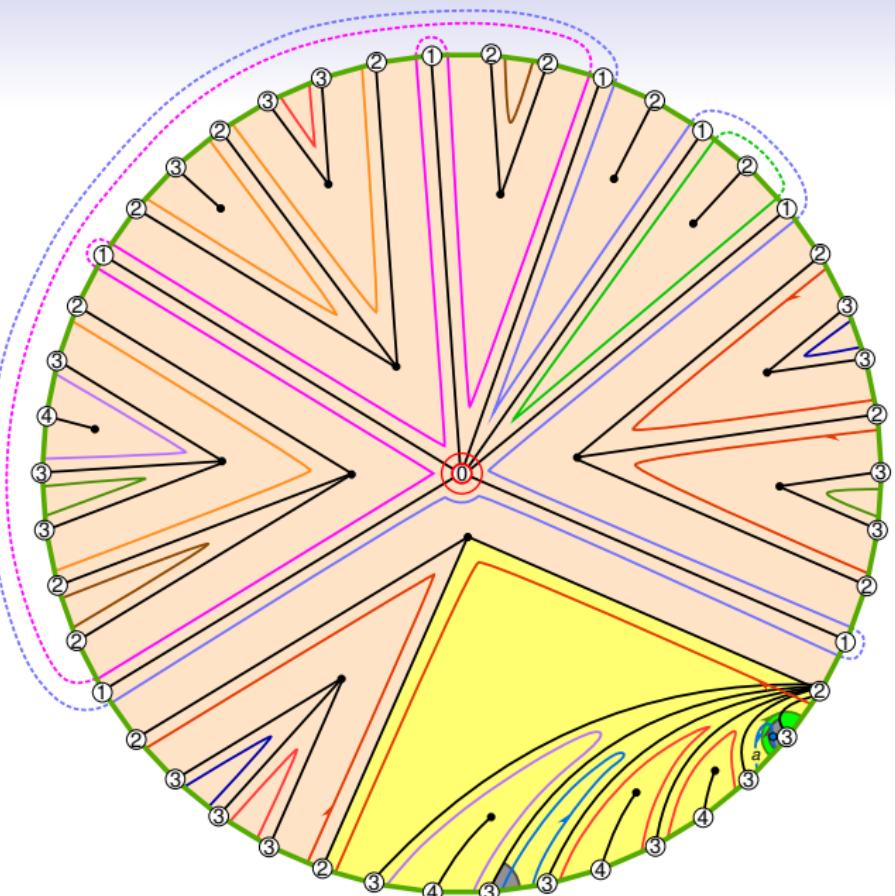
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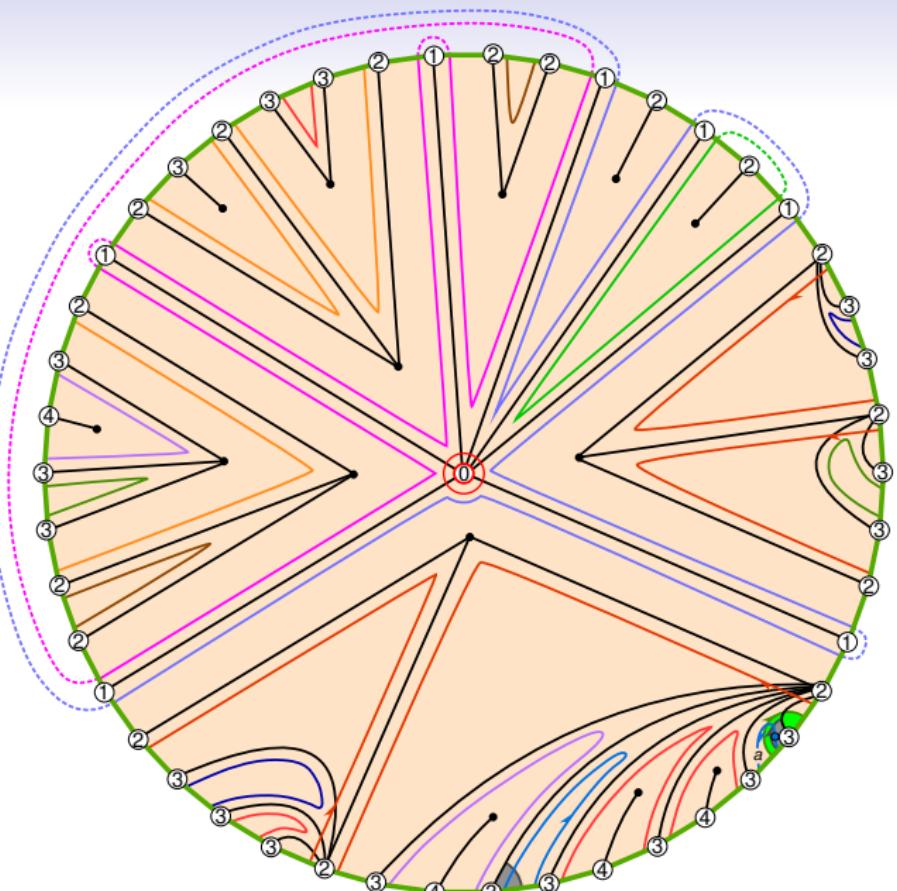
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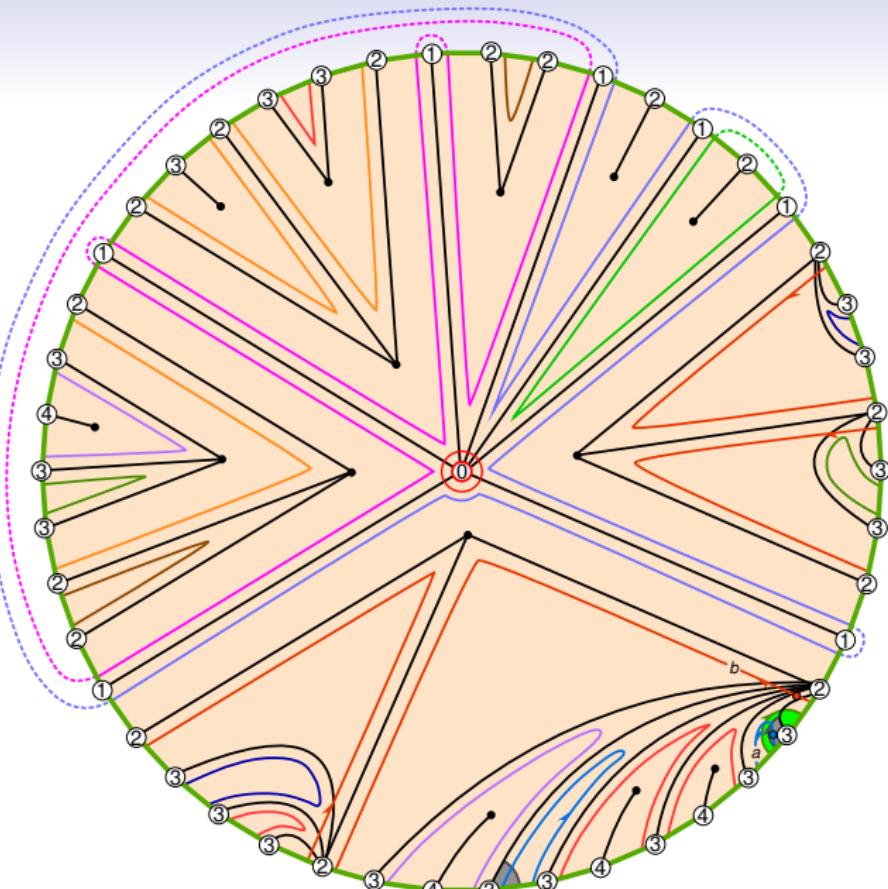
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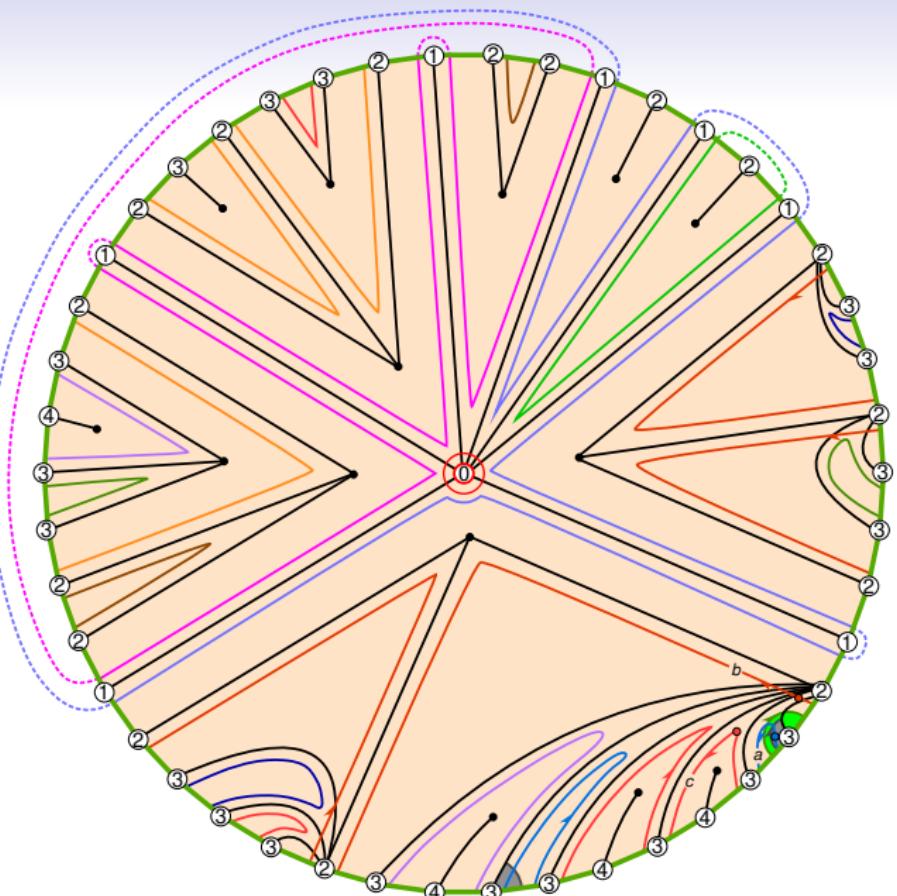
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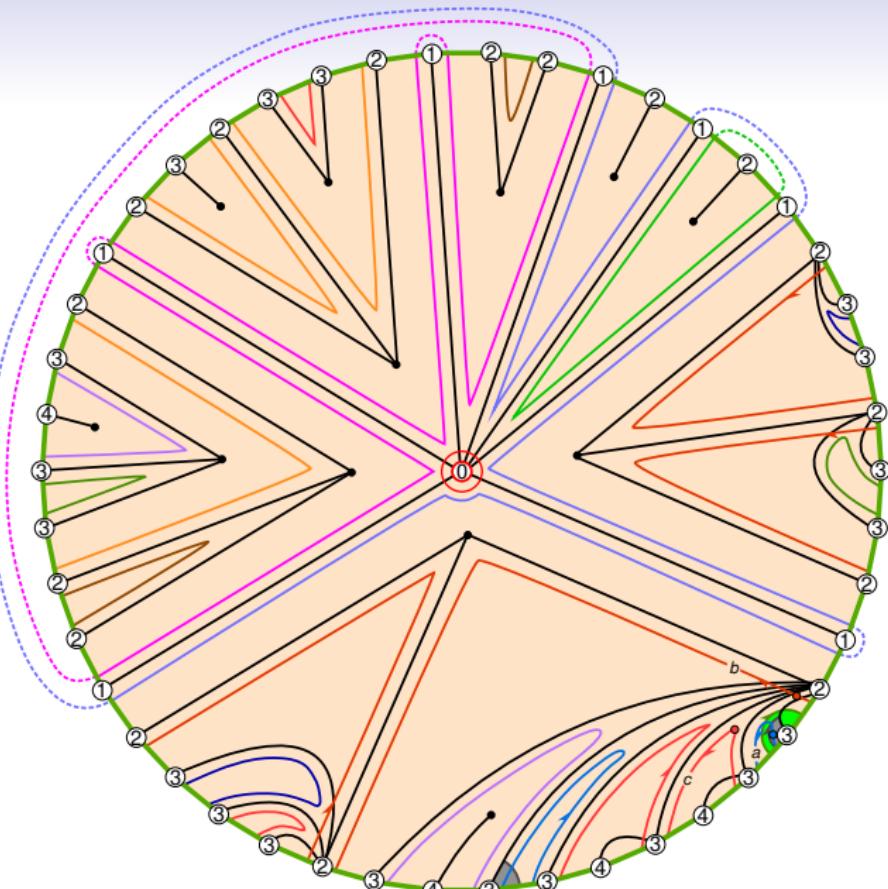
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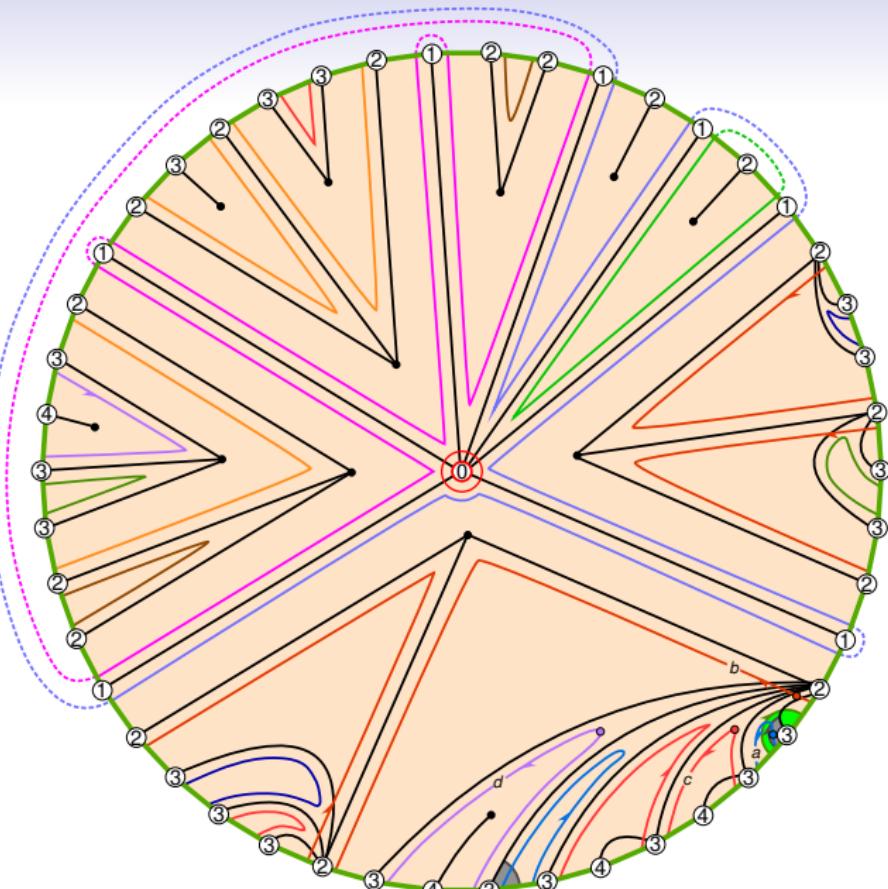
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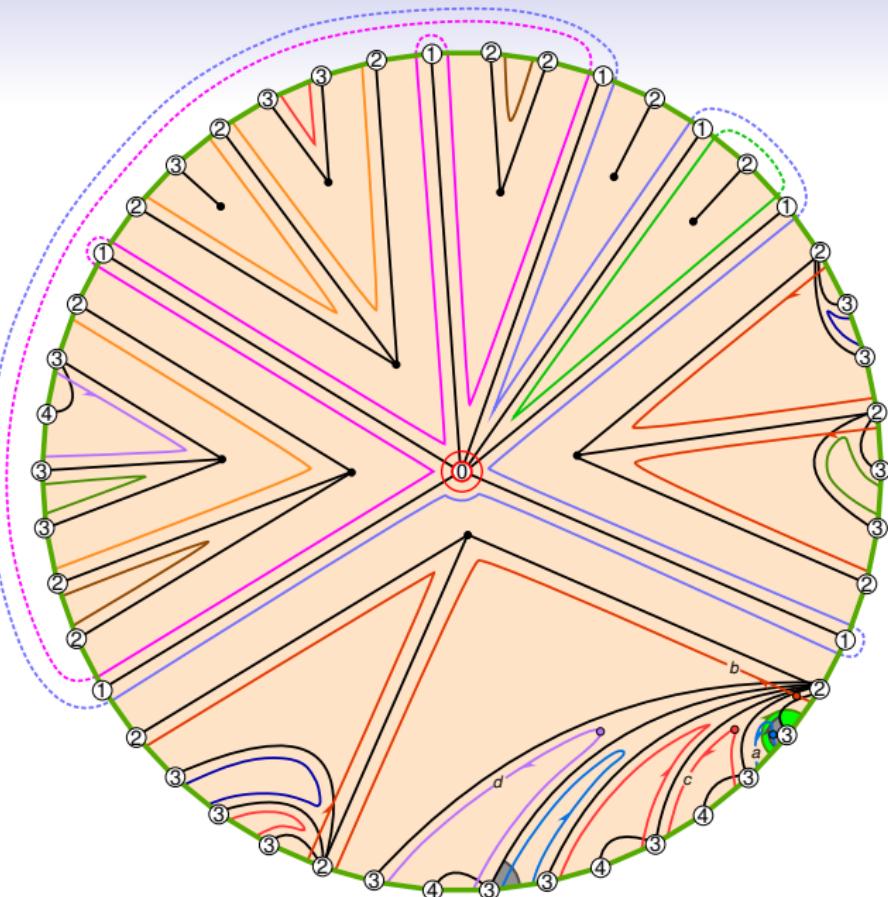
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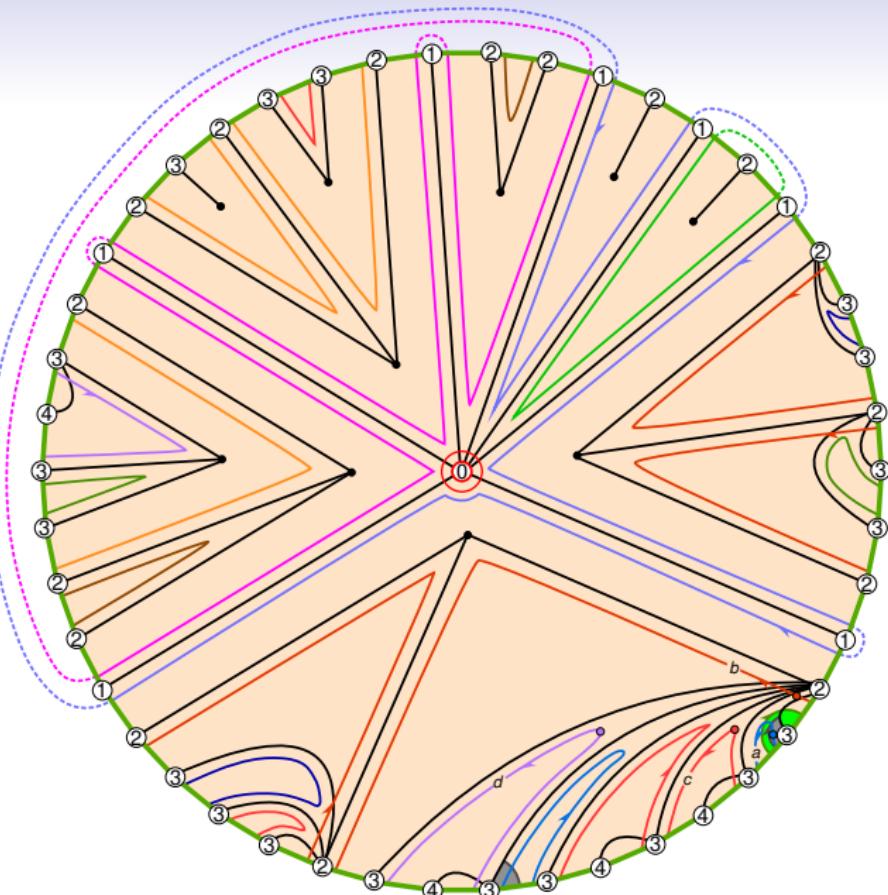
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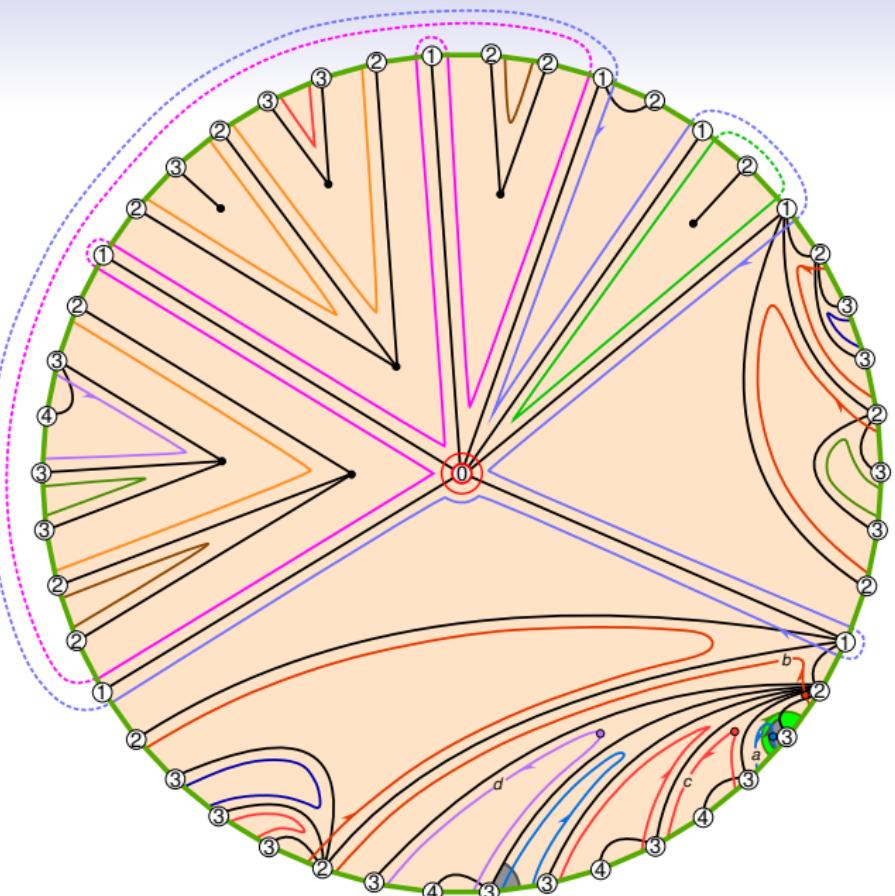
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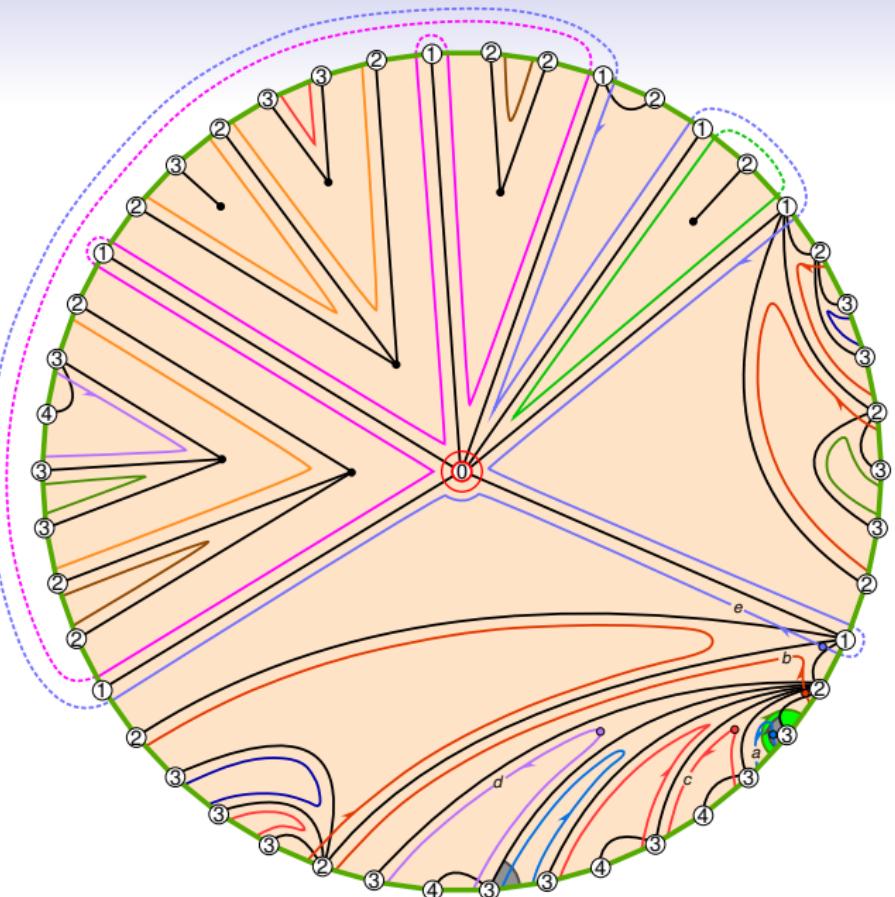
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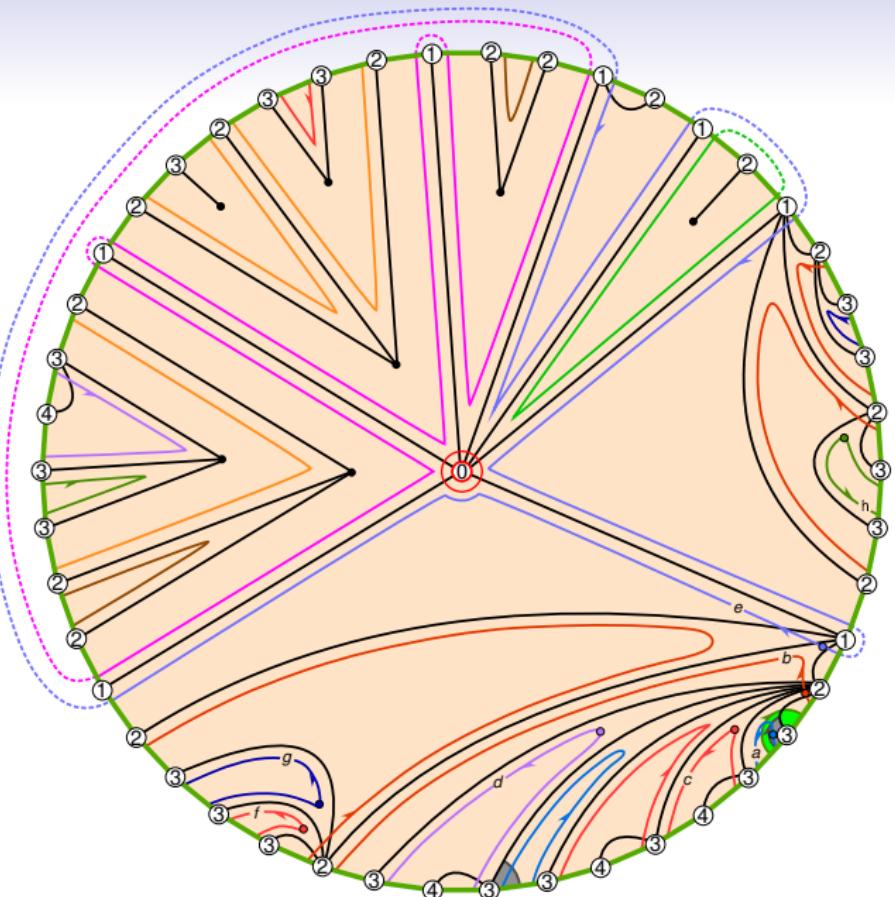
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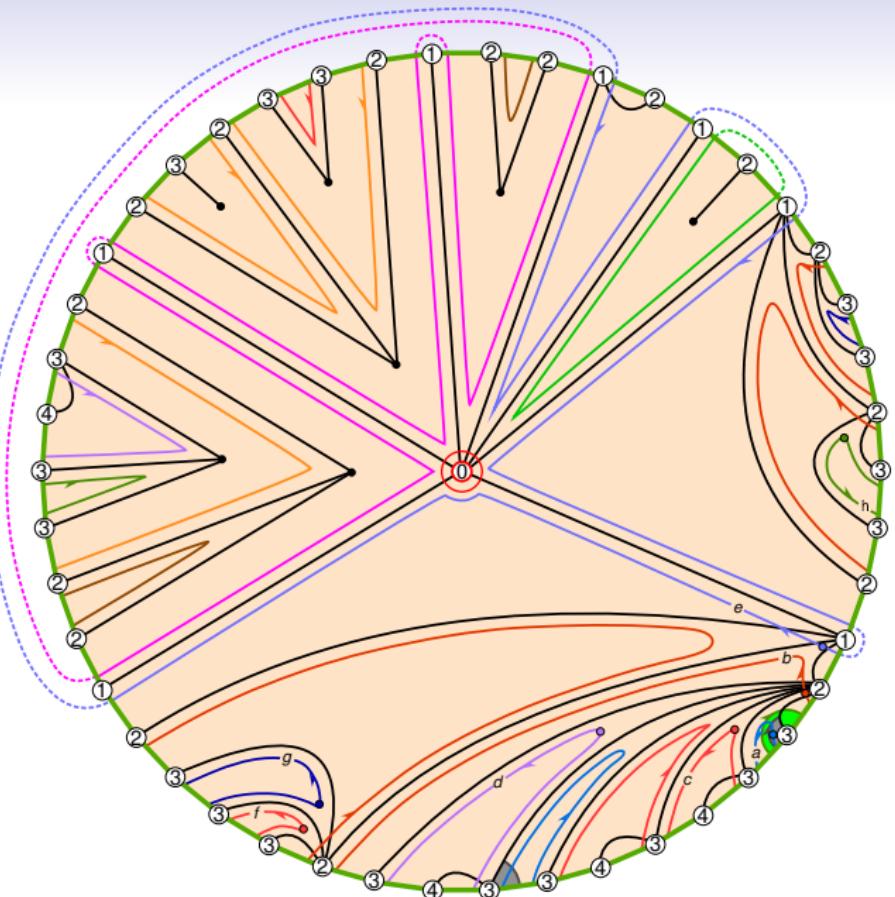
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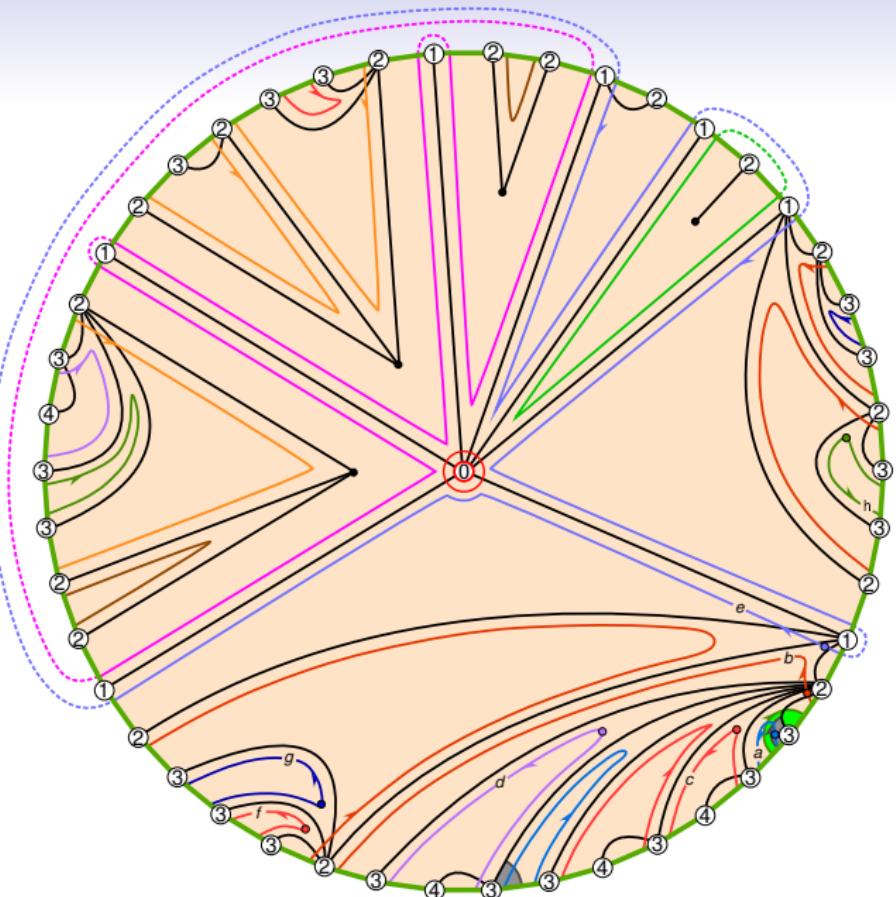
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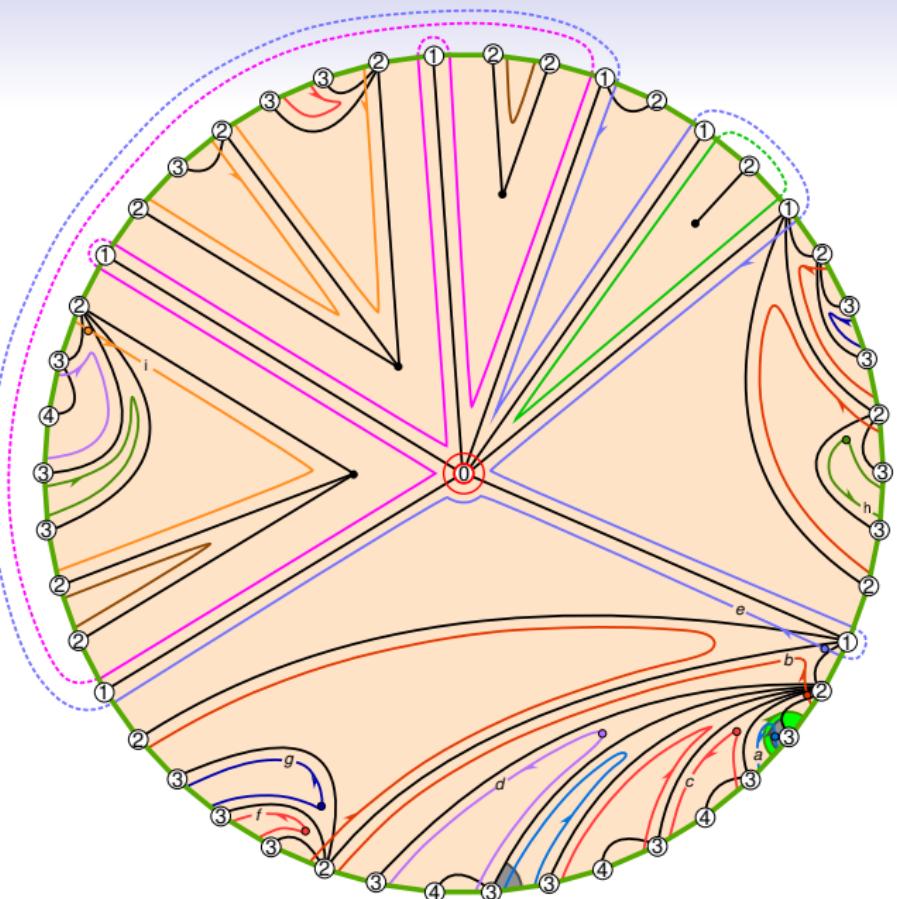
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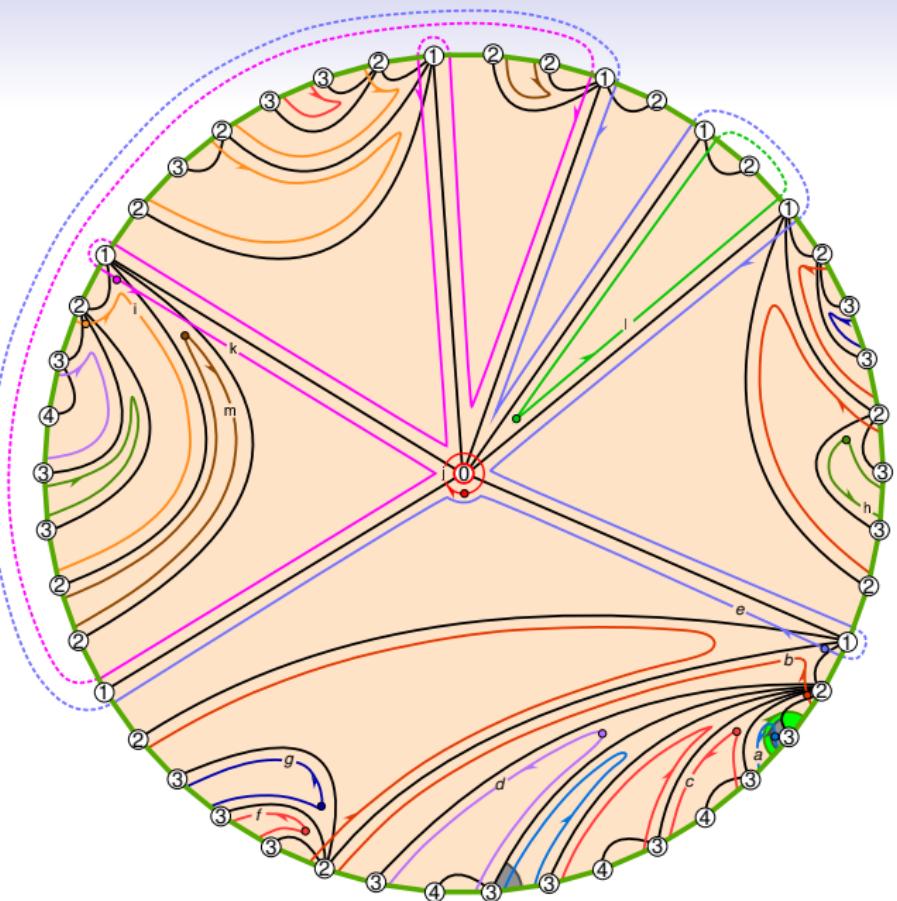
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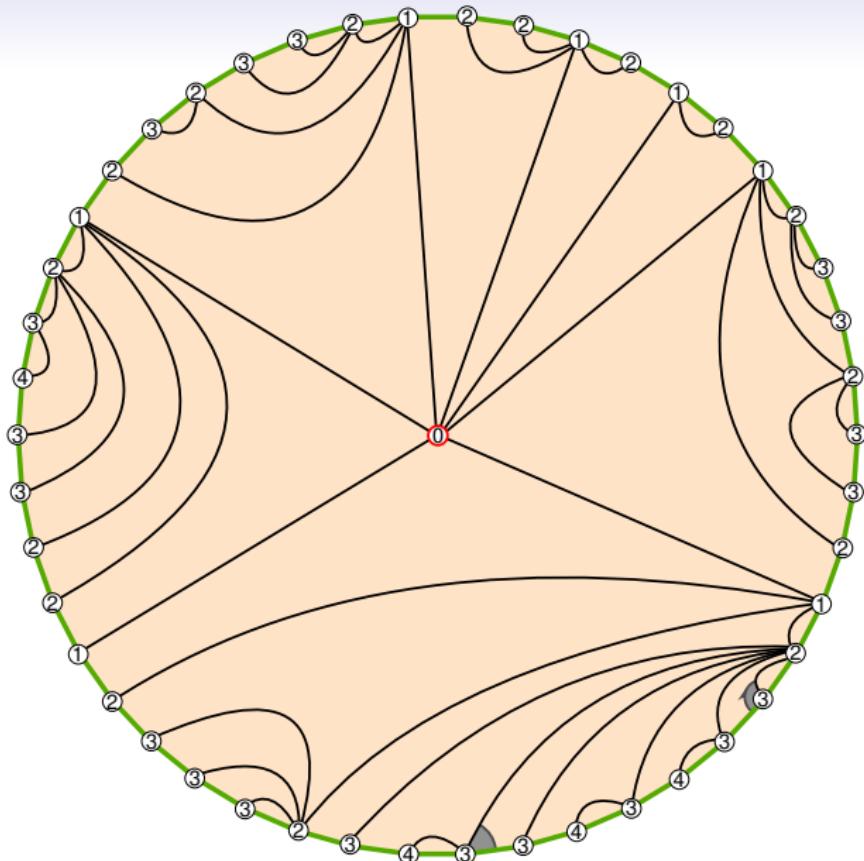
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